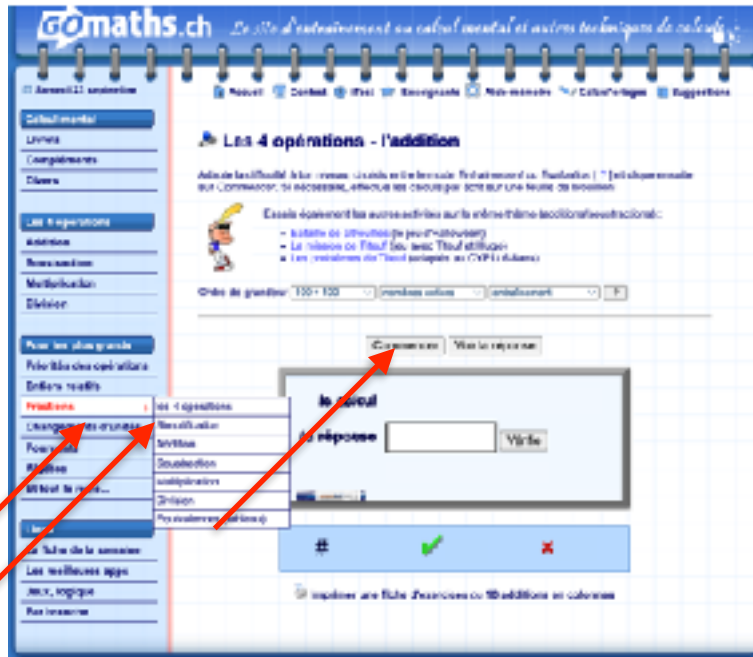


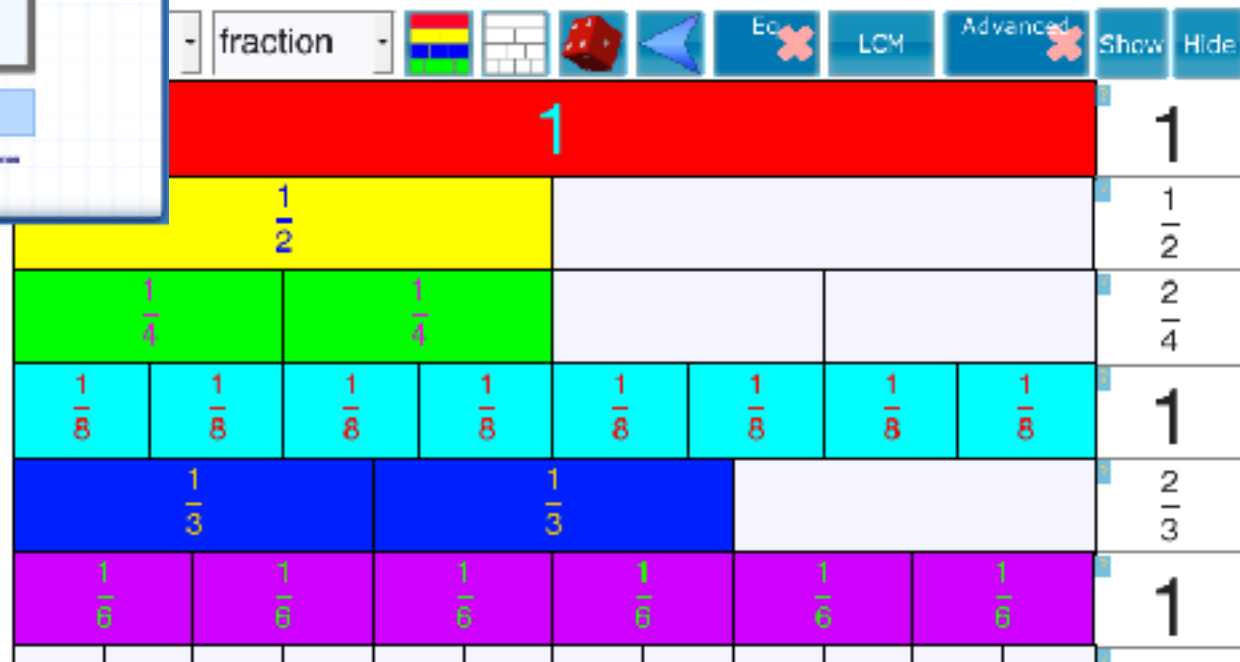
# CS-411 : Digital Education & Learning Analytics

## Chapter 3: Constructivism

# Learning Fractions: Comparing 2 methods



<https://gomaths.ch>



<https://www.visnos.com/demos/fraction-wall>

# How do people learn ?

**Chapter 3: Piaget**

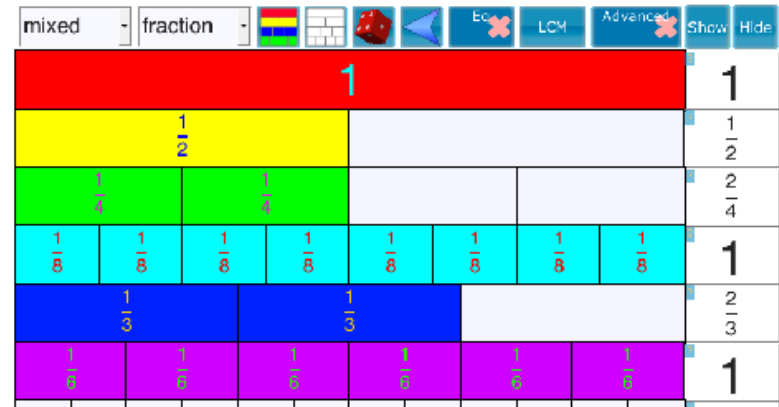
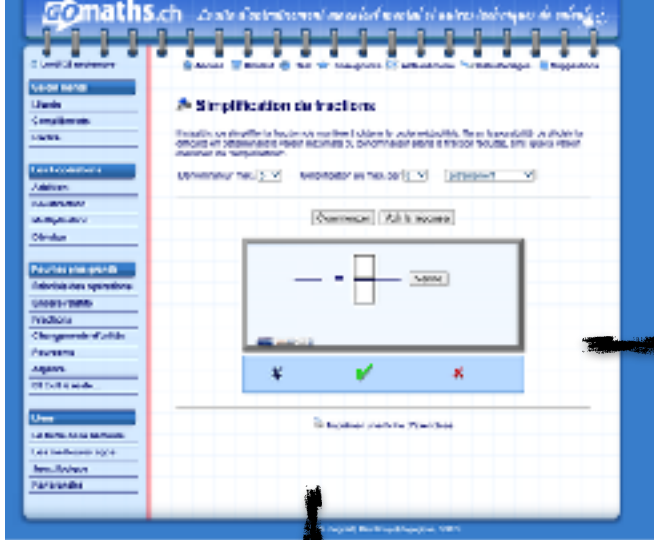
- by exploration, trial and error

**Chapter 4: Bloom**

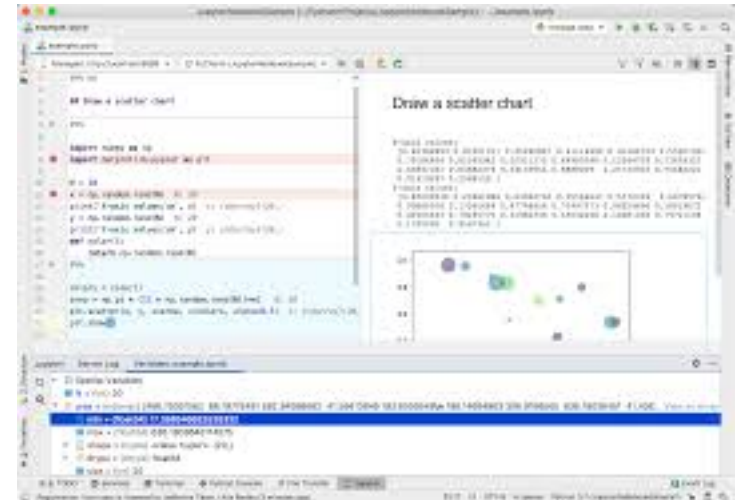
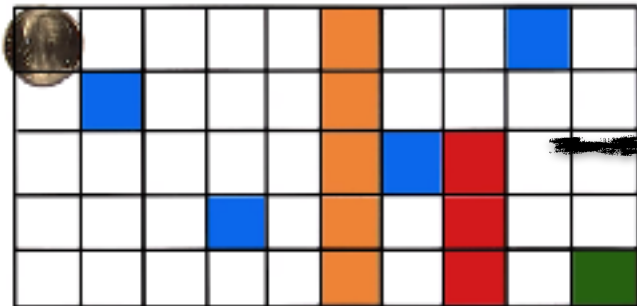
- by incremental mastery

**Chapter 5: Vygotsky**

- by verbal elaboration



Inverse Reinforcement Learning



<https://www.youtube.com/watch?v=h7uGyBcIeII>





# Curriculum ?

# Lesson A

A **splountz** is a triangle with 3 smaller shapes placed on different sides, one in the same color as the triangle and the two others in a different color.



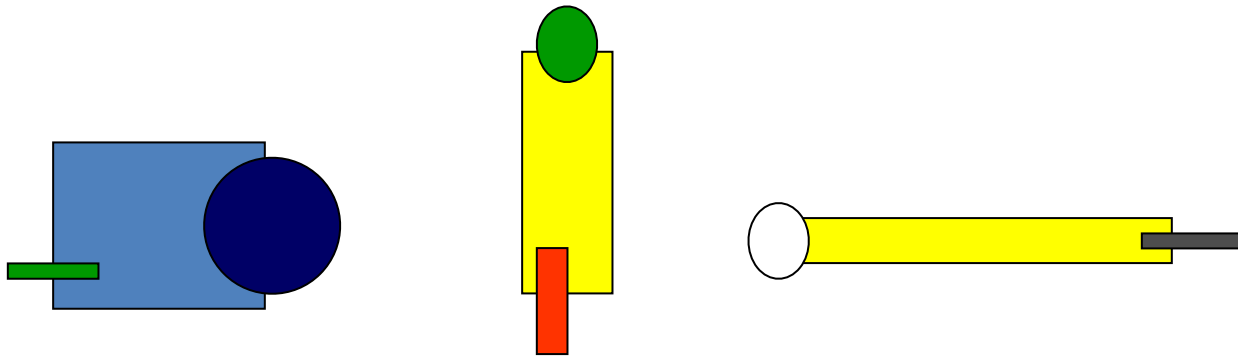
Is this a Splountz ?

☐ Yes

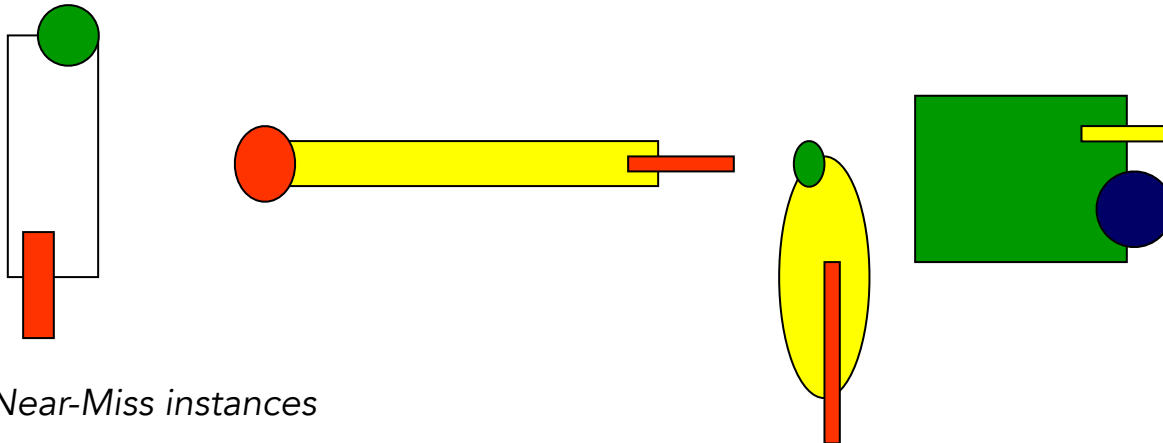
☒ No

# Lesson B

## WHAS IS A SPUC ?



Positive  
instances



*Near-Miss instances*

Negative  
instances

# Constructivism

How do people learn ?

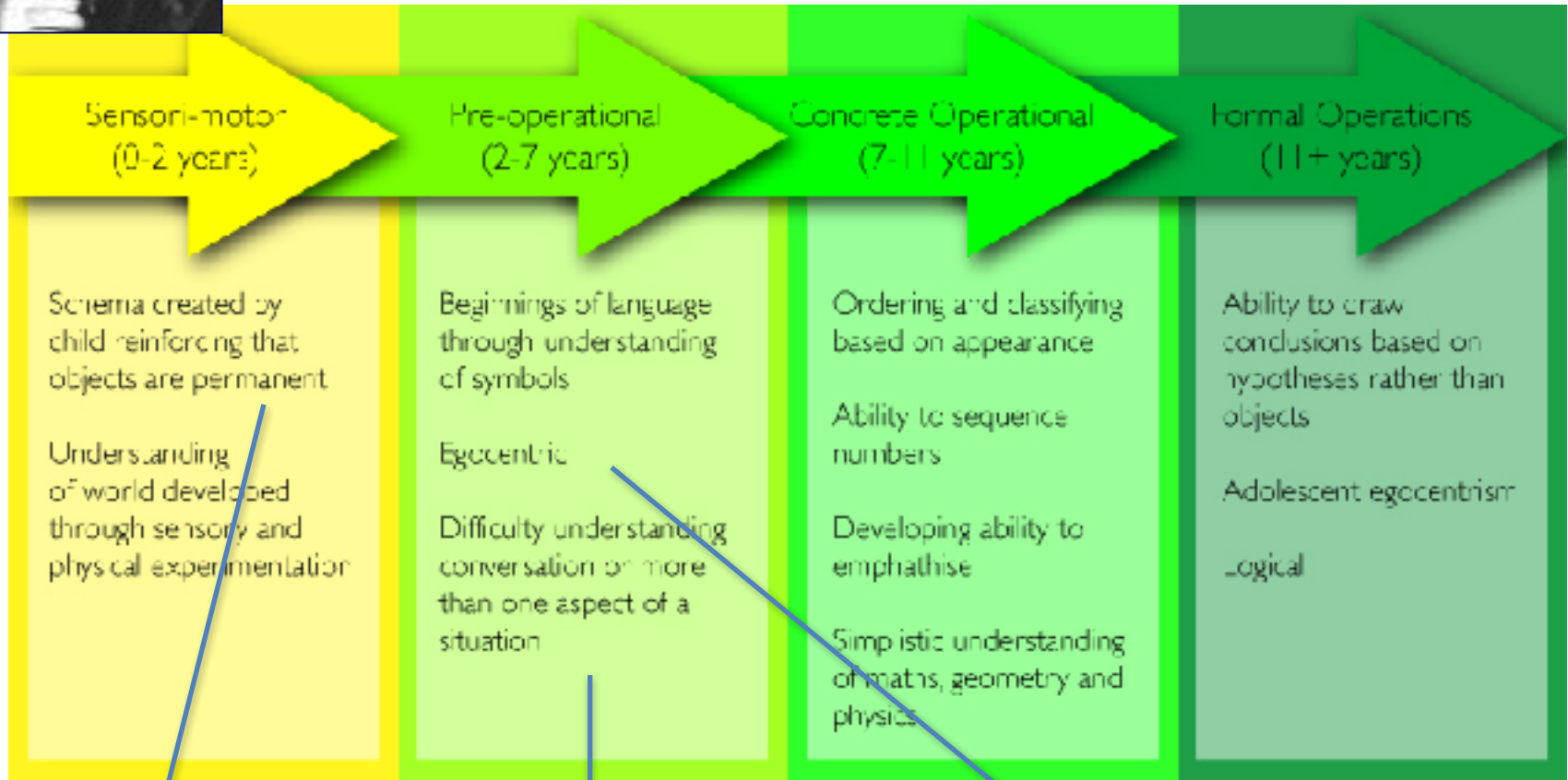
By constructing cognitive structures from experience  
(trial & error + reflection)



# Stages of cognitive development

## Constructivism

Jean Piaget



<https://www.papermasters.com/intellectual-growth.html>

Permanence of object

Conservation Task

Pyramid Task

## Assimilation and Accommodation

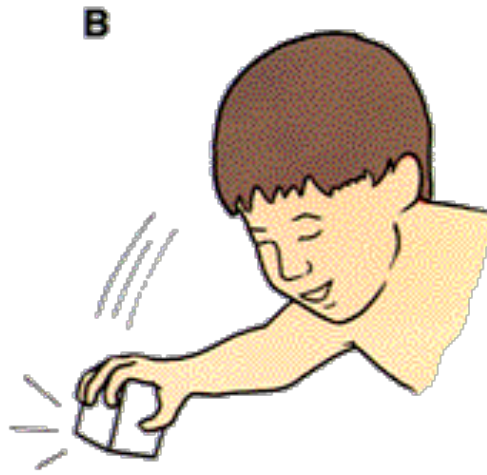
How can this girl use her “dog” schema when encountering a cat?



- She can **assimilate** the experience into her schema by referring to the cat as a “dog”  
or
- she can **accommodate** her animal schema by separating the cat, and even different types of dogs, into separate schemas.



Banging is a favorite **scheme** used by babies to explore their world . . .



. . . And **assimilation** occurs when they incorporate new objects into the scheme.

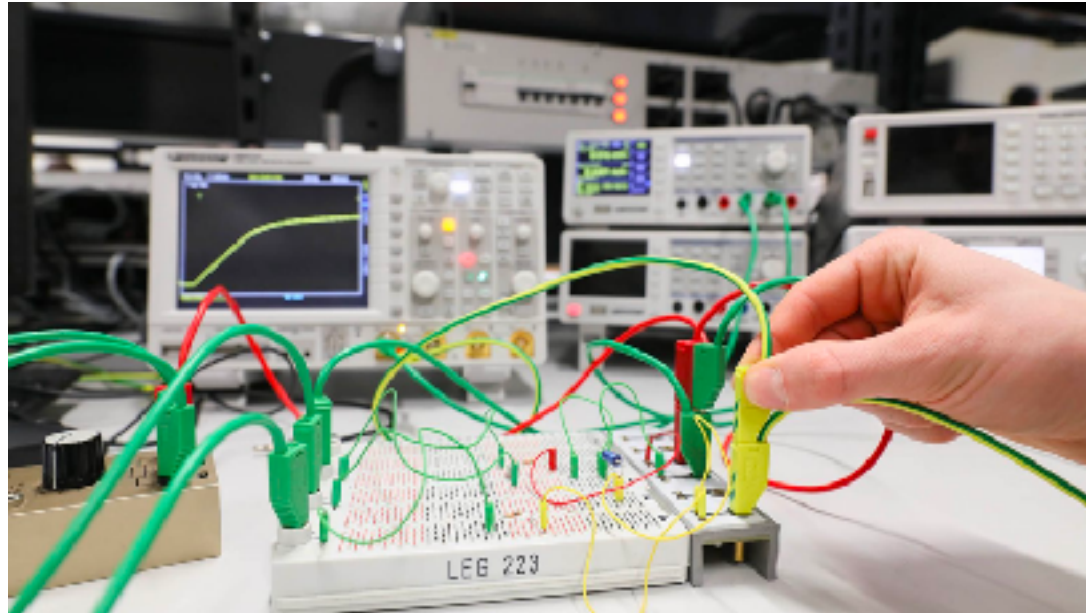


**Accomodation** occurs when the new object doesn't fit the existing scheme.

Piaget (1952) defined a schema as 'a cohesive, repeatable action sequence possessing component actions that are tightly interconnected and governed by a core meaning'. Basically, a schema is the building block of intelligent behavior

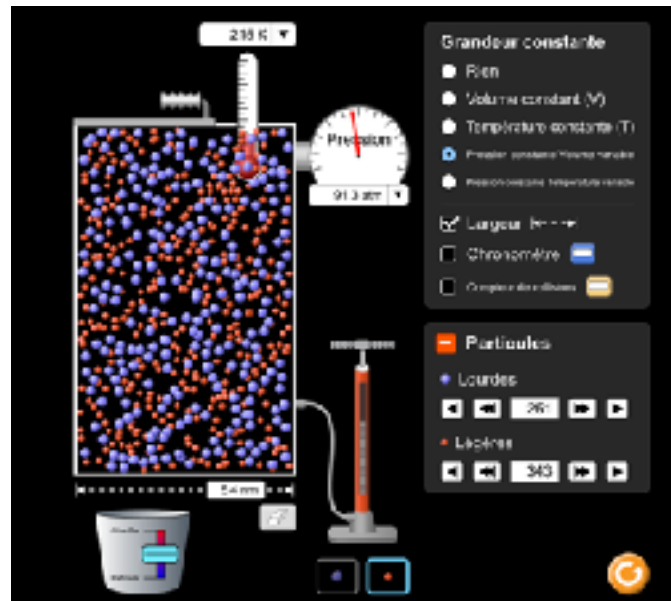
# Cognitive Conflict as key learning mechanism

- Learning from experience
- Learning by doing
- Discovery learning



## Learning by Discovery

Discovery learning lab (The SPOT)



[https://phet.colorado.edu/sims/html/gases-intro/latest/gases-intro\\_all.html?locale=fr](https://phet.colorado.edu/sims/html/gases-intro/latest/gases-intro_all.html?locale=fr)

Learning by Discovery in Berufsbildung ?



Discovery intuitive static principles (for carpenters) ?



exploration

Learning by Discovery



## Semi-Constructivism

*There is a time for telling*

No Over-expectation !

## “Productive Failure”

Who's the most consistent striker?

| Year | Mike Arwen | Dave Backhand | Ivan Right |
|------|------------|---------------|------------|
| 1988 | 14         | 13            | 13         |
| 1989 | 9          | 9             | 18         |
| 1990 | 14         | 16            | 15         |
| 1991 | 10         | 14            | 10         |
| 1992 | 15         | 10            | 16         |
| 1993 | 11         | 11            | 10         |
| 1994 | 15         | 13            | 17         |
| 1995 | 11         | 14            | 10         |
| 1996 | 16         | 15            | 12         |
| 1997 | 12         | 19            | 14         |
| 1998 | 16         | 14            | 19         |
| 1999 | 12         | 12            | 14         |
| 2000 | 17         | 15            | 18         |
| 2001 | 13         | 14            | 9          |
| 2002 | 17         | 17            | 10         |

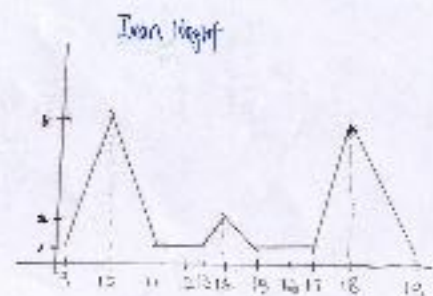
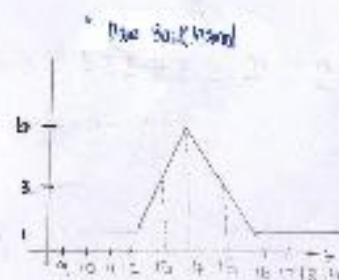
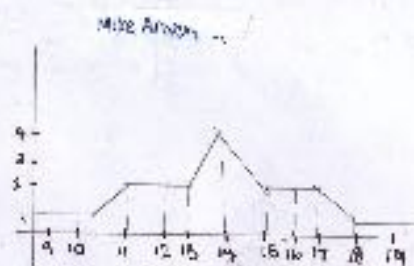
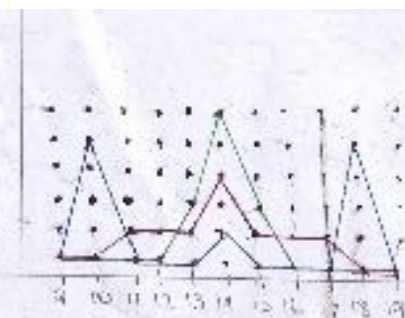
Mike Arwen : Mean =  $\frac{280}{20}$   
 = 14 goals / year  
 Mode = 14

Dave Backhand : Mean =  $\frac{280}{20}$   
 = 14 goals / year  
 Mode = 14

Ivan Right : Mean =  $\frac{280}{20}$   
 = 14 goals / year  
 Mode = 18 and 10

Comparing regularity

| 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 |
|---|----|----|----|----|----|----|----|----|----|----|
| 1 | 1  | 2  | 2  | 2  | 4  | 2  | 2  | 2  | 1  | 1  |
| 1 | 1  | 1  | 1  | 3  | 6  | 3  | 1  | 1  | 1  | 1  |
| 1 | 5  | 1  | 1  | 1  | 2  | 1  | 1  | 1  | 5  | 1  |



9 10 11 11 12 12 13 13 14 14 14 14 15 15 16 16 17 17 18 19

From Question paper: Average =  $\frac{280}{20}$

Mike has 8 years < average

4 years = average

8 years > average

Dave has 7 years < average

6 years = average

7 years > average

Ivan has 9 years < average

2 years = average

9 years > average

**Frequency of years  
above, below, and at  
average**

**Consistency = years at the  
mean / years away from the  
mean**

## Sum of year-on-year deviation

|                 |             |             |
|-----------------|-------------|-------------|
| <b>Mike</b>     | <b>Dave</b> | <b>Ivan</b> |
| 4-14 = -10      | -4          | 5           |
| 14-9 = 5        | 1           | -3          |
| 10-14 = -4      | -2          | -5          |
| 15-10 = 5       | -2          | 1           |
| -4              | 1           | -6          |
| 4               | 2           | -7          |
| -4              | 1           | -7          |
| 5               | 1           | 2           |
| -4              | 4           | 2           |
| 4               | -5          | 5           |
| -4              | -2          | -5          |
| 4               | 3           | 4           |
| -4              | -1          | -9          |
| 5               | 3           | 1           |
| -4              | -4          | 8           |
| 4               | 1           | -7          |
| -4              | 4           | -1          |
| 5               | -4          | 8           |
| -4              | 1           | 0           |
| 5               |             | -5          |
| -4              |             |             |
| 0 ✓ <u>Mike</u> | <u>2</u>    |             |

Range  
Absolute amount for:

|                      |      |   |   |
|----------------------|------|---|---|
| Mike Armen: 9 - 19   | = 10 | } | x |
| Dave England: 9 - 19 | = 10 |   |   |
| Ivan Egypt: 9 - 19   | = 10 |   |   |

## Sum of deviations about the mean

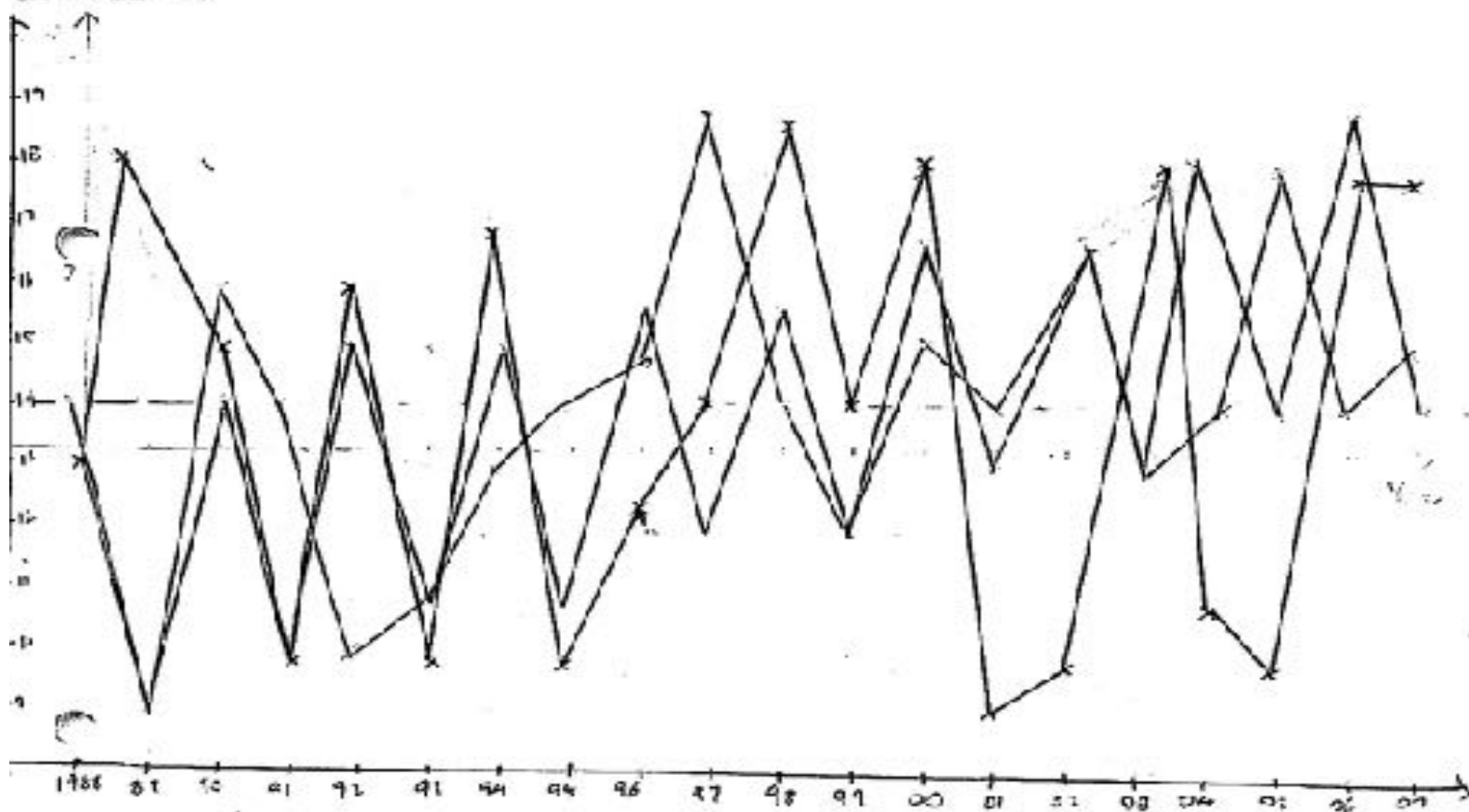
| Year   | Avg | Mike | Dave | Ivan | x  |    |
|--------|-----|------|------|------|----|----|
| 1988   | 14  | 14   | 13   | 13   | 0  | -1 |
| 1989   | 14  | 14   | 14   | 18   | 0  | 4  |
| 1990   | 14  | 14   | 16   | 15   | 0  | 1  |
| 1991   | 14  | 10   | 14   | 10   | -4 | 0  |
| 1992   | 14  | 15   | 10   | 16   | +1 | +2 |
| 1993   | 14  | 11   | 11   | 10   | -3 | -4 |
| 1994   | 14  | 15   | 13   | 17   | +1 | +3 |
| 1995   | 14  | 11   | 14   | 16   | -3 | 0  |
| 1996   | 14  | 16   | 15   | 12   | +2 | -2 |
| 1997   | 14  | 12   | 14   | 14   | -2 | 0  |
| 1998   | 14  | 16   | 16   | 16   | +2 | +5 |
| 1999   | 14  | 12   | 12   | 14   | -2 | 0  |
| 2000   | 14  | 17   | 15   | 18   | +3 | +4 |
| 2001   | 14  | 13   | 14   | 9    | -1 | -5 |
| 2002   | 14  | 12   | 17   | 16   | -2 | +3 |
| 2003   | 14  | 13   | 13   | 18   | -1 | +4 |
| 2004   | 14  | 13   | 14   | 11   | -1 | -3 |
| 2005   | 14  | 16   | 18   | 10   | 0  | +4 |
| 2006   | 14  | 19   | 14   | 18   | +5 | +4 |
| 2007   | 14  | 14   | 15   | 12   | 0  | -1 |
| Total: |     |      |      |      | 0  | 0  |

## Average of year-on-year absolute deviation

MIKE =  $\frac{5+5+4+5+4+4+4+5+1+4+4+5+4+4+1+5+4+5+4}{19}$   
 $= 84/19 = 4.26$

DAVE =  $\frac{4+7+2+4+1+2+1+1+4+5+2+3+1+3+4+1+4+4+1}{19}$   
 $= 54/19 = 2.84$  DAVE is most consistent

IVAN =  $\frac{5+3+5+1+6+7+7+2+2+5+5+4+9+1+8+4+1+8+0}{19}$   
 $= 4.29$



- Mike Arnesen
- - - Dave Backlund
- ... Ivan, Right

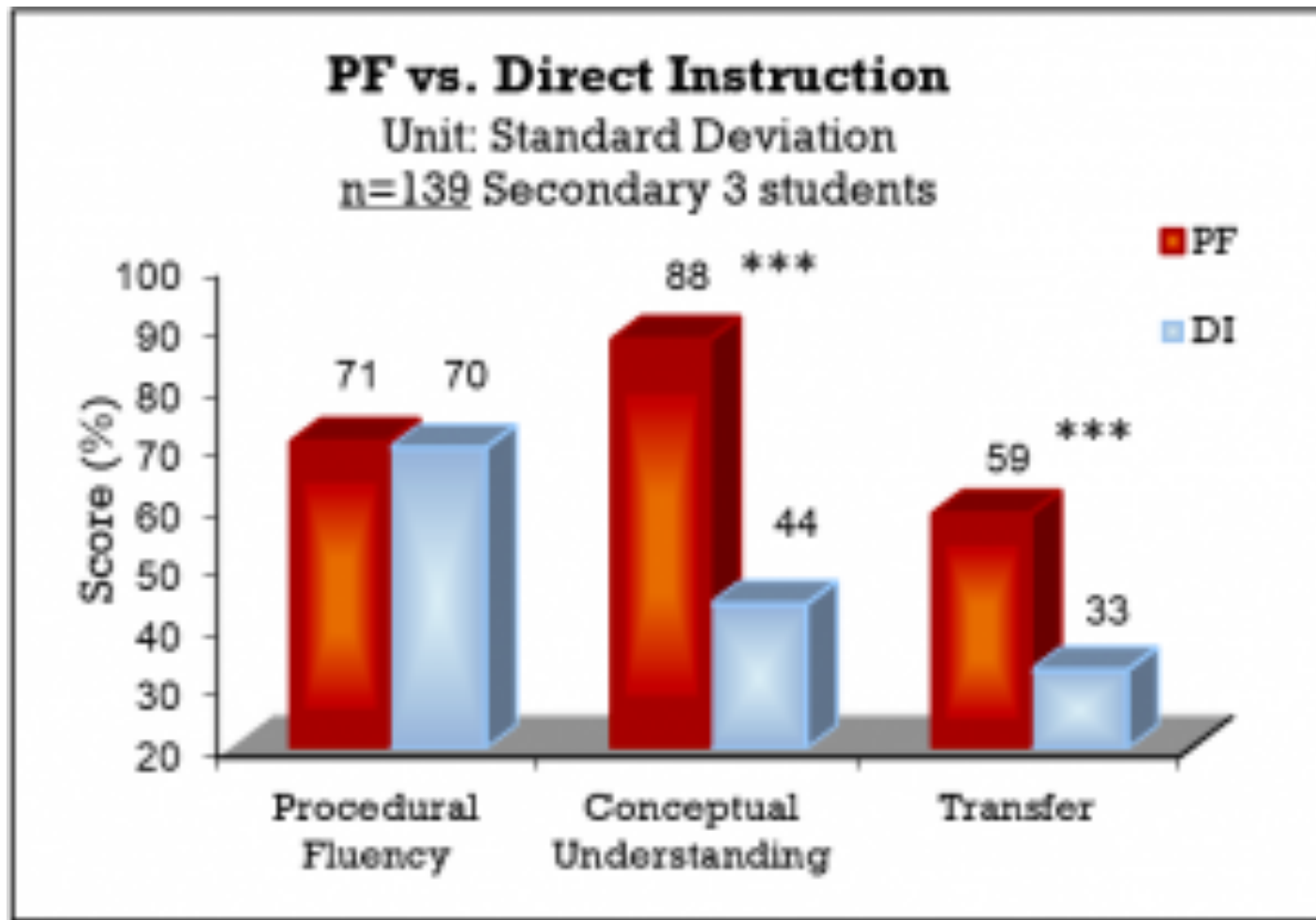
### Idea 3: Measure Graph Length

$$\begin{aligned}
 \text{MA} & \sqrt{26} + \sqrt{66} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{26} + \sqrt{26} = 83.26 \\
 \text{DB} & \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} = 56.54 \\
 \text{IR} & \sqrt{26} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{26} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} + \sqrt{17} = 94.54
 \end{aligned}$$

∴ Dave Backlund is the most consistent player as he has the shortest "stretch-and-shrink" graph, showing consistency over time.

Azad  
Arnesen

3



# Constructivism $\neq$ Teacherless

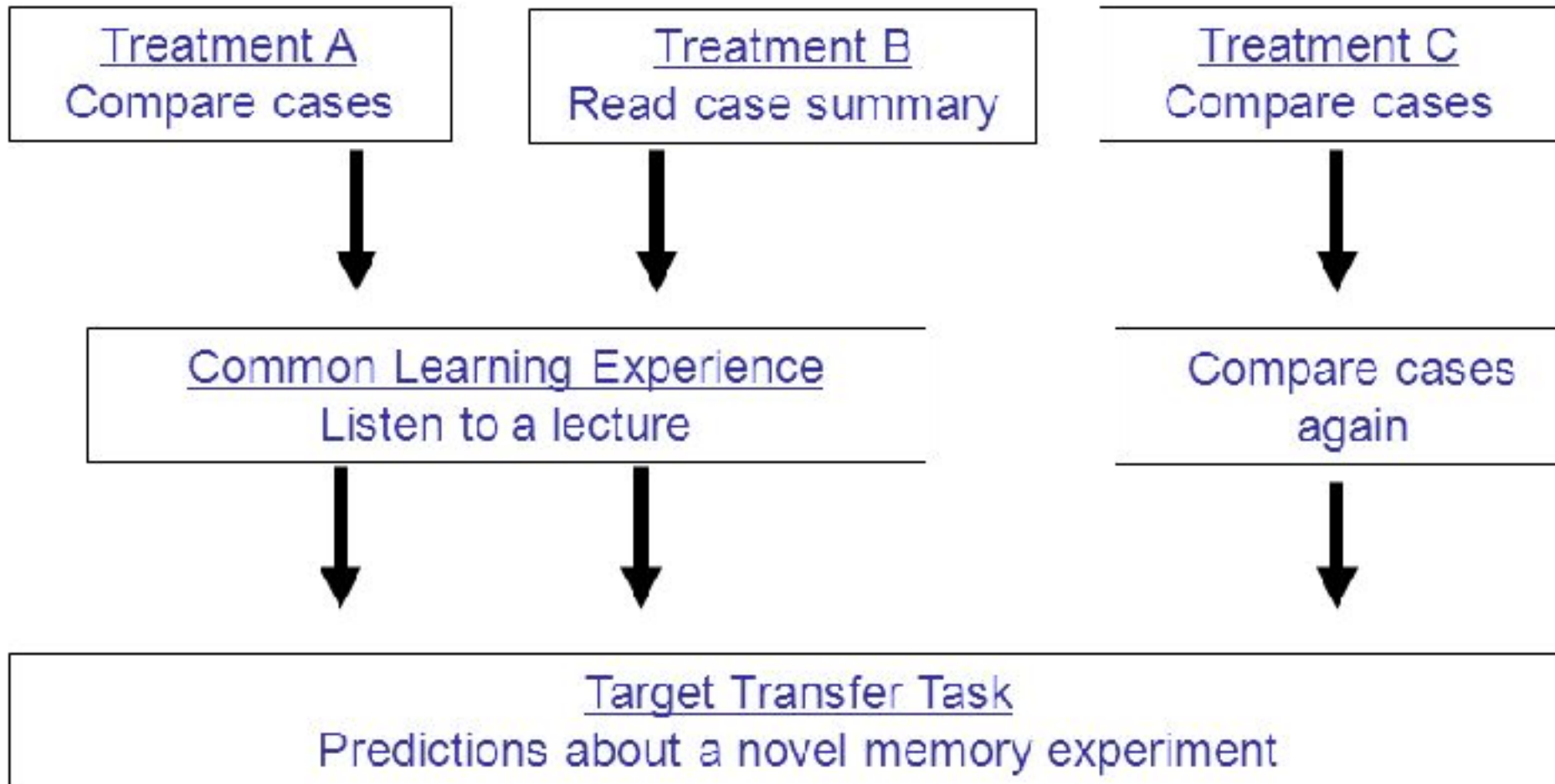
There is a time for telling



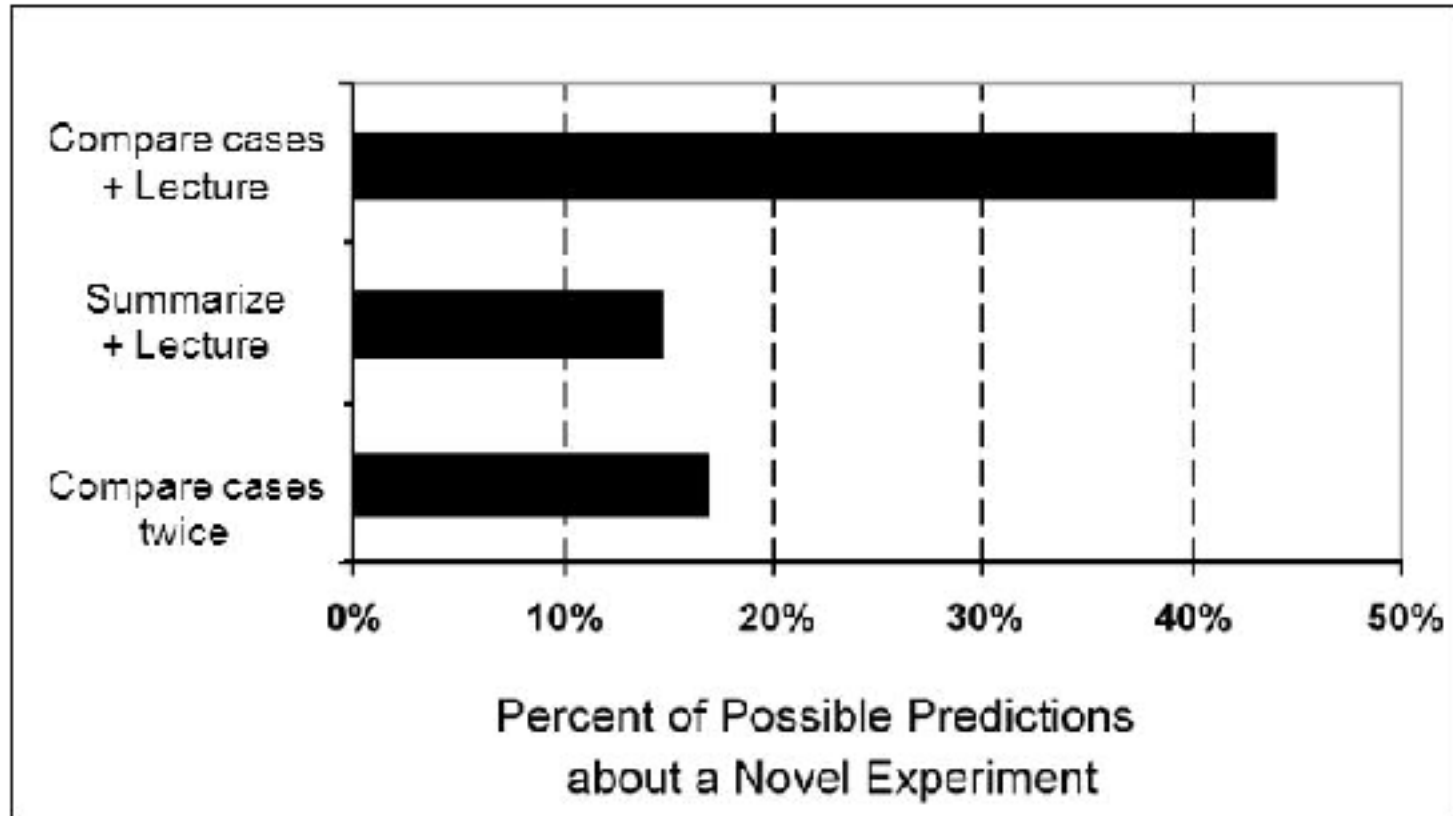
Exploration

Consolidation

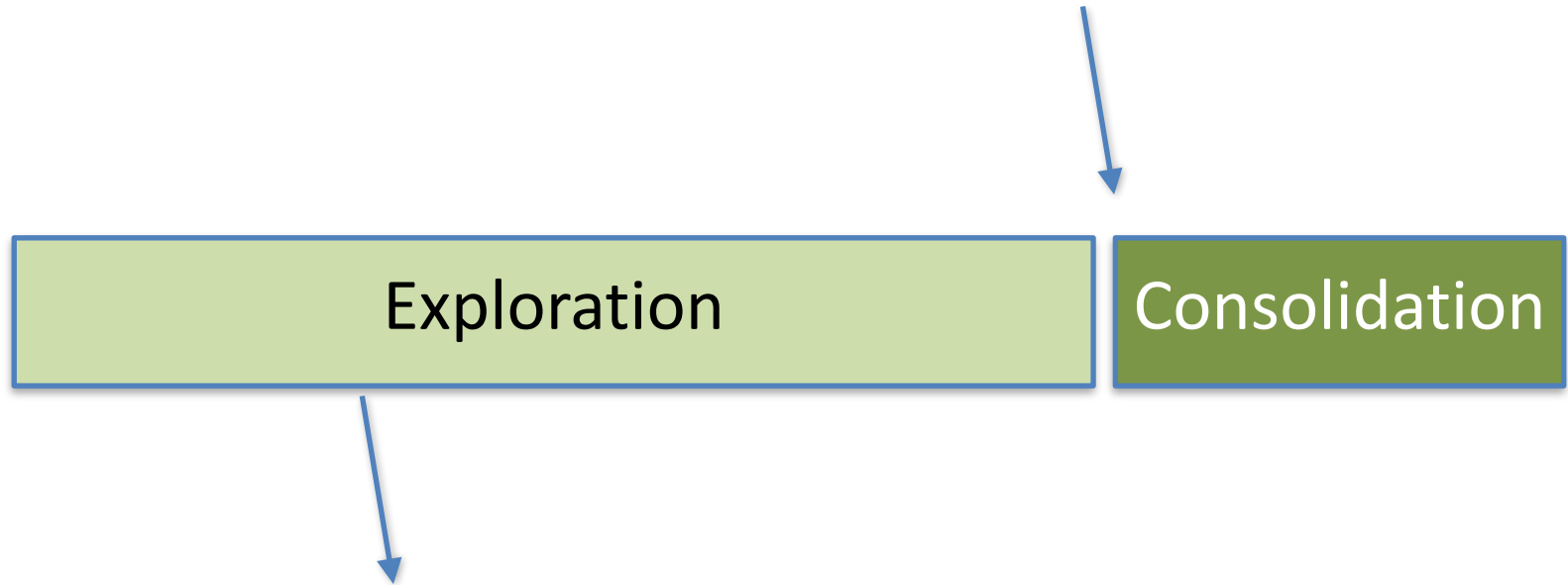
# « Contrasting Cases »



# « Contrasting Cases »



There is a time for telling



How to guide learners ?

[Don't imitate Monthly Python](#)

-

## Exploration

## Consolidation

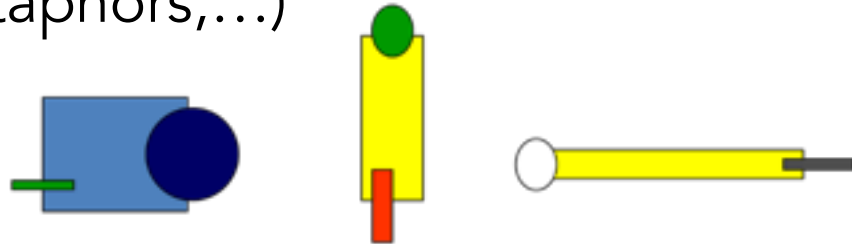
1. **Carefully design the data set** 
2. Comparisons, playing with differences
3. Conflict: trapping predictions
4. Advance organizers (metaphors,...)
5. Pushing reflection

| Year | Mike Arwen | Dave Backhand | Ivan Right |
|------|------------|---------------|------------|
| 1988 | 14         | 13            | 13         |
| 1989 | 9          | 9             | 18         |
| 1990 | 14         | 16            | 15         |
| 1991 | 10         | 14            | 10         |
| 1992 | 15         | 10            | 16         |
| 1993 | 11         | 11            | 10         |
| 1994 | 15         | 13            | 17         |
| 1995 | 11         | 14            | 10         |
| 1996 | 16         | 15            | 12         |
| 1997 | 12         | 19            | 14         |
| 1998 | 16         | 14            | 19         |
| 1999 | 12         | 12            | 14         |
| 2000 | 17         | 15            | 18         |
| 2001 | 13         | 14            | 9          |
| 2002 | 17         | 17            | 10         |

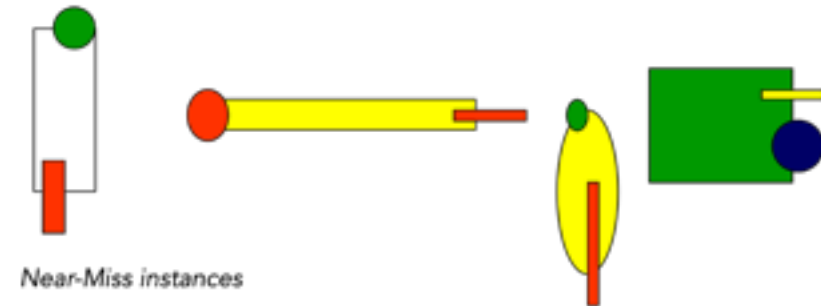
# Exploration

# Consolidation

1. Carefully design the data set
- 2. Comparisons, playing with differences**
3. Conflict: trapping predictions
4. Advance organizers (metaphors,...)
5. Pushing reflection



Positive instances



Near-Miss instances

Negative instances

Gloria and Tim were asked to solve  $5(x + 3) = 20$ .

Gloria's "distribute first" way

Tim's "divide first" way

First I distributed.

Then I subtracted on both sides.

I divided by 5.

Here is my answer.

?

$$5(x + 3) = 20$$

$$5x + 15 = 20$$

$$\downarrow$$

$$5x + 15 = 20$$

$$-15 \quad -15$$

$$\downarrow$$

$$\frac{5x}{5} = \frac{5}{5}$$

$$\downarrow$$

$$x = 1$$



$$5(x + 3) = 20$$

$$\frac{5(x + 3)}{5} = \frac{20}{5}$$

$$\downarrow$$

$$x + 3 = 4$$

$$-3 \quad -3$$

$$\downarrow$$

$$x = 1$$



?

First I divided by 5.

Then I subtracted from both sides.

Here is my answer.

?

How did Gloria and Tim find the solution to the equation?

1

Which method is better? What are some important differences between Gloria's "distribute first" method and Tim's "divide first" method?

## Exploration

## Consolidation

1. Carefully design the data set
2. Comparisons, playing with differences
- 3. Conflict: trapping predictions**
4. Advance organizers (metaphors,...)
5. Pushing reflection



## Exploration

## Consolidation

1. Carefully design the data set
2. Comparisons, playing with differences
3. Conflict: trapping predictions
- 4. Advance organizers (metaphors,...)**
5. Pushing reflection



## Exploration

## Consolidation

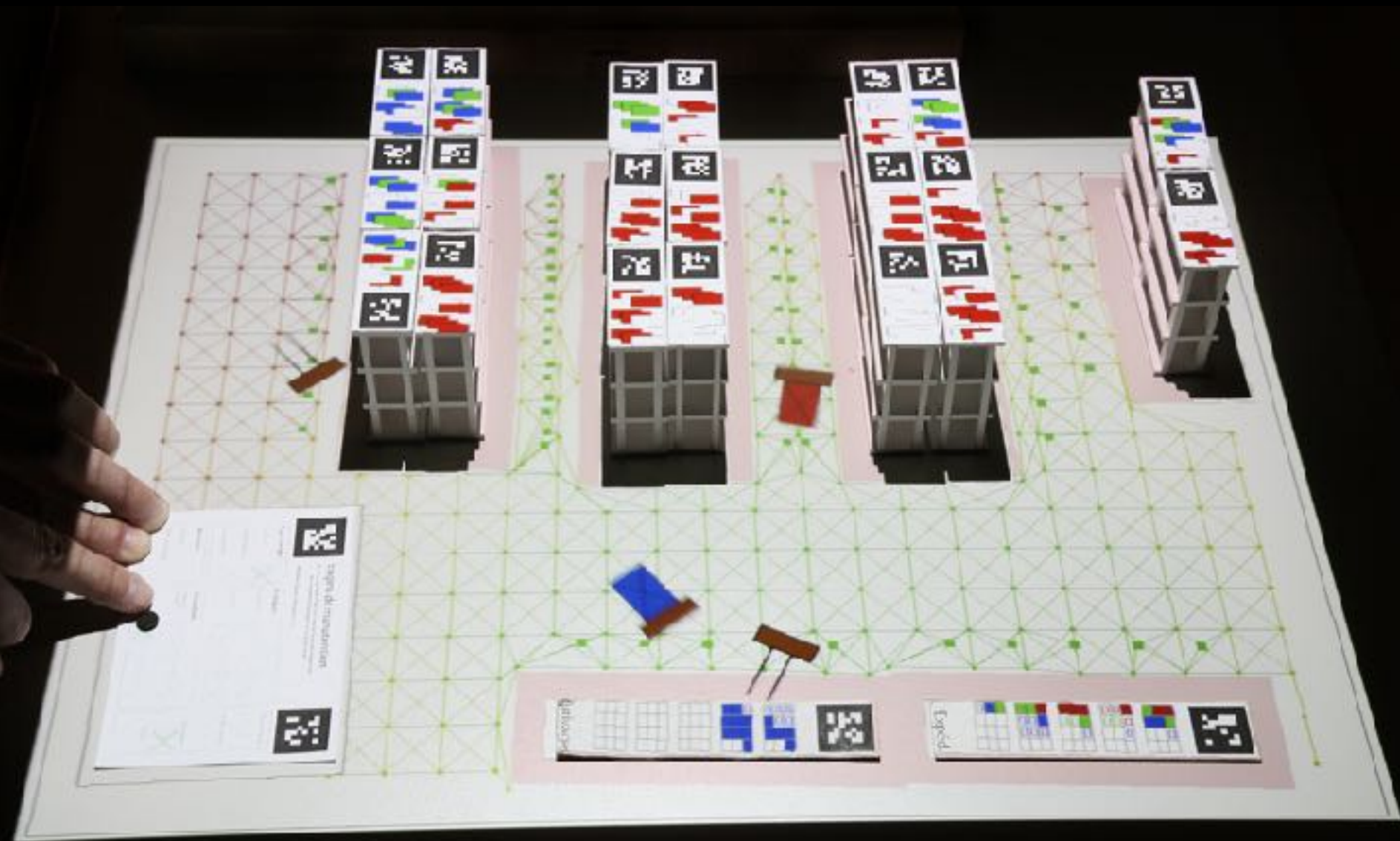


1. Carefully design the data set
2. Comparisons, playing with differences
3. Conflict: trapping predictions
4. Advance organizers (metaphors,...)
- 5. Pushing reflection**

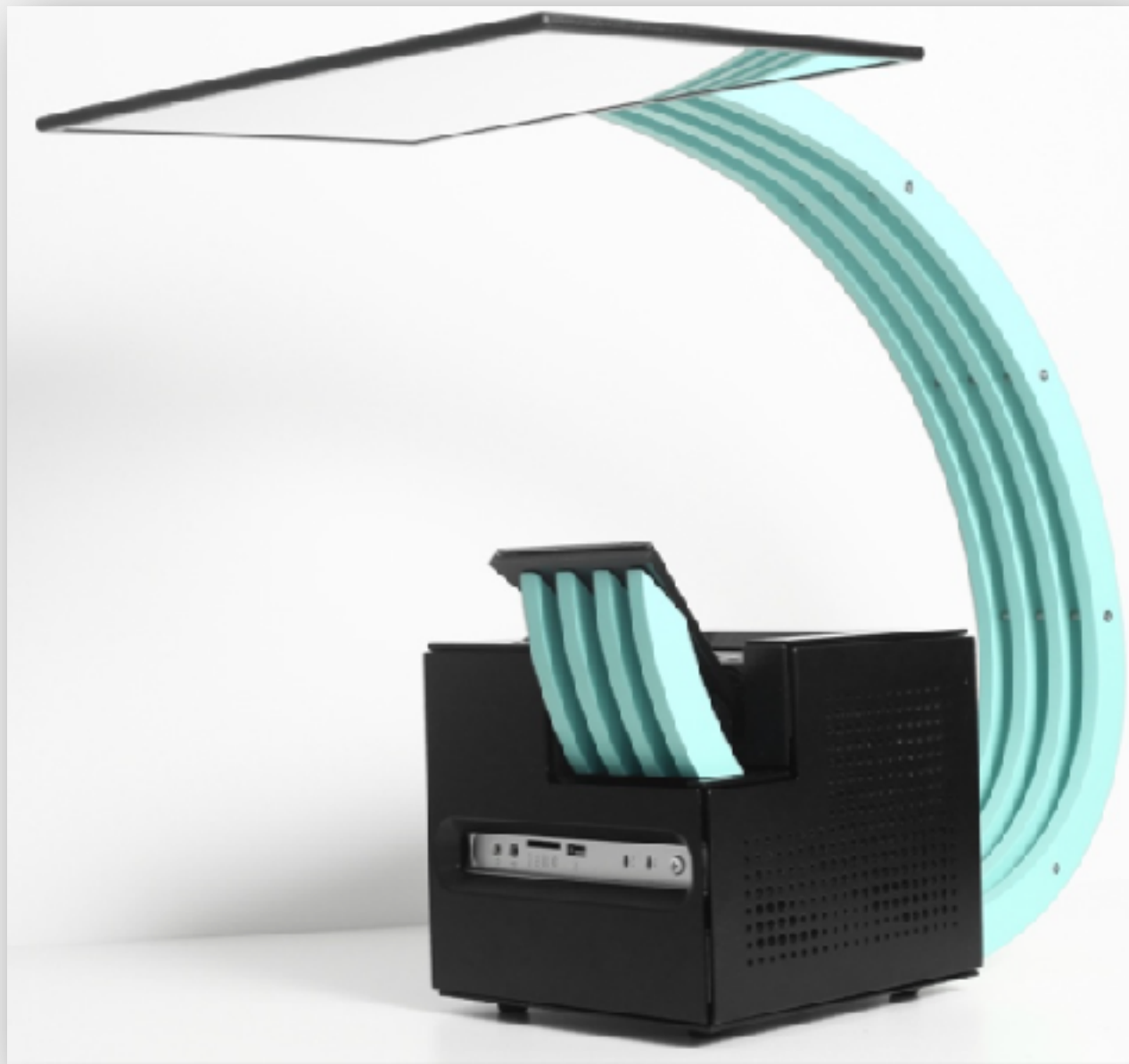


Apprentissage

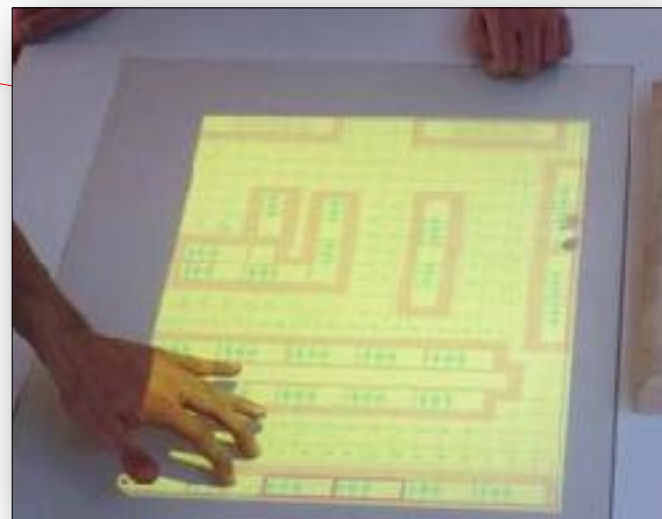
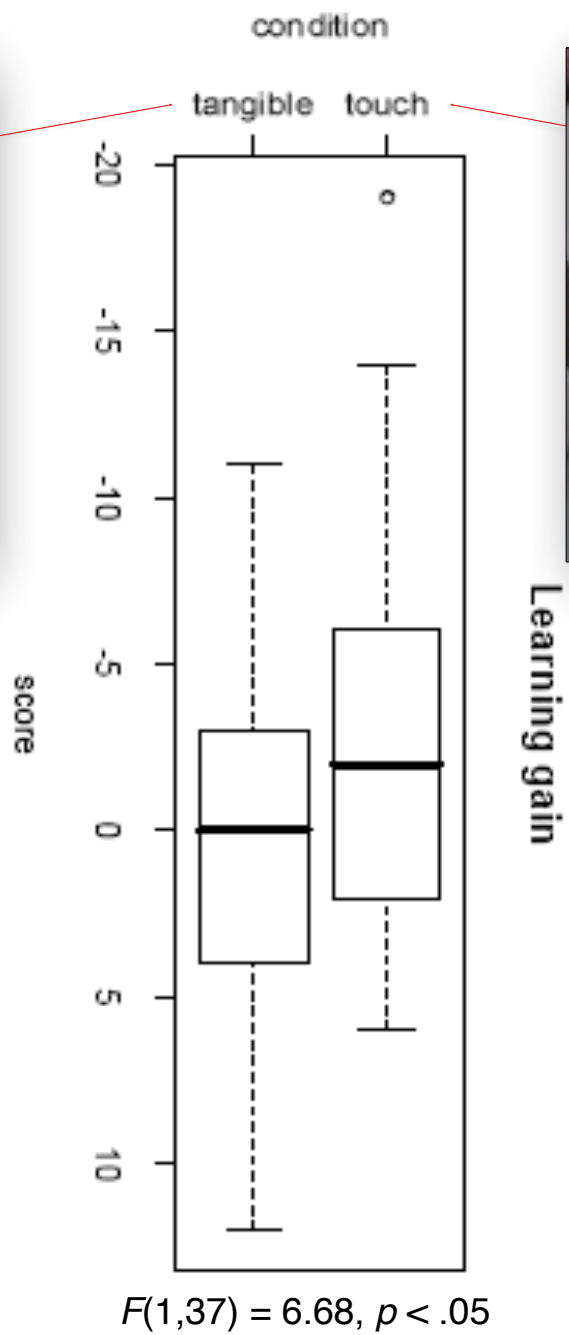


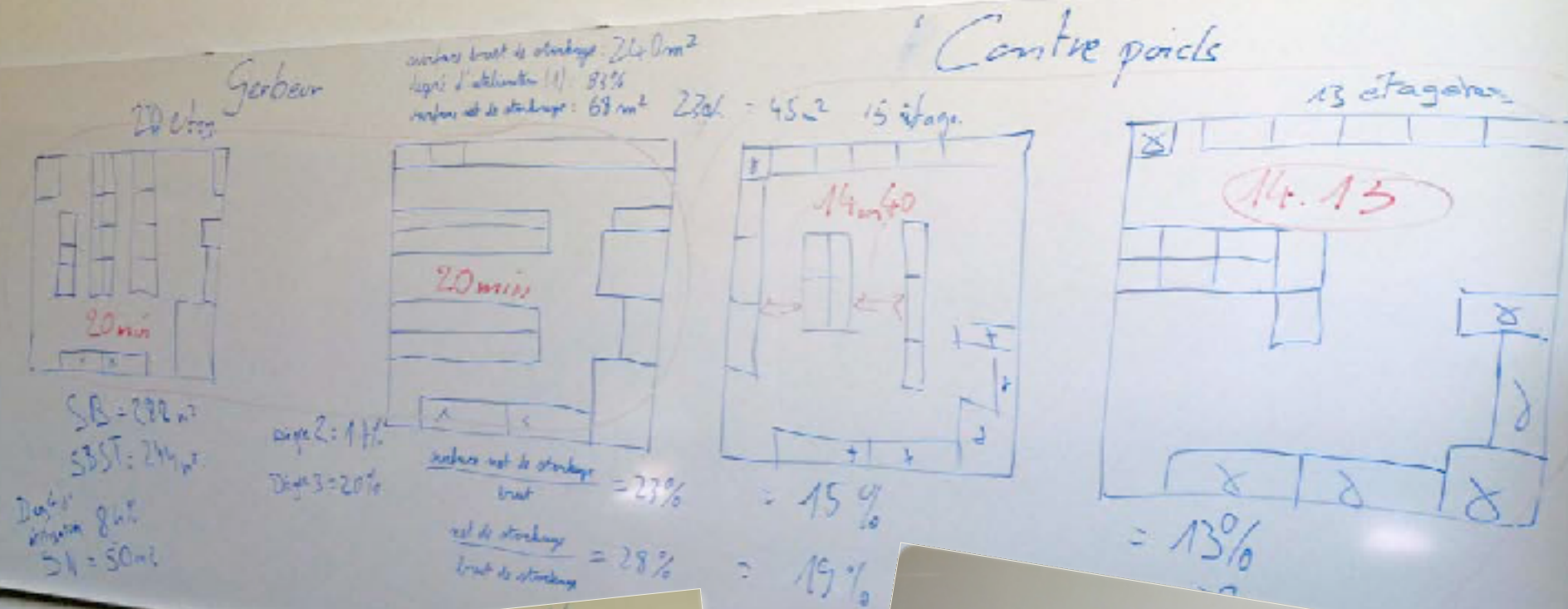


The TinkerLamp

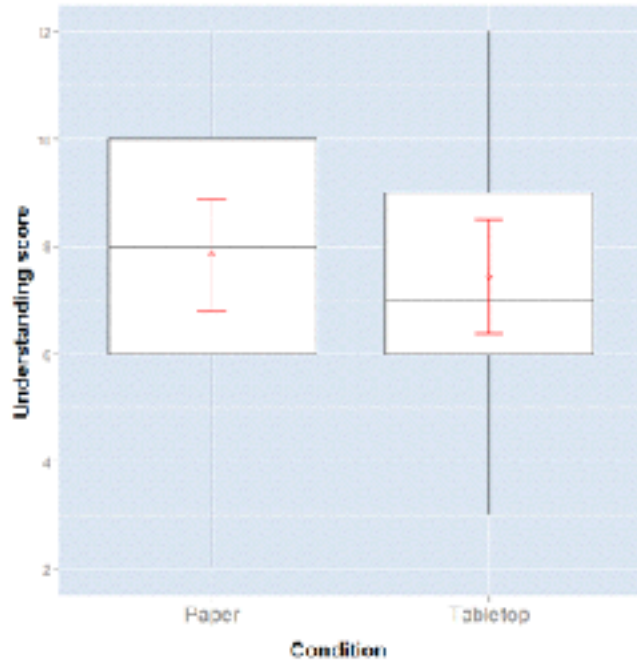






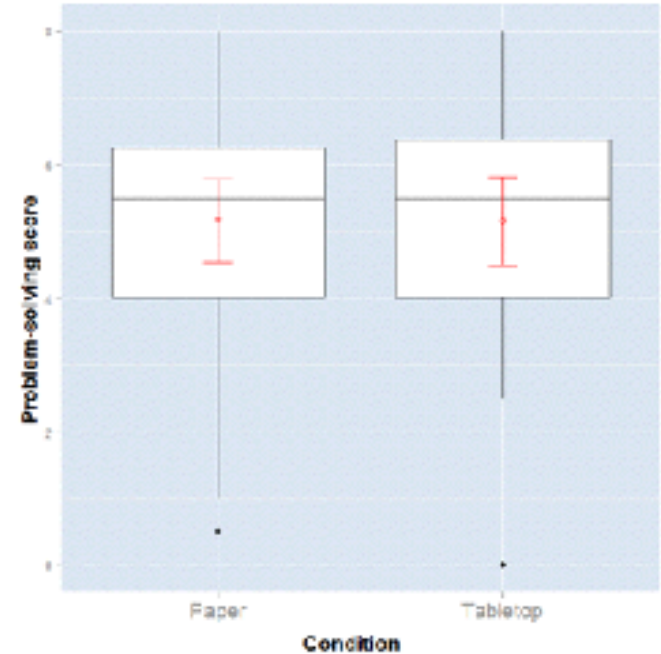


No sign. effect in  
understanding



mean = 7.84 vs. mean = 7.43  
 $F(1,14) = .25; p > .05$

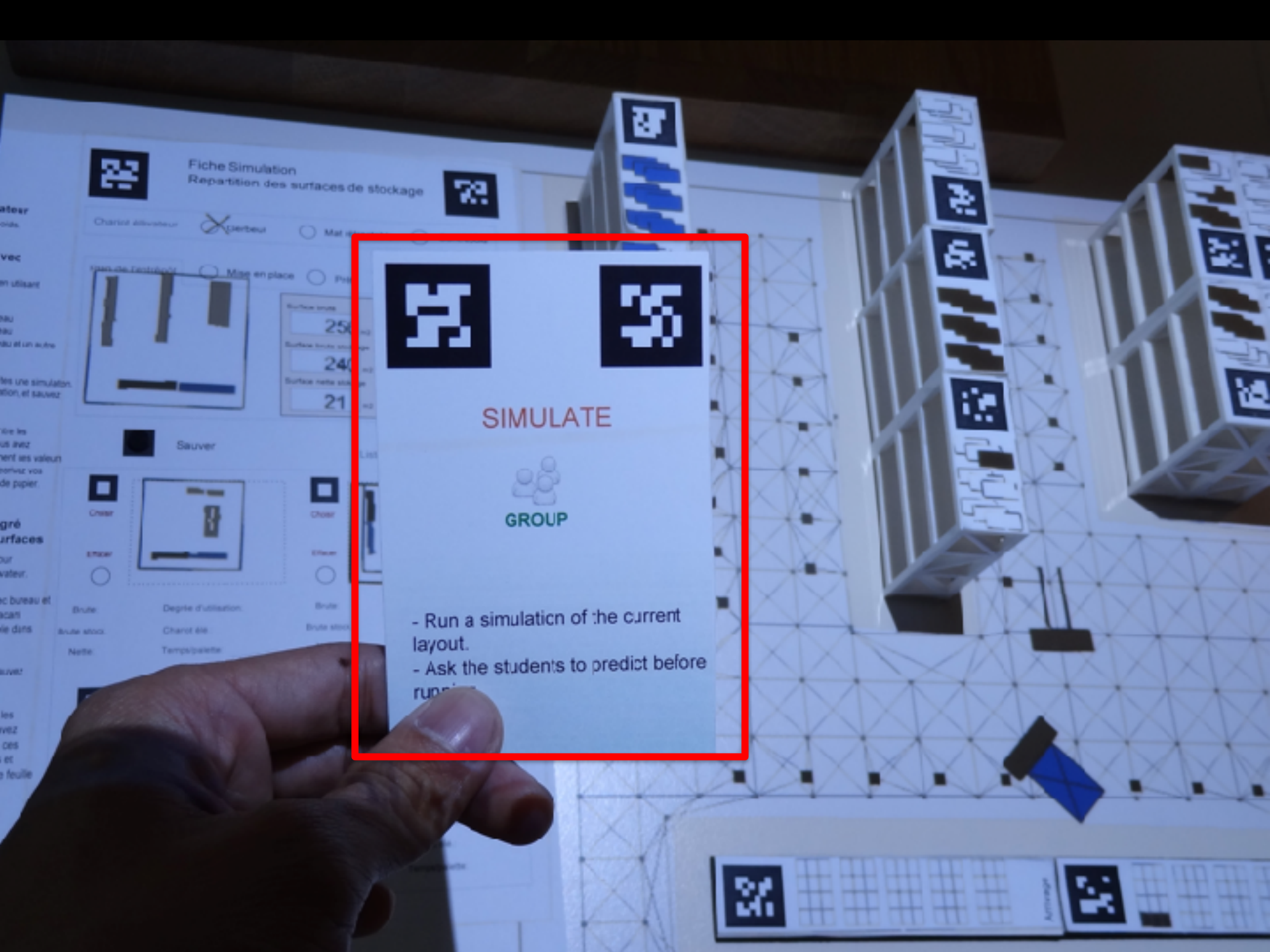
No sign. effect in  
problem-solving



mean = 5.16 vs. mean = 5.15  
 $F(1,14) = .06, p > .05$

# “Tentation de manipulation”





Fiche Simulation  
Repartition des surfaces de stockage

Chariot élévateur

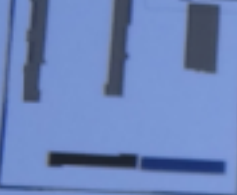


Matériau

Plan de l'entrepôt

Mise en place

Pré



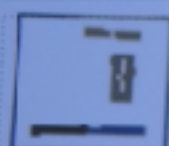
Surface brute  
25  
Surface brute stockée  
24  
Surface nette stockée  
21



Sauver



Charger



Charger



Effacer



Effacer

Brute:

Degré d'utilisation

Brute:

Brute stock

Chariot élé

Brute stock

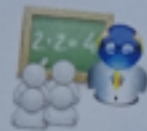
Nette

Temps palette

- Run a simulation of the current layout.
- Ask the students to predict before running



## PAUSE CLASS



CLASS

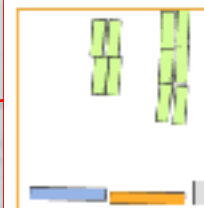
- Pause all the actions (simulation, building model, etc.) in the whole class

Orange



### Comparaison

☒ Afficher les dimensions



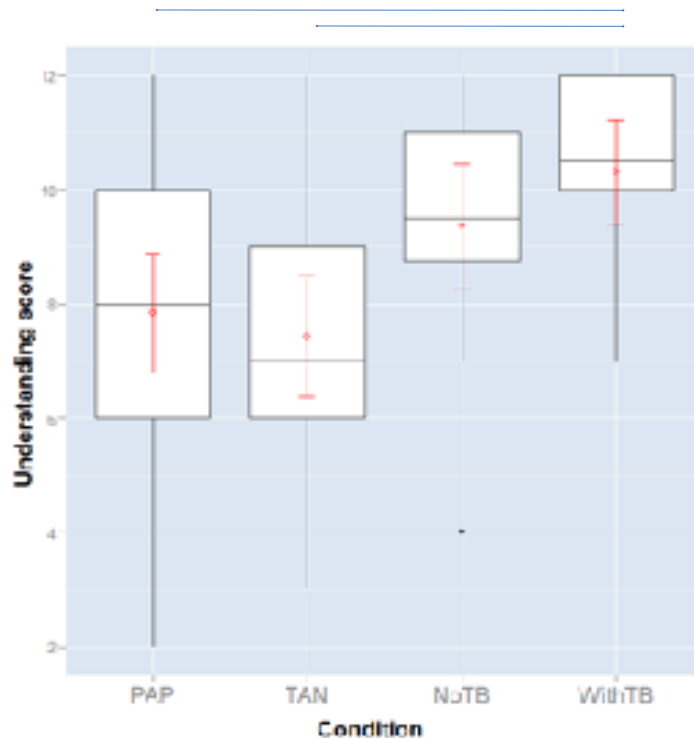
Brute: 256m2  
 Brute stock: 236m2  
 Netto: 30m2  
 Étagères: 12  
 Degré d'util.: 12.6%  
 Chariot: gerbeur  
 Temps/palette: 115s  
 Temps simul.: 0:13:49



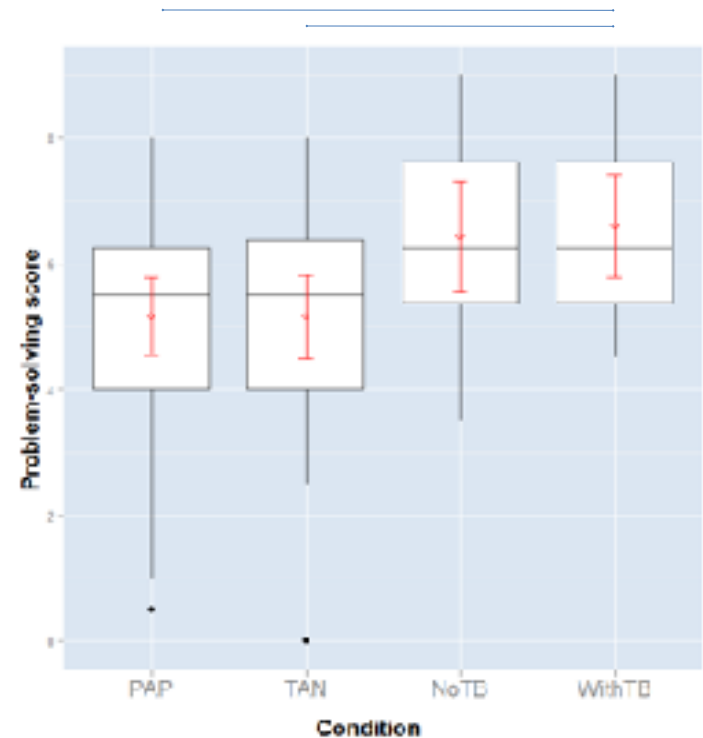
Brute: 256m2  
 Brute stock: 220m2  
 Netto: 36m2  
 Étagères: 12  
 Degré d'util.: 16.4%  
 Chariot: gerbeur  
 Temps/palette: 130s  
 Temps simul.: 0:23:40

# Post-test

Sign. effect in  
understanding



Sign. effect in  
problem-solving



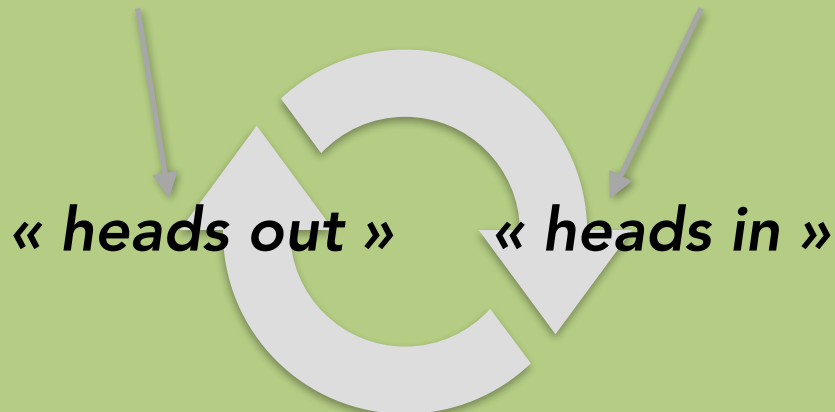
| Measures              | Warehouse study's conditions |                | Evaluation of TinkerLamp 2.0 conditions |                                  |
|-----------------------|------------------------------|----------------|-----------------------------------------|----------------------------------|
|                       | Paper/pen                    | TinkerLamp 1.0 | TinkerLamp 2.0<br>With TinkerBoard      | TinkerLamp 2.0<br>No TinkerBoard |
| Understanding score   | 7.84(2.05)                   | 7.43(2.02)     | 9.39(2.03)                              | 10.31(1.70)                      |
| Problem-solving score | 5.16(1.70)                   | 5.15(1.78)     | 6.44(1.65)                              | 6.59(1.53)                       |

## Exploration

## Consolidation

- 
1. Carefully design the data set
  2. Comparisons, playing with differences
  3. Conflict: trapping predictions
  4. Advance organizers (metaphors,...)
  5. **Pushing reflection**

**Reflection turns experience into knowledge**



How do people learn ? →

Which technology for learning ?

*Jean Piaget*



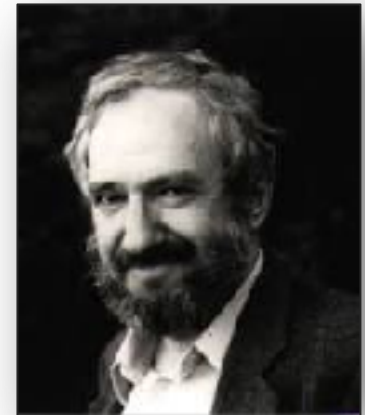
Scheme



Object to  
think with

If I cannot reach object A, I  
can take object B that  
connects my hand to A

To implement a complex  
program, I can decompose it  
into sub-problems

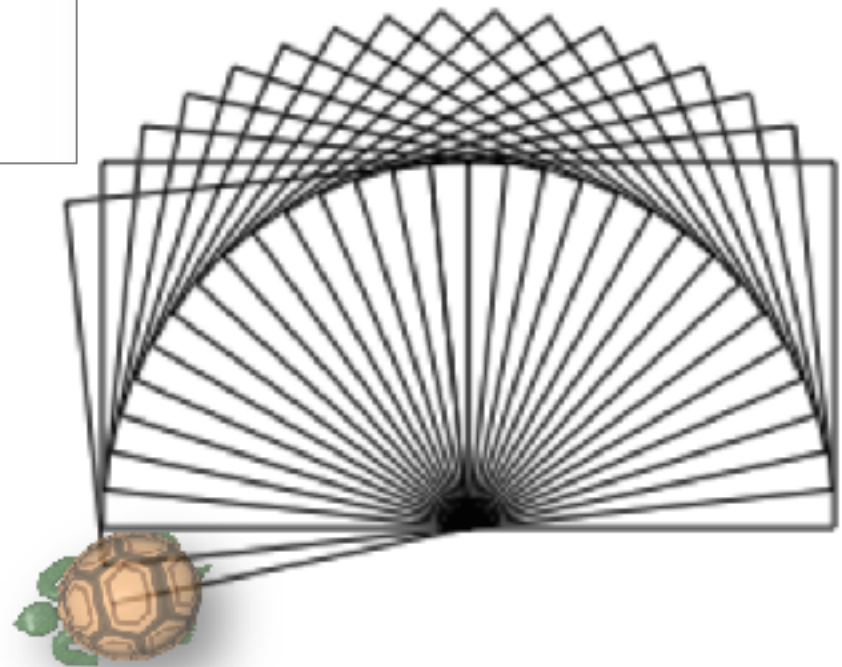


*Seymour Papert*

Function/method in  
programming language

# « MICROWORLD »

```
ExoLogO  
define "carre [[size]  
[repeat 4 [forward :size wait 0.1 right 90]]]  
  
define "fleur [[size]  
[clean repeat 60 [carre :size left 6]]]  
  
fleur 100
```

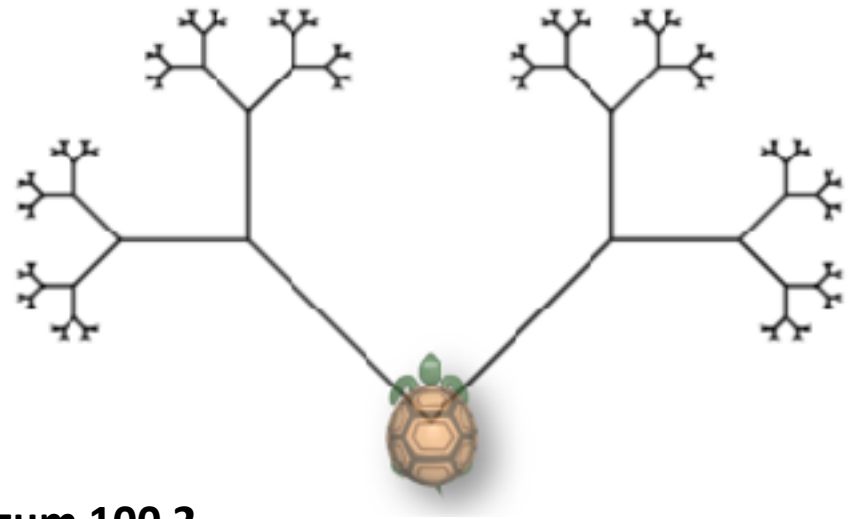


<http://www.alancsmith.co.uk/logo/>

```

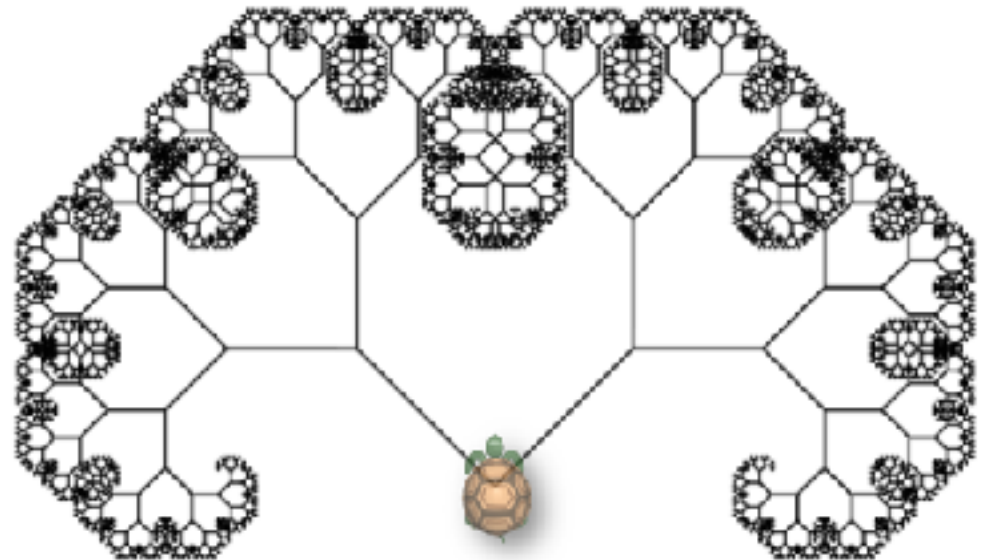
define "Zum" [[length divider]
  [if :length < 1
    [stop]
    [ left 45
      forward :length
      zum :length/:divider :divider
      back :length
      right 90
      forward :length
      zum :length/:divider :divider
      back :length
      left 45
    ]
  ]
]

```



**zum 100 2**

**zum 100 1.5**

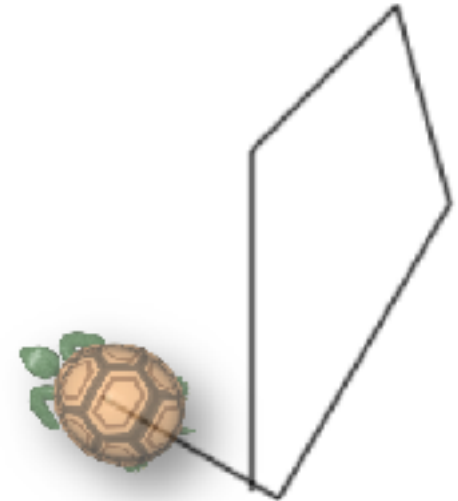


# Cognitive Conflict as key learning mechanism

(1) I want to get this



(2) I got that



```
define "house1 [[  
  [forward 100  
    right 45  
  forward 60  
    right 120  
  forward 60  
    right 45  
  forward 100  
    right 90  
  forward 60  
  ]  
]]
```



(3) The problem is here

METACOGNITION

## Cognitive Conflict as key learning mechanism

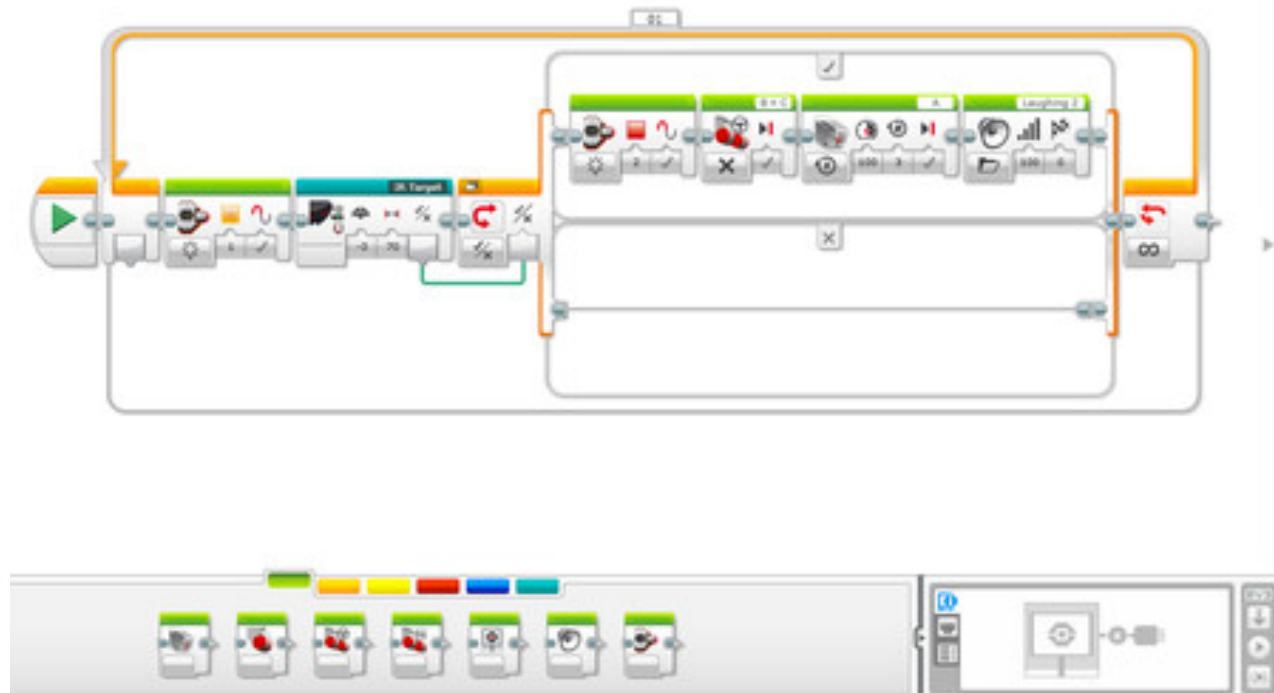
- Learning from experience
- Learning by doing
- Learning from failure
- Discovery learning

### Conditions:

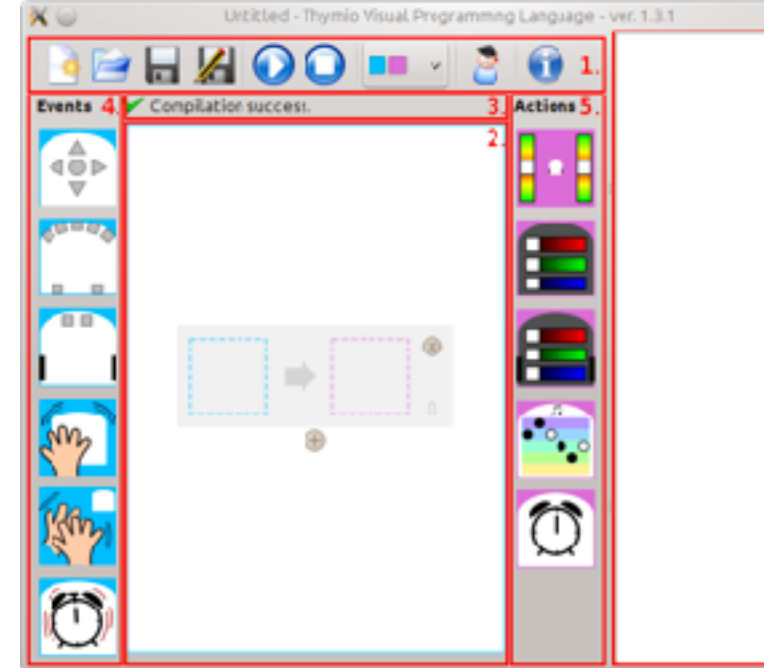
1. The conflict is detected
2. The learner finds how to solve it

*Role of the environment (sequence of projects / teacher / peer)*

constructivism → **constructionnism**



THYMIO



<https://aseba.wikidot.com/fr:thymiovgl>

<https://www.youtube.com/watch?v=8RiEDT8bsOs>



constructivism →  
constructionism

<http://guerrillamakerspace.squarespace.com/space-4/>



Digital Fabrication  
and Hands-on Learning in Education

<http://fablabatschool.org/>

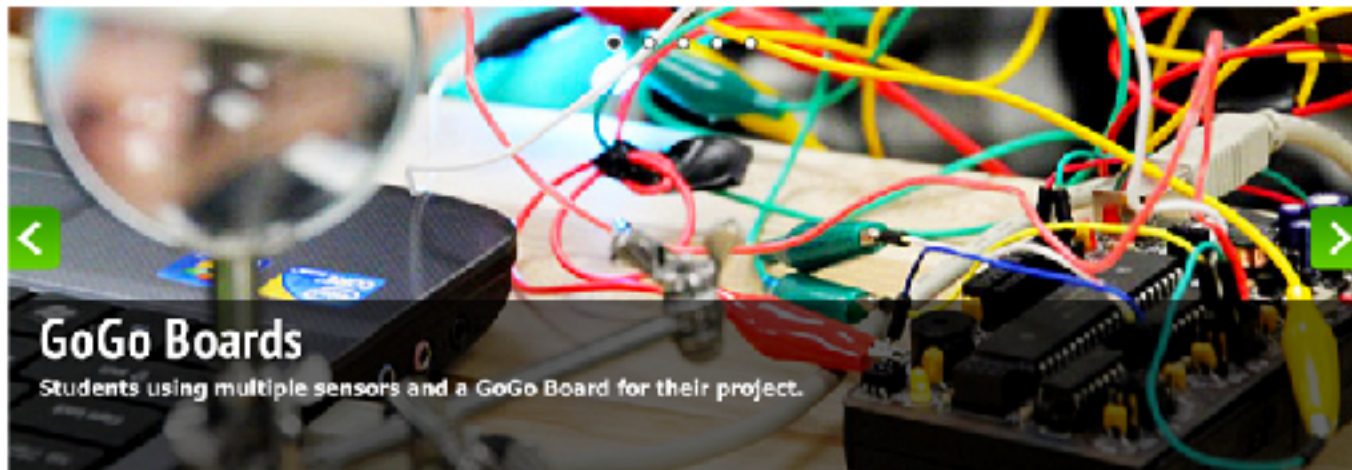
[About](#)

[Blogs](#)

[Photos](#)

[Projects](#)

[Resources](#)

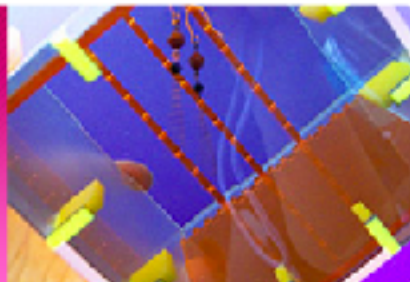


## GoGo Boards

Students using multiple sensors and a GoGo Board for their project.

## Projects

Check out past  
student projects!



## Resources

Find useful link,  
activities, and  
tutorials here!



## FabLab@School

A growing network of educational digital fabrication labs that put cutting-edge technology for design and construction - such as 3D printers and laser cutters - into the hands of middle and high school students.

### WORKSHOP @ IDC 2013

A half-day workshop on Digital Fabrication and Making in Education will take place on Monday afternoon, June 24th, 2013.

This is a satellite event of the 12th International Conference on Interaction Design and Children - IDC 2013.

FabLabs@School  
Around the World



CASTILLEJA  
SCHOOL

RUSSIA

STANFORD

THAILAND



How to Get a  
FabLab@  
School



<http://www.3ders.org/articles/20120701-fayetteville-free-library-launched-3d-printing-fab-lab.html>

# From constructivism to **constructionnism**



Seymour Papert, MIT



« *Radical* » *branch*

The scandal of education is that every time you teach something, you deprive a [student] of the pleasure and benefit of discovery.

I think schools generally do an effective and terribly damaging job of teaching children to be infantile, dependent, intellectually dishonest, passive and disrespectful to their own developmental capacities.

Every maker of video games knows something that the makers of curriculum don't seem to understand. You'll never see a video game being advertised as being easy. Kids who do not like school will tell you it's not because it's too hard.

Constructivism

Microworlds

*Radical*

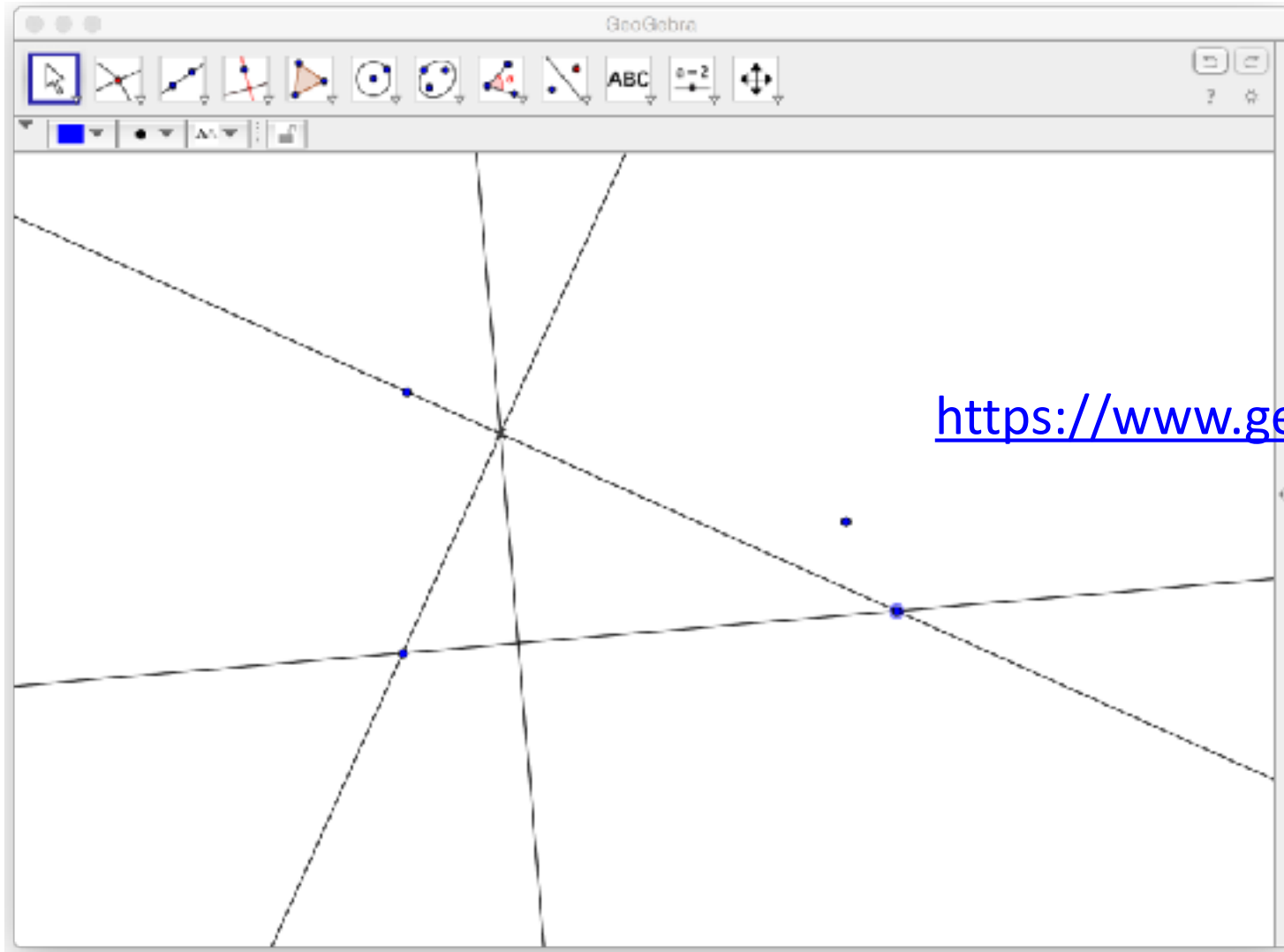
*Quest for  
effectiveness*

Constructionism

Guided Discovery

- *Content-rich microworlds*
- *Simulations*
- *Modelling*

# Quest for effectiveness: Adding Contents

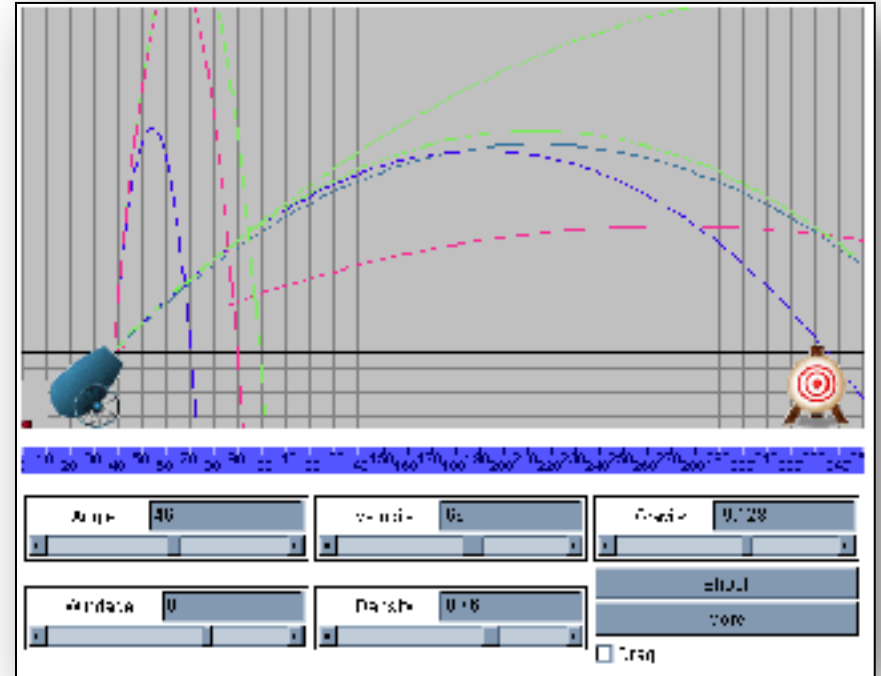


<https://www.geogebra.org/>

# Learning from Simulations



Acquire Skills



Discover underlying model

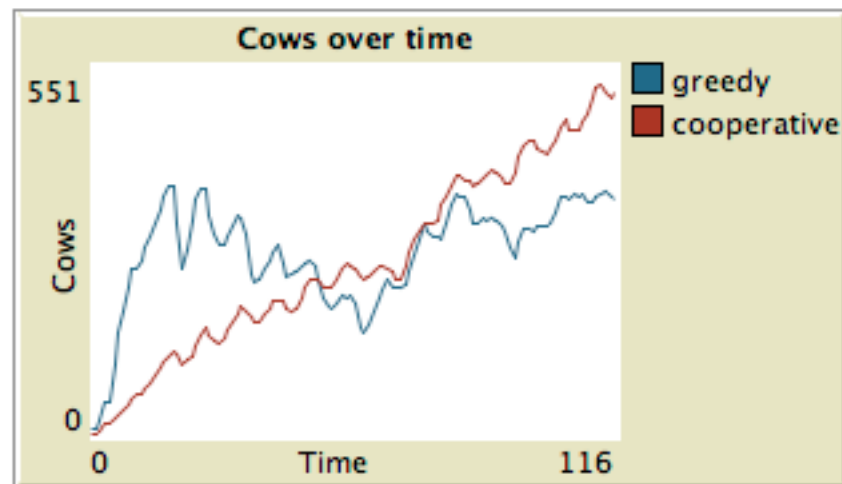
NET LOGO

button  normal speed ☒ view updates on ticks Settings...

setup go

basic sliders:

|                              |                    |
|------------------------------|--------------------|
| initial-cows 20              | stride-length 0.08 |
| cooperative-probability 0.50 | metabolism 6       |
| reproduction-cost 54         |                    |
| reproduction-threshold 102   |                    |



# greedy cows  
353

# cooperative cows  
508



advanced sliders:

|                       |                      |
|-----------------------|----------------------|
| high-growth-chance 77 | grass-energy 51      |
| low-growth-chance 30  | max-grass-height 10  |
|                       | low-high-threshold 5 |

# Learning from Simulations

More [examples](#)

An Overview paper

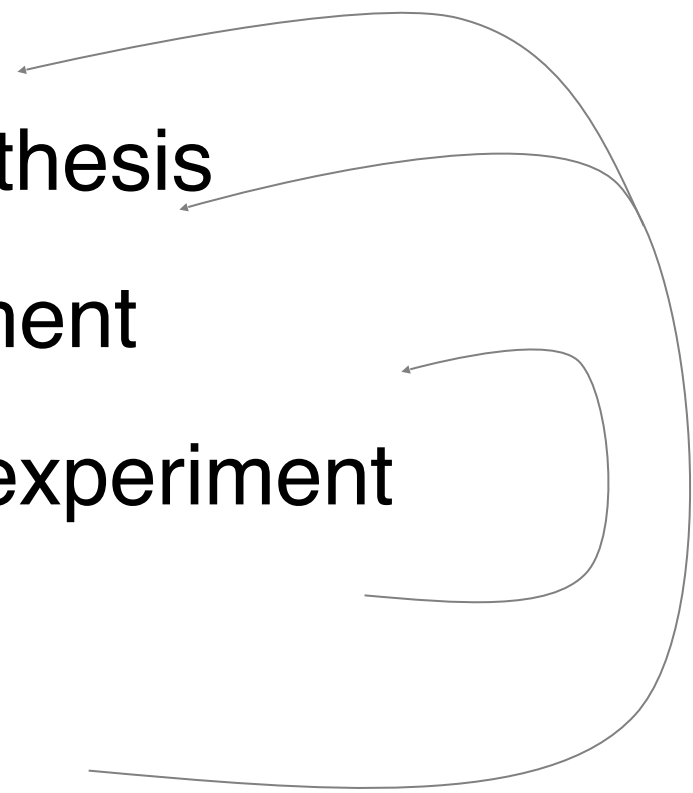
# Inquiry learning

“Inquiry-based learning involves learners

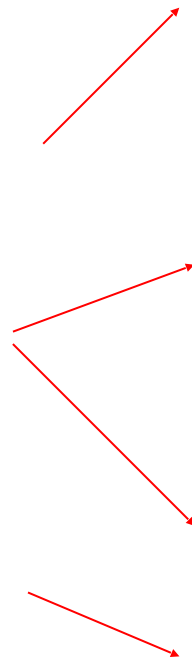
- asking **questions** about the natural or material world,
- collecting **data** to answer those questions,
- making **discoveries** and
- **testing** those discoveries rigorously”

*de Jong, 2006*

# Hypothetico-deductive reasoning

1. (Raise a question)
  2. Generate an hypothesis
  3. Design an experiment
  4. Run/simulate the experiment
  5. Interpret results
- 
- The diagram illustrates the iterative nature of the hypothetico-deductive process. It features five numbered steps. Curved arrows indicate feedback loops from later steps back to earlier ones: from step 5 to step 1, from step 4 to step 3, and from step 3 to step 2. These loops suggest that the process is not strictly linear and allows for revisiting previous stages based on new information or results.

# But...

1. Question
  2. Hypothesis
  3. Design
  4. Run
  5. Interpret
- No clear hypothesis is formulated or badly formulated (42% ), i.e. no relationship between variables
  - Design unconvulsive experiments, students vary several parameters at at time
  - Confirmation bias: to design experience that confirm the hypothesis
  - 35% to 63% errors in data interpretation and graphics readings
- 
- ```
graph LR; H2[Hypothesis] --> E1[No clear hypothesis...]; H3[Design] --> E2[Design unconvulsive...]; H4[Run] --> E3[Confirmation bias...]; H5[Interpret] --> E4[35% to 63% errors...];
```

# And...

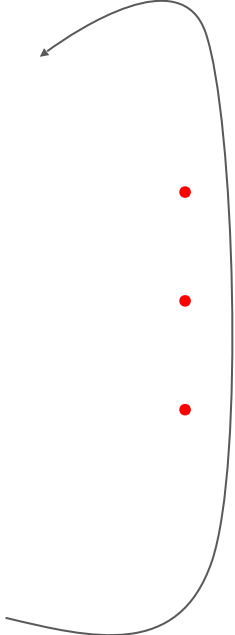
1. Question

2. Hypothesis

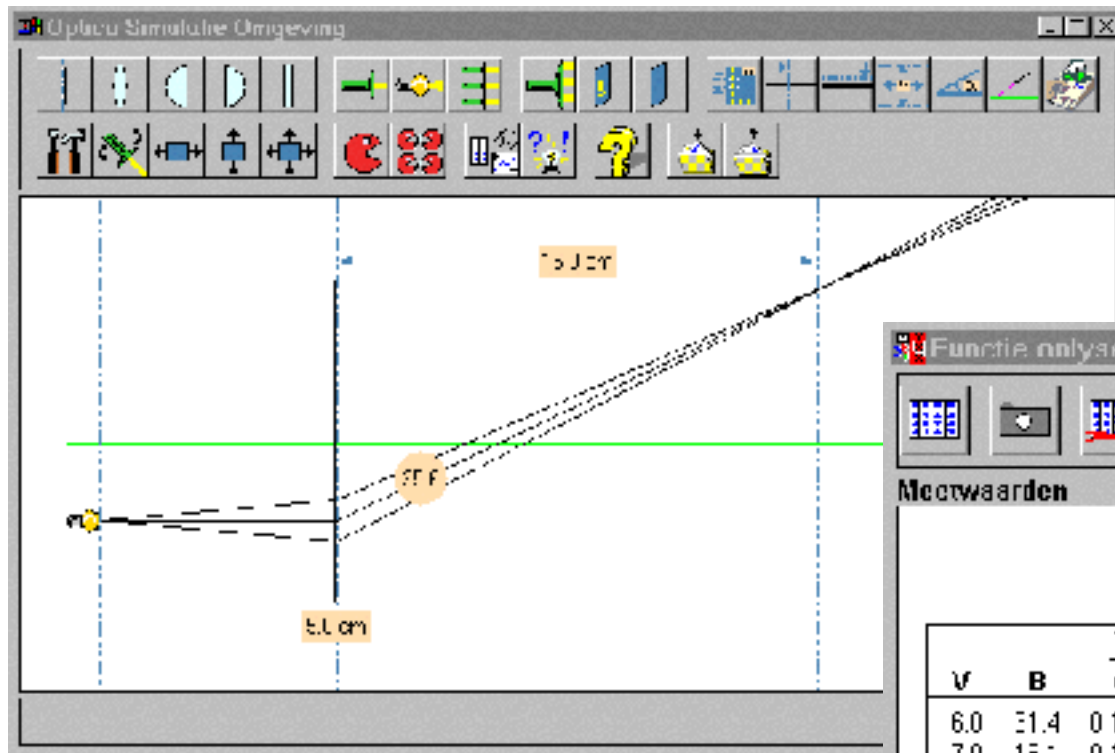
3. Design

4. Run

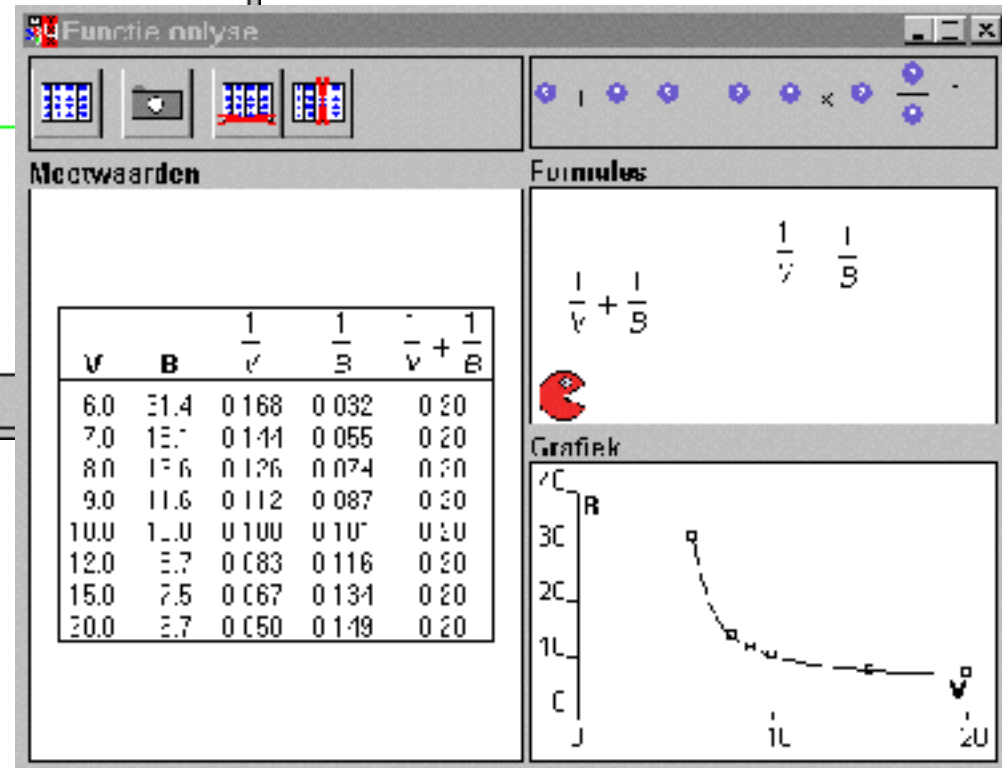
5. Interpret

- 
- Change several parameters
  - Keep hypothesis despite negative evidence
  - Reject hypothesis despite positive evidence

# Example of **tools** to overcome these pitfalls



Tool to express hypotheses



# Example of **scenario** to overcome these pitfalls

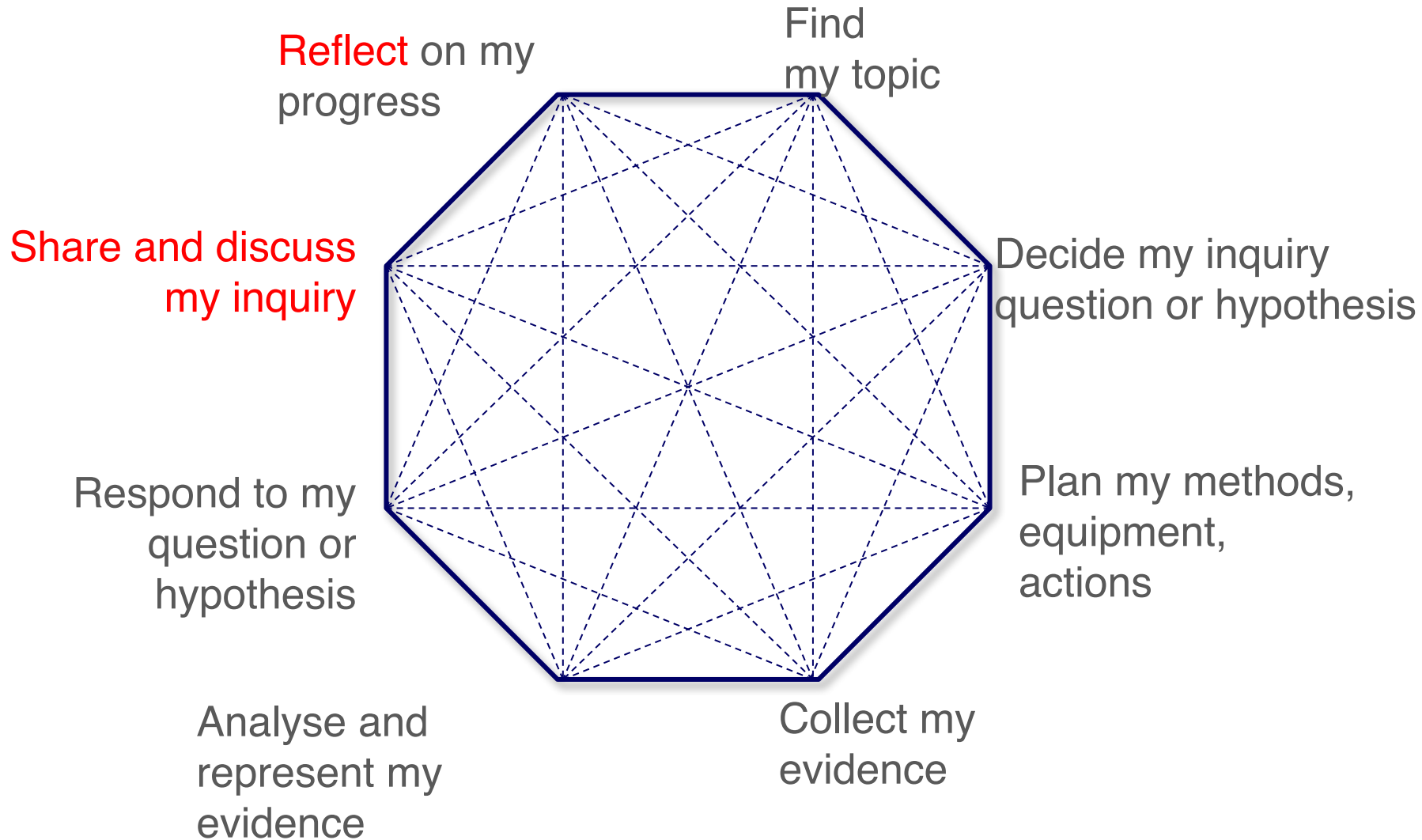
- ① Ask students to write their hypothesis
- ② Find student with conflicting hypothesis
- ③ Ask them to find out with the simulation which hypothesis is right

Gijlers, H., & De Jong, T. (2005). The relation between prior knowledge and students' collaborative discovery learning processes. *Journal of research in science teaching*, 42(3), 264-282.

The effects of any learning technology  
depends upon the quality of  
classroom **orchestration**

# Cycle of engagement and reflection

by Mike Sharples, Open University



# Inquiry is a more open process than simulations

A lesson is not inquiry based if:

- Students know what results they are supposed to get
- The questions and steps are pre-determined for them
- The teacher is working harder than the students

**Healthy Eating** Version ID: BCTA2.m4f@GIT:135a2905-62b6524660373

My progress: 1 - 2 - 3 - 4 - 5

**Healthy Eating**  
An investigation of healthy diet and nutrients.

**Navigation**

- Find my topic
- Decide my inquiry question or hypothesis
- Plan my methods, equipment & actions
- Collect my evidence
  - My data
- Analyze and represent my evidence
- Respond to my question or hypothesis
- Share and discuss my inquiry
- Reflect on my progress

My inquiries > Healthy Eating > Collect my evidence > Food diary for 20.09.2010 (Breakfast) >

**Food diary for 20.09.2010 (Breakfast)**

View Edit

Submitted by Amelia Student on Mon, 09/09/2010 - 22:34

**Breakfast**

| Food                        | Portion Size |
|-----------------------------|--------------|
| Bread - Brown               | 2 slice(s)   |
| Meat - Red                  | 1 portion    |
| Pulses (peas/beans/lentils) | 1 portion    |
| Egg                         | 2 portion    |

**Dinner**

| Food                        | Portion Size |
|-----------------------------|--------------|
| Bread - Brown               | 2 slice(s)   |
| Meat - Red                  | 1 portion    |
| Pulses (peas/beans/lentils) | 1 portion    |
| Egg                         | 2 portion    |
| Meat - White                | 1 portion    |
| Vegetables                  | 1 portion    |

**Snack**

| Food   | Portion Size |
|--------|--------------|
| Yogurt | 1 portion    |

| Sensors                          |
|----------------------------------|
| 3 cm Wave Signal Strength        |
| AC Millivolt                     |
| Accelerometer 2 axis             |
| Accelerometer 3 axis             |
| Altimeter                        |
| Anemometer                       |
| Carbon Dioxide                   |
| Carbon Dioxide Replacement Cell  |
| Carbon Monoxide                  |
| Carbon Monoxide Replacement Cell |
| Charge Sensor                    |
| Conductivity                     |
| Current ±1 A                     |
| Current ±1 mA                    |
| Current ±10 A                    |
| Current ±100 mA                  |
| Distance IR                      |
| Distance Ultrasonic Basic        |
| Electrosmog advanced             |
| Electrosmog Basic                |
| Flow Advanced                    |
| Flow Meter                       |
| Force Dual Range                 |
| Frequency                        |
| Humidity                         |
| IR Irradiance                    |
| Joulemeter                       |
| Light (Advanced)                 |
| Light (General Purpose)          |
| Magnetic Field with 100mT Probe  |
| Magnetic Probe 30 mT             |
| Nitrogen Dioxide                 |
| Oxygen Atmospheric               |
| Oxygen Atmospheric Cell          |
| Oxygen Probe - Dissolved         |
| pH Interface                     |
| pH Probe Sensor - advanced       |
| pH Probe Sensor - basic          |
| Pressure (Absolute 0 - 700 KPa)  |
| Pressure (Absolute 0 - 200 KPa)  |

Sharples, M., Collins, T., FeilssM., Gaved, M., Mulholland, P., Paxton, M., & Wright, M. (2011) A Laboratory of Knowledge-Making for Personal Inquiry Learning. Artificial Intelligence in Education.



# ScienceScope

Linking ICT With Science Education

<http://www.sciencescope.co.uk/Pages/SensorCategories.aspx>

Constructivism

Microworlds

*Radical*

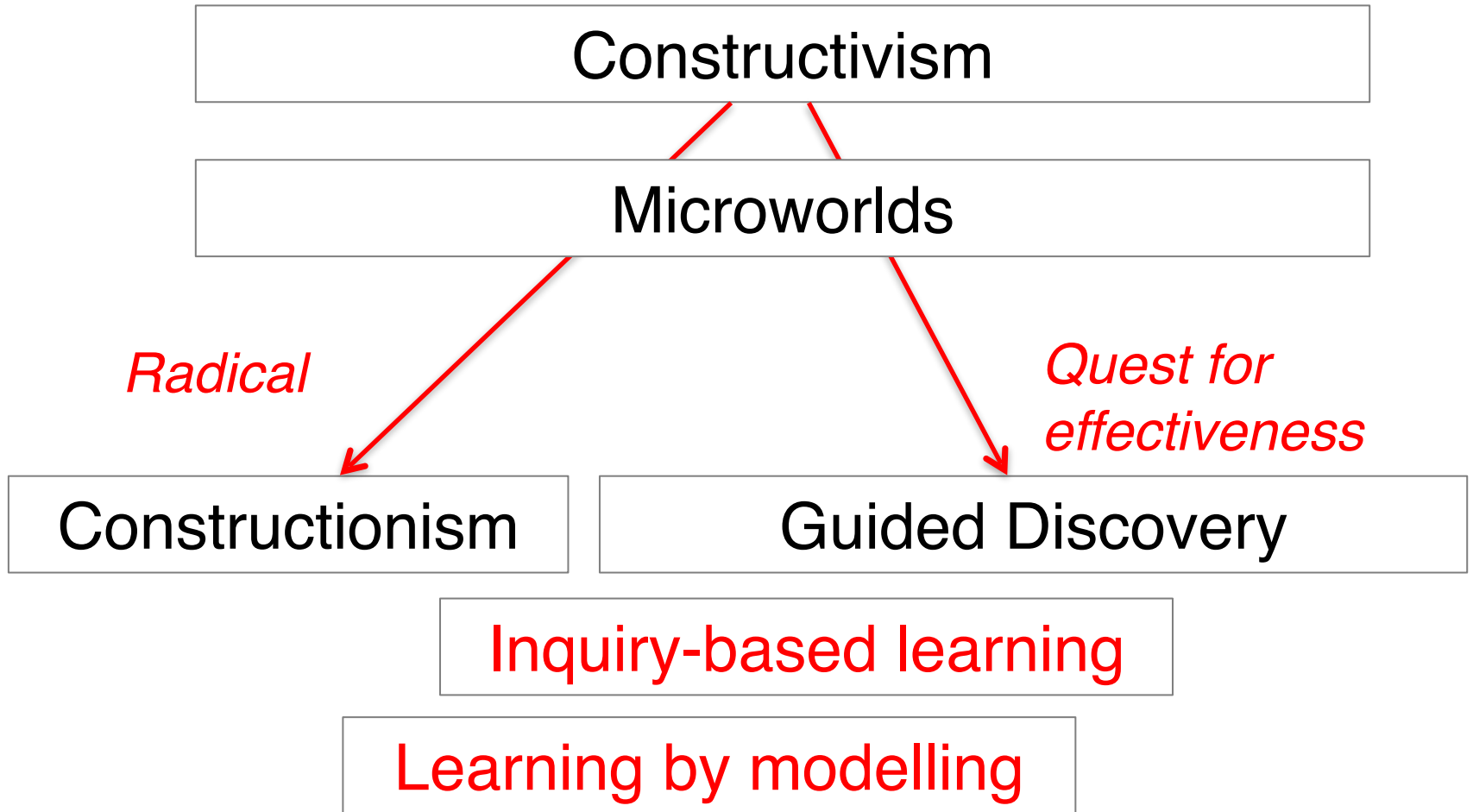
*Quest for  
effectiveness*

Constructionism

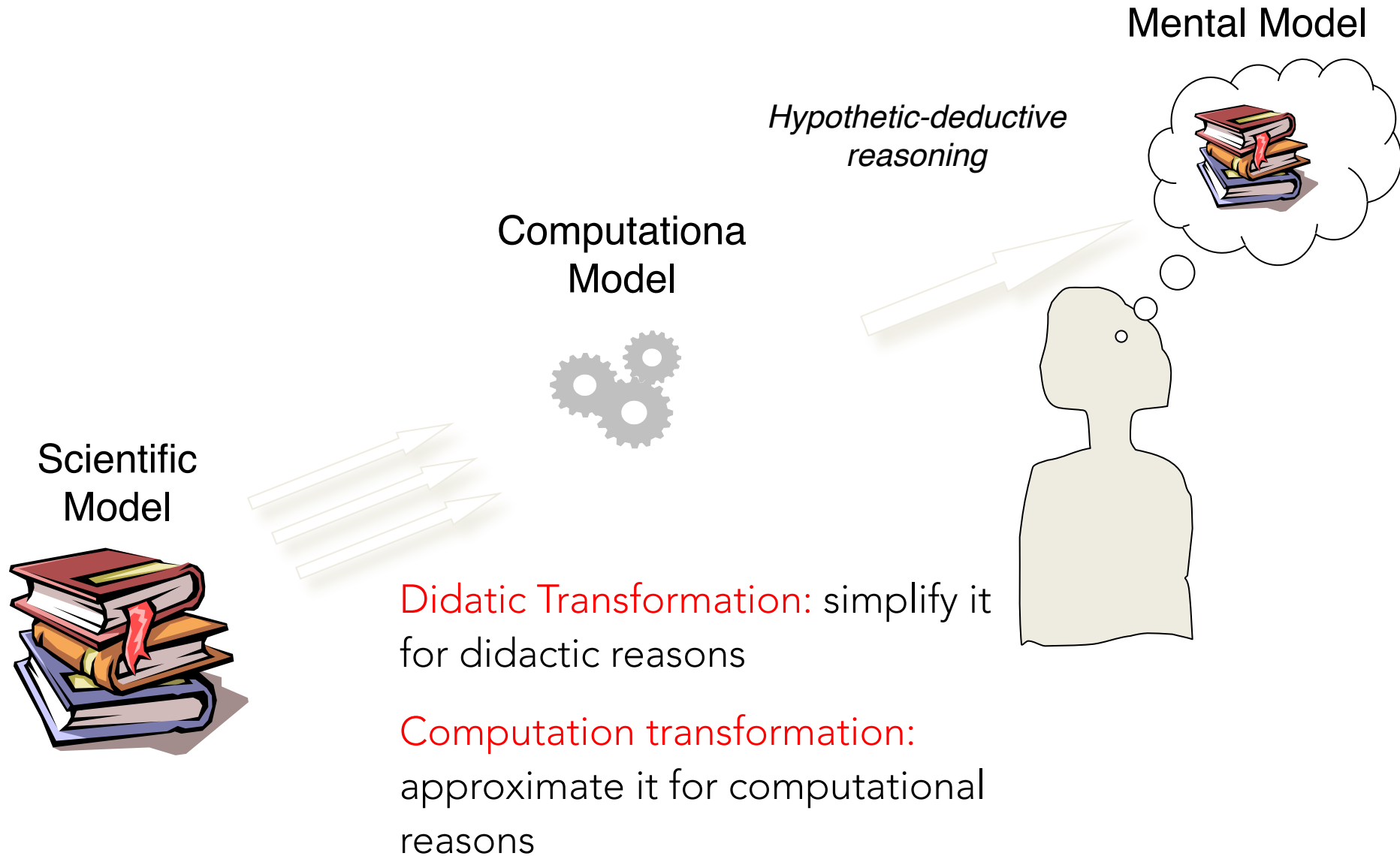
Guided Discovery

Inquiry-based learning

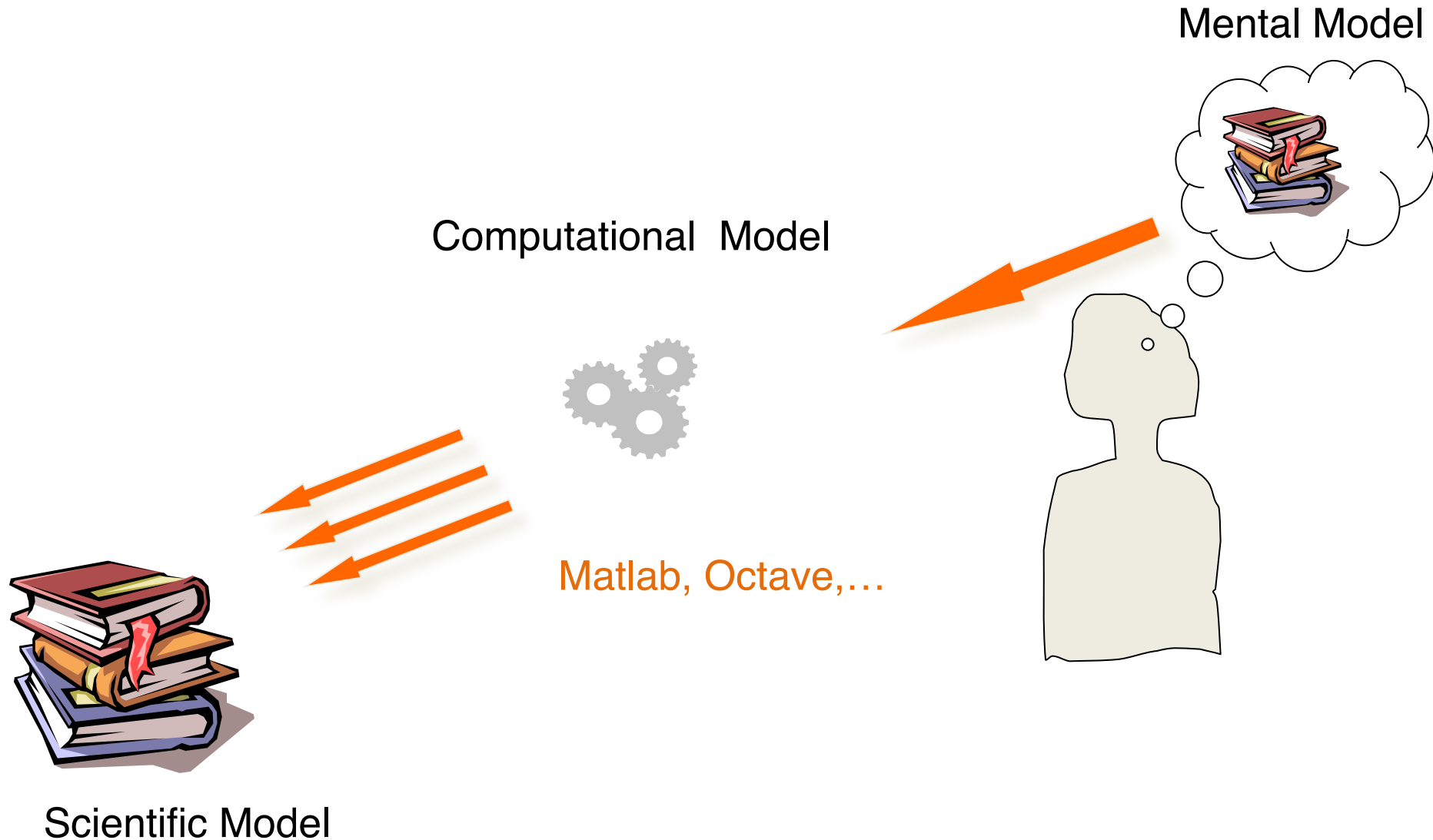
Learning by modelling



# Learning from simulations



# Learning from modelling



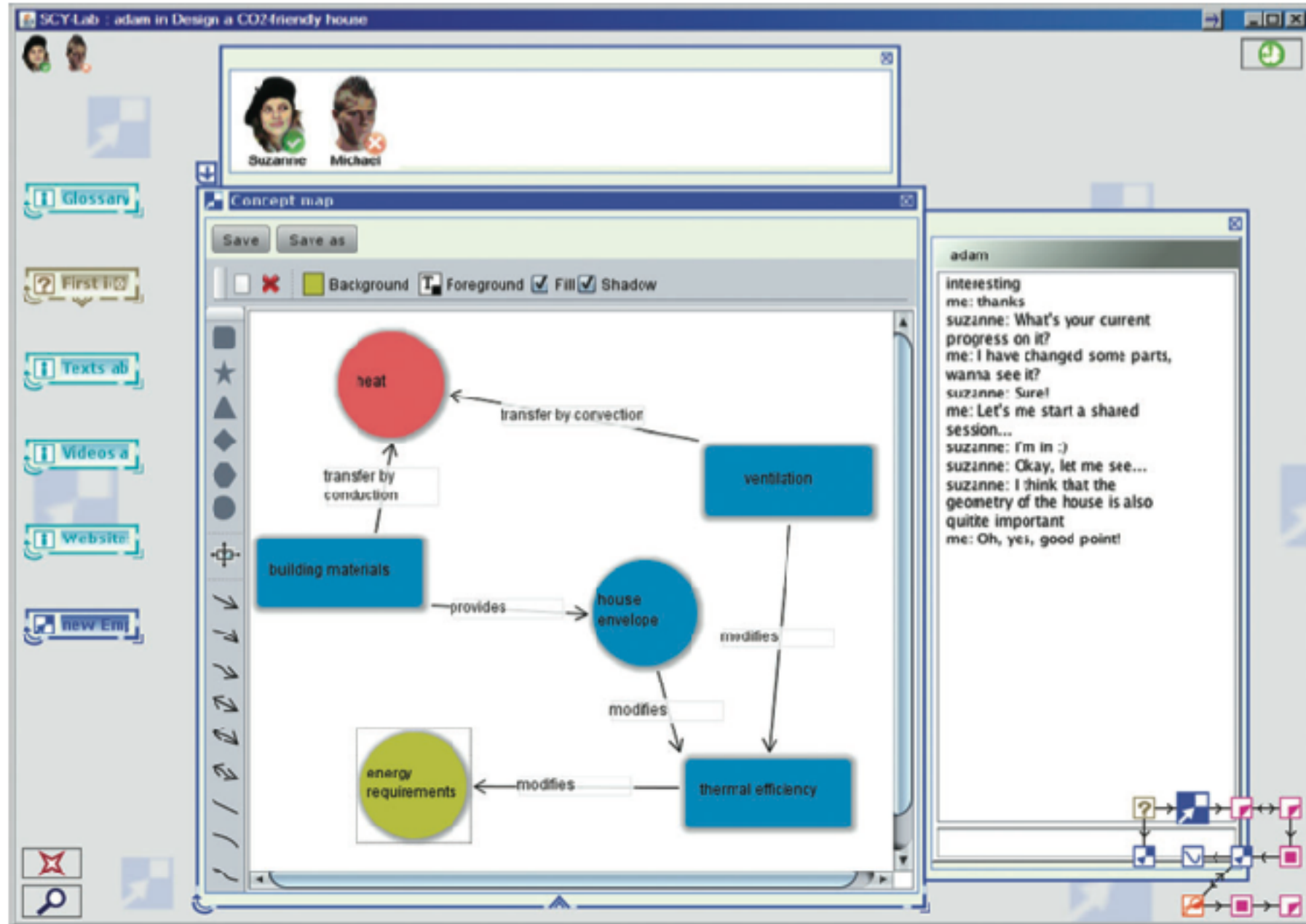
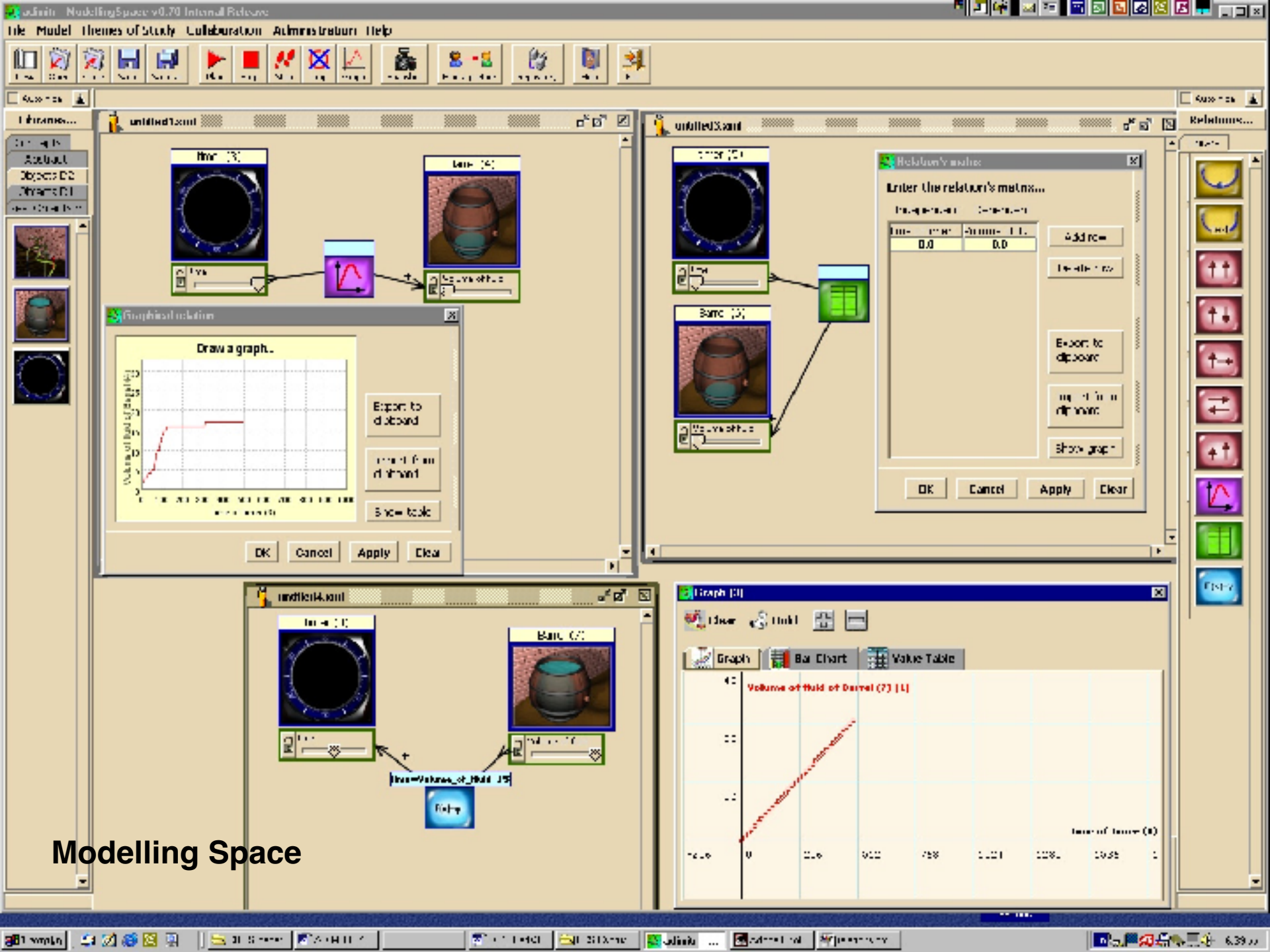


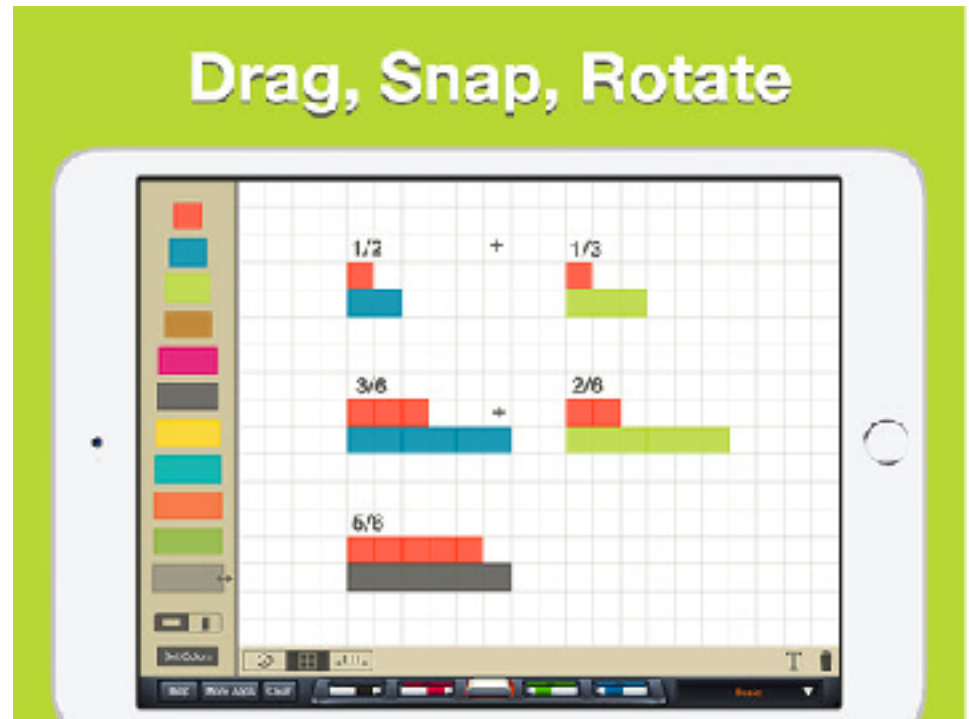
Figure 2: A SCY concept map with drawers attached. Available peers are above and a SCYchat is active to the right



# Manipulating real or virtual objects ?



Cuisenaire Rods

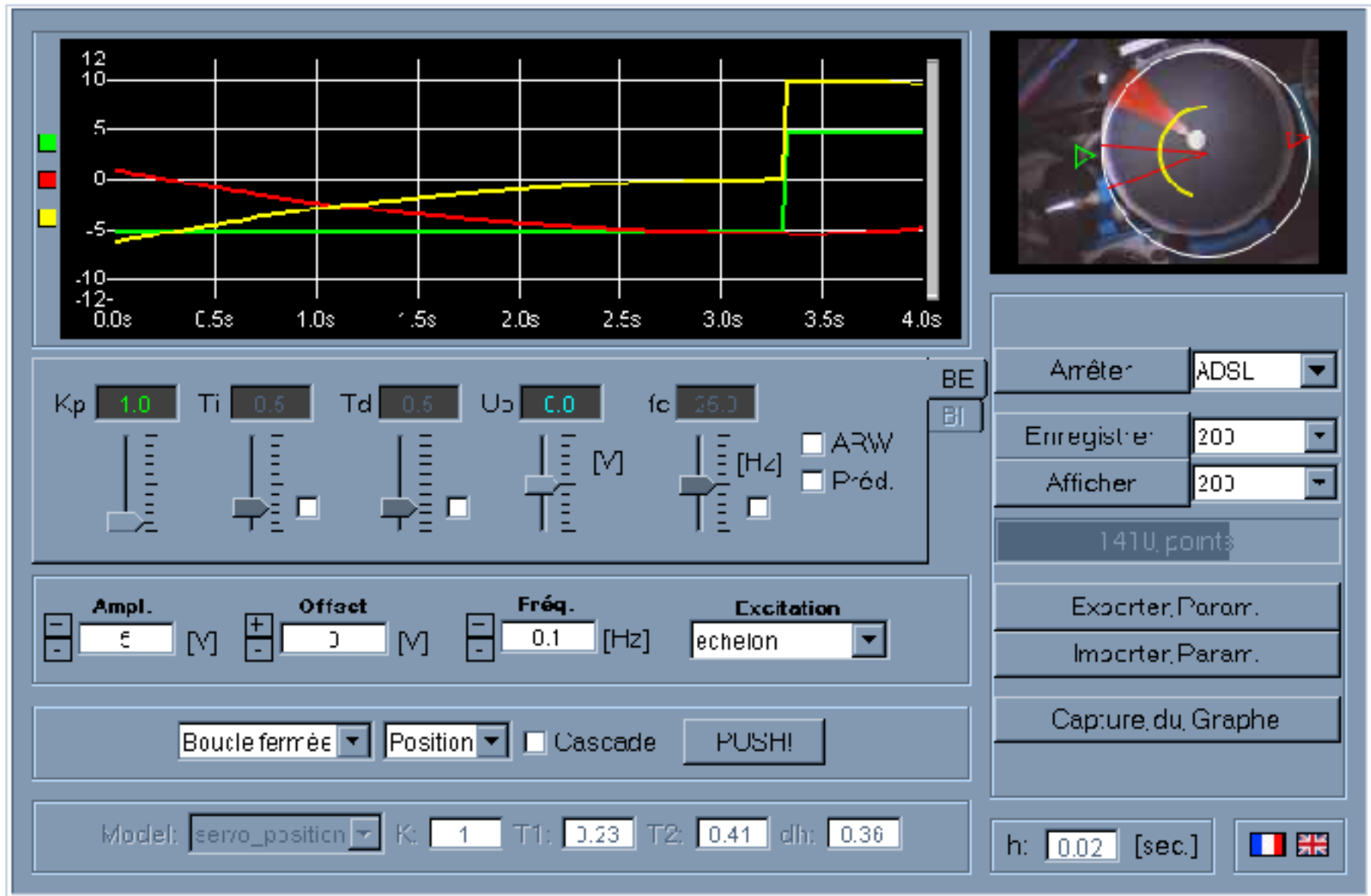


iPad Version

<https://itunes.apple.com/gb/app/number-rods/id536204074?mt=8>



# The real-virtual debate: offer both!



<http://emersion.epfl.ch/mechatronics/index.html>

For you project, look for reusable exploration/simulation/problem solving activities

# Summary:

1. People don't learn by being taught but by **adapting their knowledge structures** through interaction with artefacts. Educational philosophy: from telling students what to do to letting them **invent** things
2. In practice, this approach does not work very well without external **support** and requires talented teachers. Learning from simulation requires **inquiry skills**. Training these transversal skills are key goals of any education
3. Evolution of pedagogical methods from building mental schemes to building **concrete** objects. Digital artefacts offer rich interactions but digital education is not limited to virtual object. **Tangible** interfaces and augmented reality open it to physical manipulation.