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**Problem 1.**

- (a)  $\langle N(t), g(t) \rangle$  is a Gaussian random variable with zero mean and  $P \times \|g(t)\|^2$  variance.
- (b)  $\mathbf{z} * \mathbf{p}$  is a zero-mean Gaussian random variable of variance  $\|p\|^2$ .
- (c)  $\|\psi\|^2 = T_s \|\mathbf{psi}\|^2$ . To have unit norm,  $\mathbf{psi}$  has to be normalized by  $\frac{1}{\sqrt{T_s}}$
- (d) For simplicity we consider  $\text{length}(\text{normpsi}) = 2mn$  and not  $\text{length}(\text{normpsi}) = 2mn + 1$  (you also obtain full credit if you used  $2mn + 1$ ).  $\text{length}(\text{normpsi2}) = 4mn$ .

$$\text{length}(\mathbf{q}) = \text{length}(\text{normpsi2}) + \text{length}(\text{normpsi}) - 1 = 6mn - 1$$

The convolution has value 1 when at indices  $j = 2mn$  and  $j = 4mn$ . It has value 0 for indices  $j = 2mn + km$ , where  $k$  is an integer such that  $2mn < j < 4mn$ . We can not say anything if  $j < 2mn$  or  $j > 4mn$ , as the pulses do not overlap.

**Problem 2.** (c), (f), (d), (a), (g), (b), (e)

(c) is the only operation performed for all satellites

**Problem 3.** From the middle of the graph (equivalent to 0 Hz because of the use of `fftshift`) to the two spikes there are 400 samples. Therefore the two spikes are at frequencies  $f = 400 * F_s / NFFT = 600$  Hz and -600 Hz.

- (a)  $s(t) = Ae^{2\pi jft}$  — false
- (b)  $s(t) = A \cos(2\pi ft)$  — true,  $f = 600$  Hz
- (c)  $s(t) = A_1 \sin(2\pi f_1 t) + A_2 \sin(2\pi f_2 t)$ , with  $f_1 \neq f_2$  — false if the Nyquist condition is respected; there is one exception if  $f_1 = -f_2 = 600$  or  $f_1 = -f_2 = -600$  and  $A_1 \neq A_2$
- (d)  $s(t) = A_1 \sin(2\pi 100t) + A_2 \sin(2\pi 900t)$  — false
- (e)  $s(t) = A_1 e^{2\pi j f_1 t} + A_2 e^{2\pi j f_2 t}$ , with  $f_1 \neq f_2$  — true,  $f_1 = 600$ ,  $f_2 = -600$
- (f)  $s(t) = A \sin(2\pi ft)$  — true,  $f = 600$  Hz
- (g)  $s(t) = 100t + 900t$  — false
- (h)  $s(t) = A_1 \sin(2\pi 100t) + A_2 \sin(2\pi 900t)$  — false
- (i)  $s(t) = A_1 e^{2\pi f_1 t} + A_2 e^{2\pi f_2 t}$ , with  $f_1 \neq f_2$  — false

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#### Problem 4.

```
% Simulate binary uncoded PSK transmitted over the AWGN channel
% Specific instructions:
%
% Set NrBits to E5;
% Set Es_sigma2 to 3 dB
% Produces a binary random sequence of length NrBits taking values in {0,1}
% Map the bit sequence into a symbol sequence where 0 --> 1 and 1 --> -1
% Create the output of the AWGN channel that has the symbol sequence as input
% The energy per symbol over the noise variance shall be Es_sigma2 in dB
% Determine the bit sequence estimate (maximum likelihood decoding)
% Compute and print the error probability

clear all

NrBits=1E5; % number of transmitted bits
Es_sigma2=3; % Energy per symbol to noise variance in dB

bits=randi([0,1],NrBits,1); % random bits generation
symbols=1-2*bits; % symbols
receivedSymbols = awgn(symbols, Es_sigma2); % noisy received signal
bits_est_uncoded = receivedSymbols<0; % decoded bits
ber = sum(bits_est_uncoded ~= bits)/length(bits) % bit error probability
```

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### Problem 5.

```
% Load data.mat.
% Knowing that satellite 9 has Doppler frequency 1030 Hz,
% find the first sample that contains the start of the C/A code of satellite 9.

clear all;
close all;
clc;

%load GPS parameters
gpsConfig();
global gpssc;

sat_number=9;
doppler=1030;

%load the data (you do not need to use the getData instruction)
load data;

%determine the sample from which the first code starts
% get C/A code for this sat and upsample it to the sampling rate
p = kron(satCode(sat_number), ones(1, gpssc.spch));

% Read a chunk of data: we need twice the length of the C/A code, minus one sample
samples_per_code = length(p);
y = data(1:2*samples_per_code-1);

% generate the time axis
t = (0 : length(y)-1) * gpssc.Ts;

correction=exp(-2*pi*1j*t*doppler);
yc=y.*correction;

c=xcorr(yc,p);
c=c(length(yc):end);
[m,tau]=max(abs(c));
```