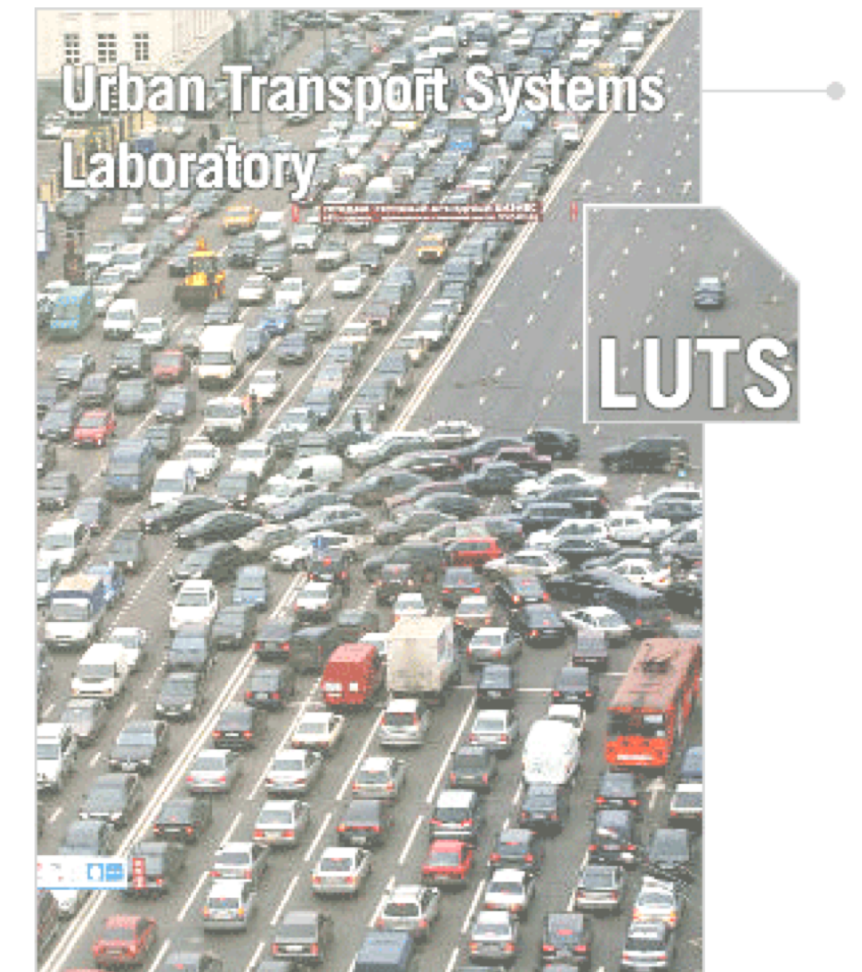


Traffic flow modeling

An intro to LWR Theory

Intro to traffic flow modeling and ITS

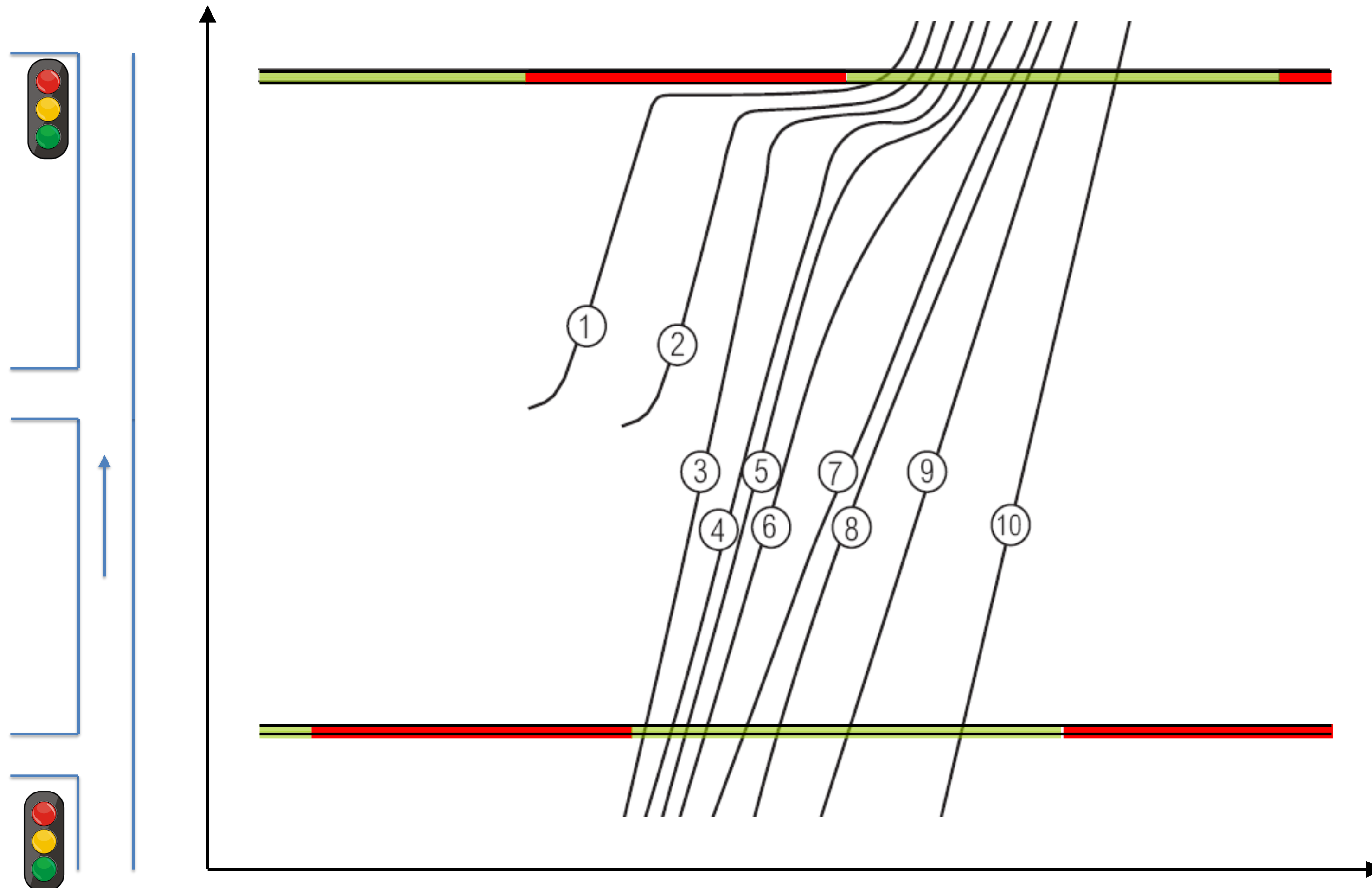
Prof. Nikolas Geroliminis



Welcome



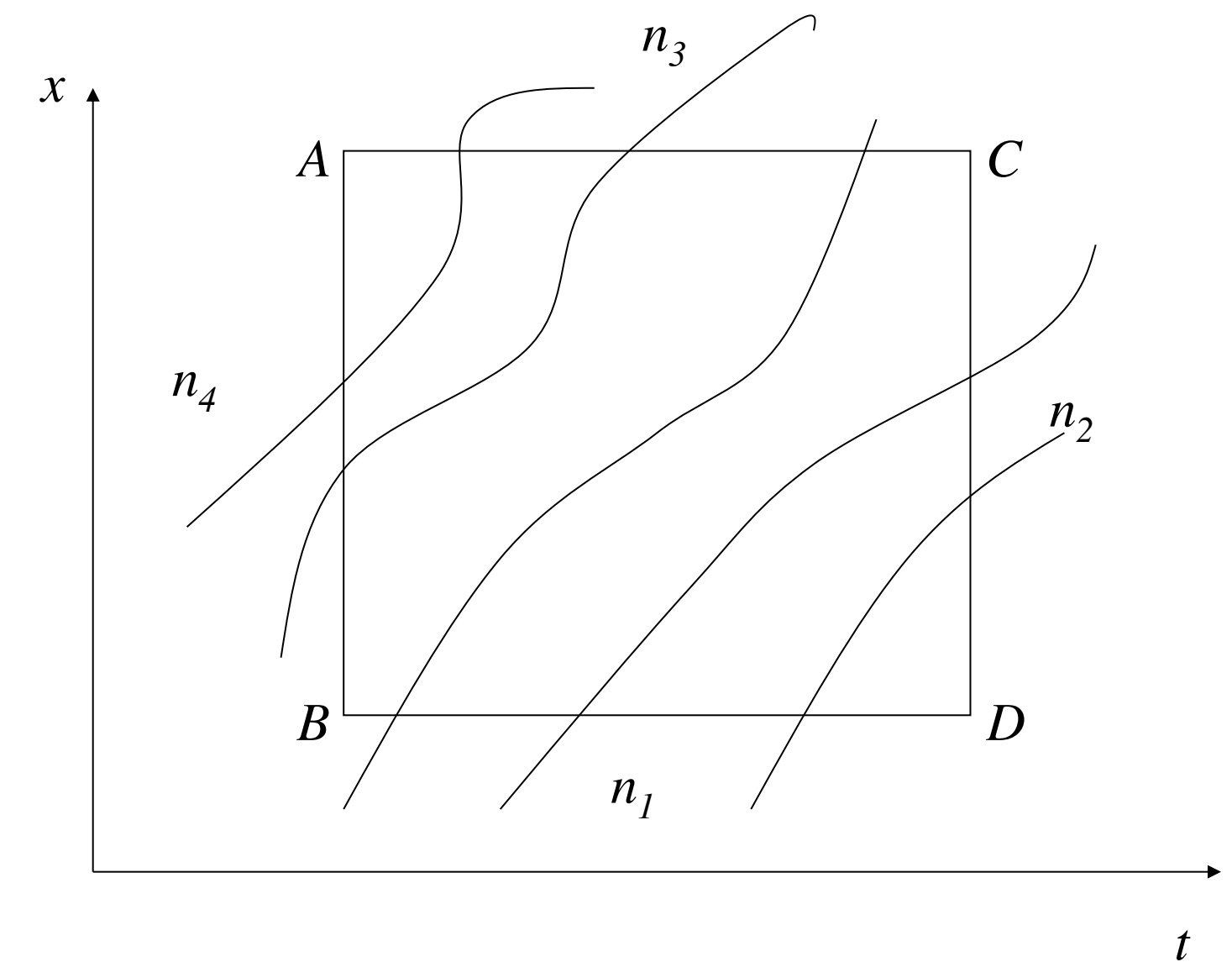
Trajectories of vehicles at a traffic light



Differential form of conservation law

$$\frac{\partial k(x, t)}{\partial t} + \frac{\partial q(x, t)}{\partial x} = 0$$

A simple proof



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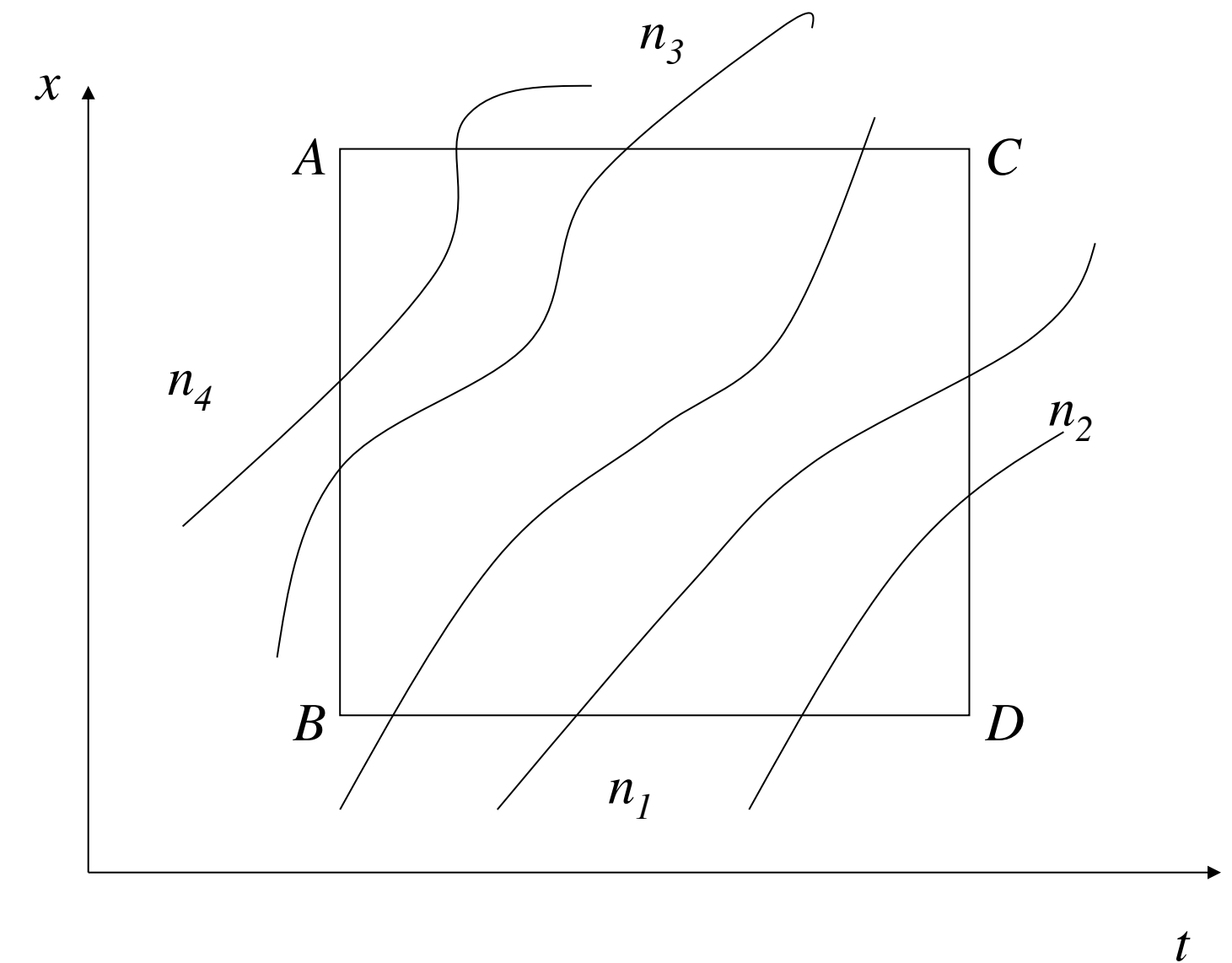
A simple proof

$$n_1 + n_4 = n_3 + n_2$$

$$q_{BD} * \Delta T + k_{AB} * \Delta L = q_{AC} * \Delta T + k_{CD} * \Delta L$$

$$0 = (q_{AC} - q_{BD}) * \Delta T + (k_{CD} - k_{AB}) * \Delta L$$

$$\frac{\Delta k}{\Delta T} + \frac{\Delta q}{\Delta L} = 0$$



Shockwaves and conservation law

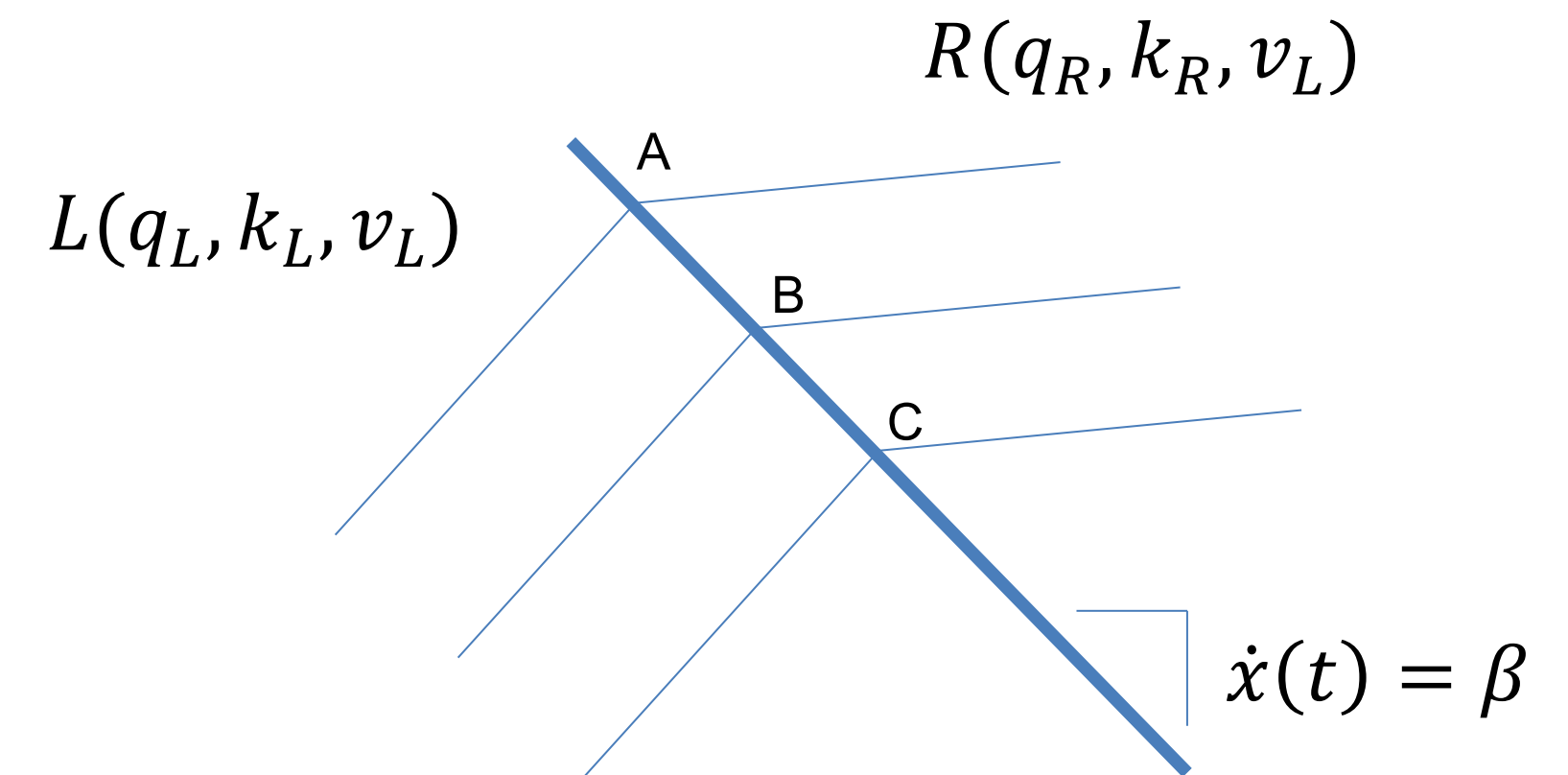
- A shock wave is a drastic change in traffic density that propagates through a traffic stream.

$$\frac{\partial k(x, t)}{\partial t} + \frac{\partial q(x, t)}{\partial x} = 0 \quad (1)$$

- Shocks only happen for increasing density profile $k_R > k_L$ (unique solution).

- Instantaneous speed adjustment (infinite acceleration)

- $\dot{x}(t) = \frac{q_R - q_L}{k_R - k_L}$ (Rankine-Hugoniot condition)



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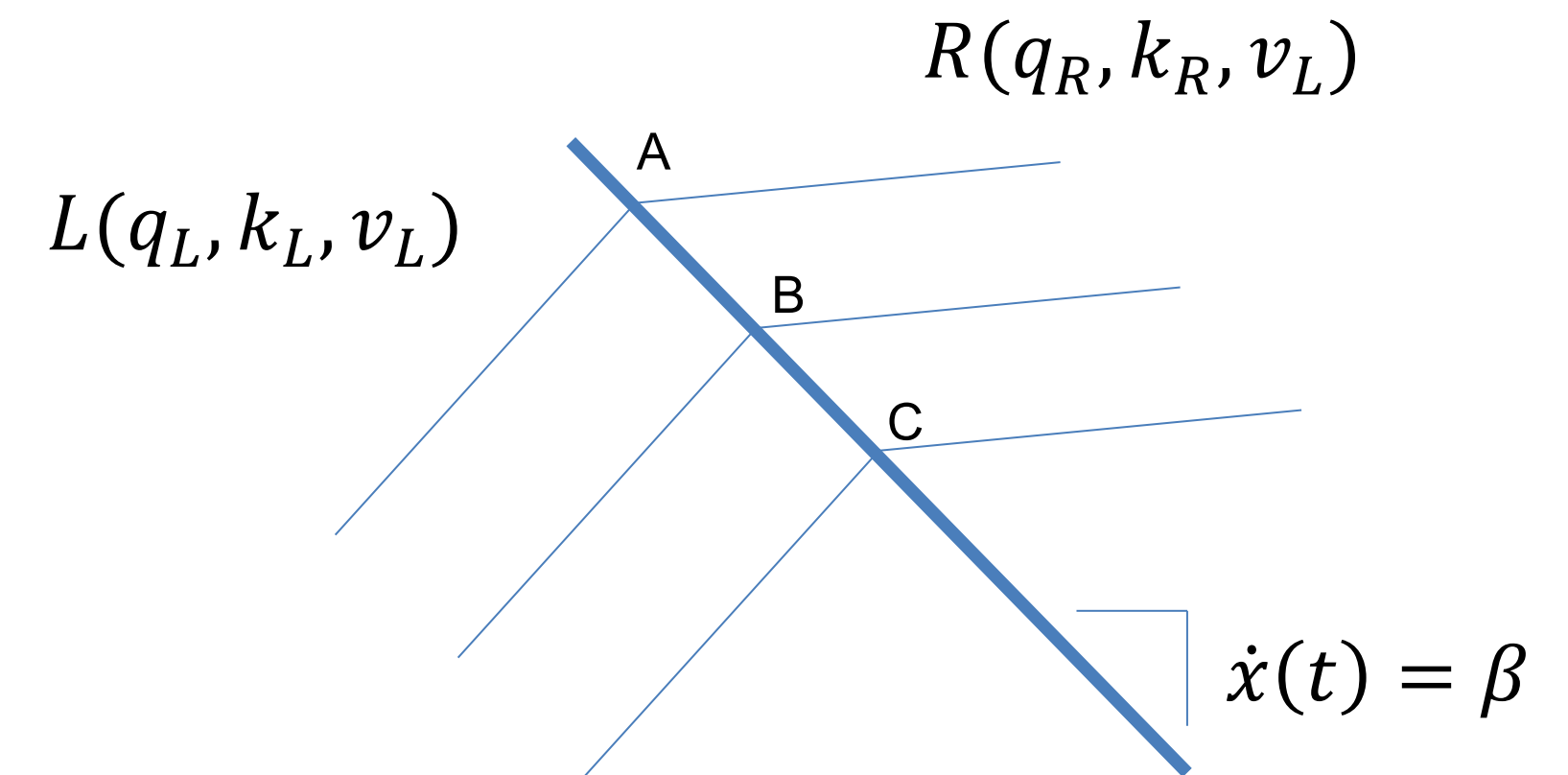
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A simple proof of R-H:

$$(\beta + v_L) * t = s_L$$

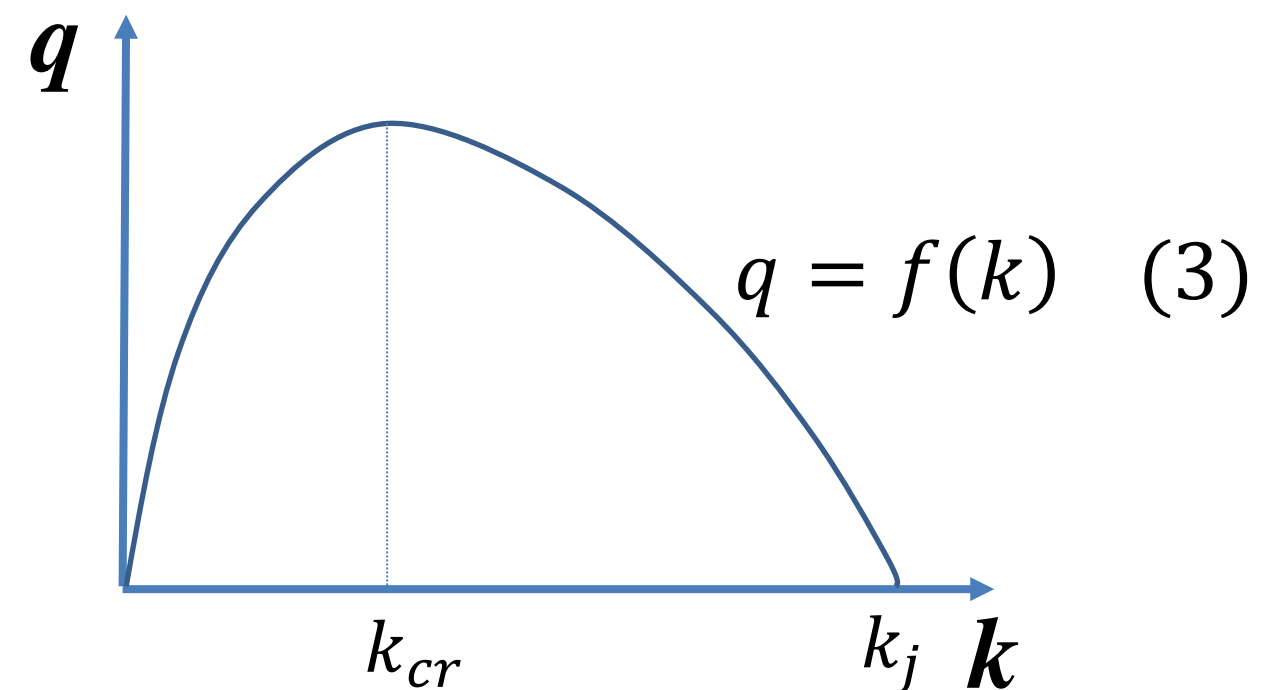
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Basics of LWR Theory

$$\frac{\partial k(x, t)}{\partial t} + \frac{\partial q(x, t)}{\partial x} = 0 \quad (1)$$

$$\dot{x}(t) = \frac{q_R - q_L}{k_R - k_L} \quad (2)$$



$$\frac{\partial k(x, t)}{\partial t} + f'(k) \frac{\partial k(x, t)}{\partial x} = 0 \quad (4)$$

$$k_t + c(k)k_x = 0 \quad (4')$$

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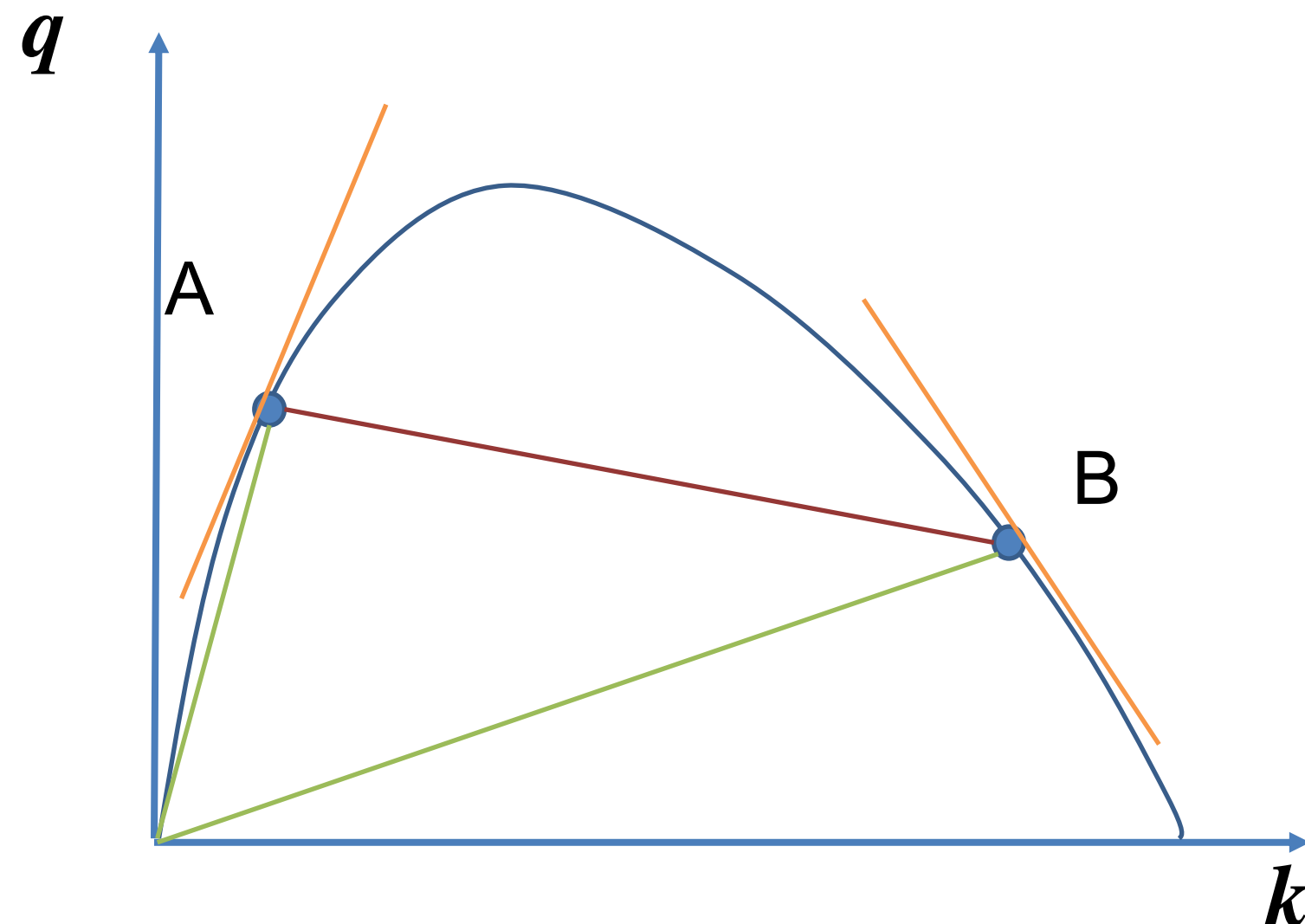
$$q = f(k) \quad (3)$$

$$\frac{\partial k(x, t)}{\partial t} + f'(k) \frac{\partial k(x, t)}{\partial x} = 0 \quad (4)$$

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Lemma: An observer that travels at speed $c(k)$ sees no change in density

Proof:
$$\frac{dk(x, t)}{dt} = k_t + k_x \frac{dx}{dt} = k_t + k_x c(k) = 0.$$



$c(k)$:characteristic speed

Basics of LWR Theory

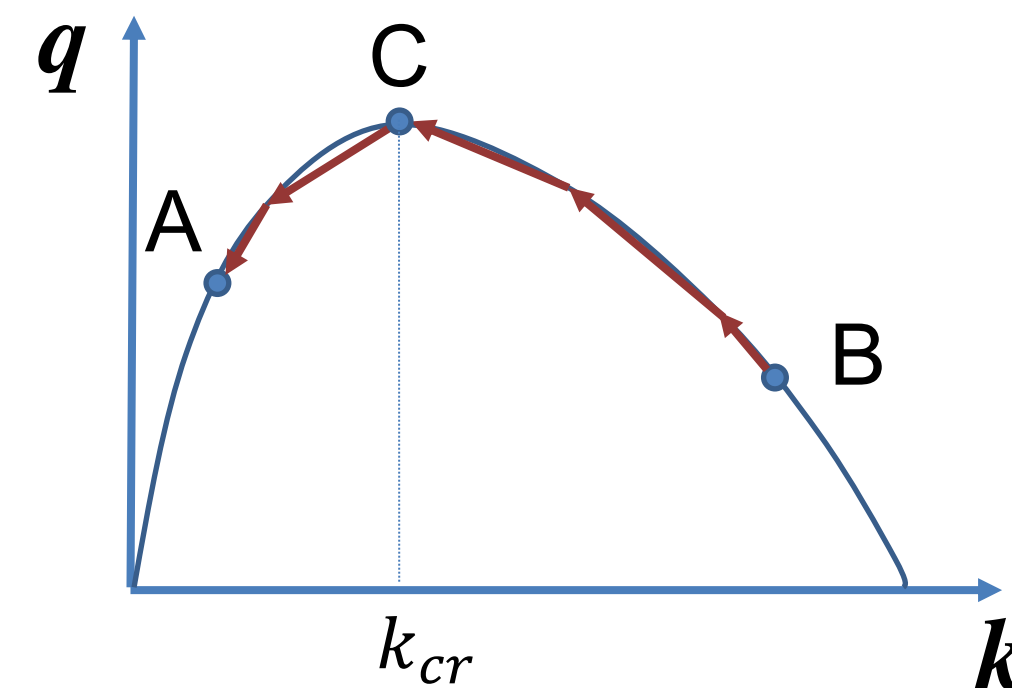
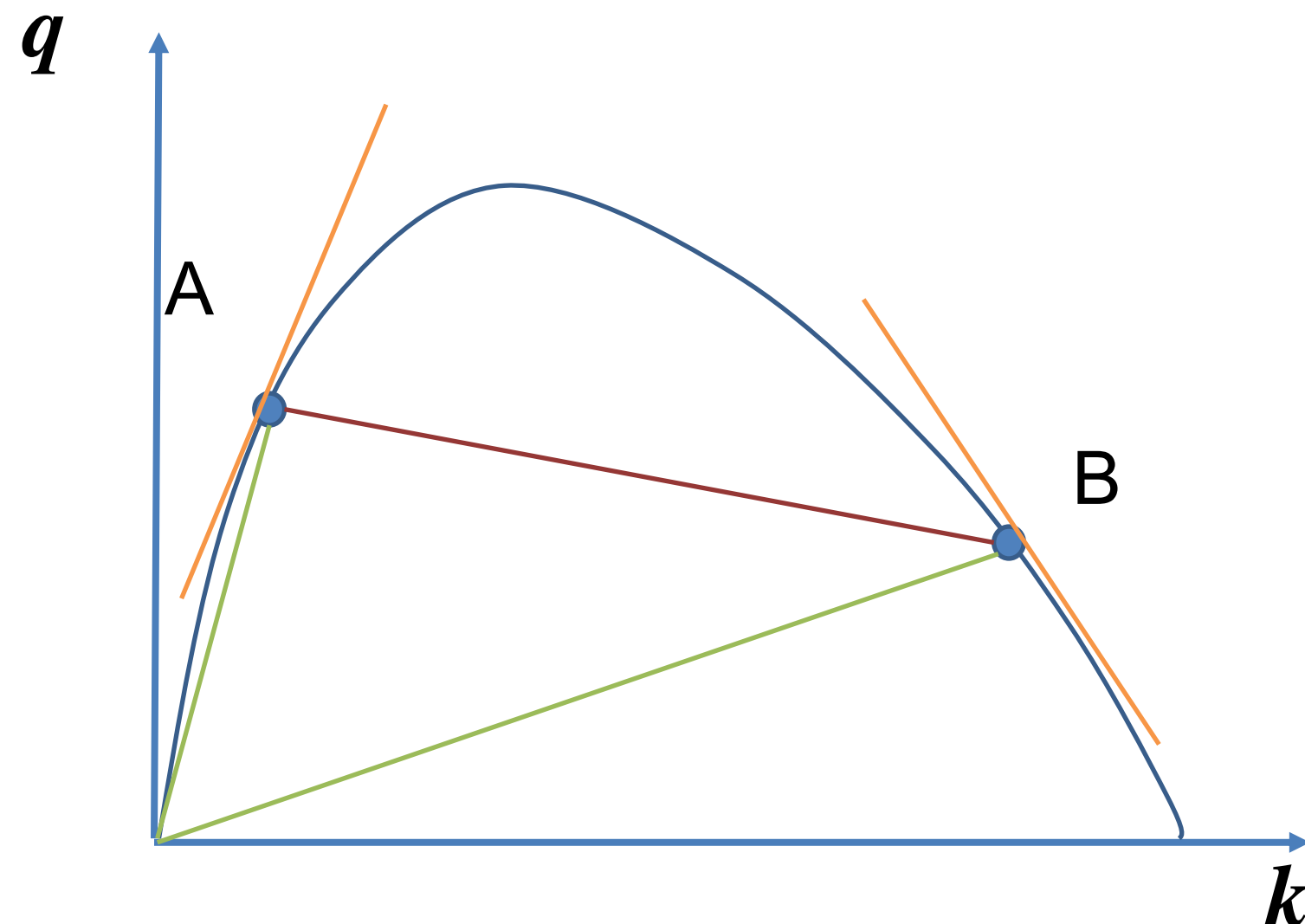
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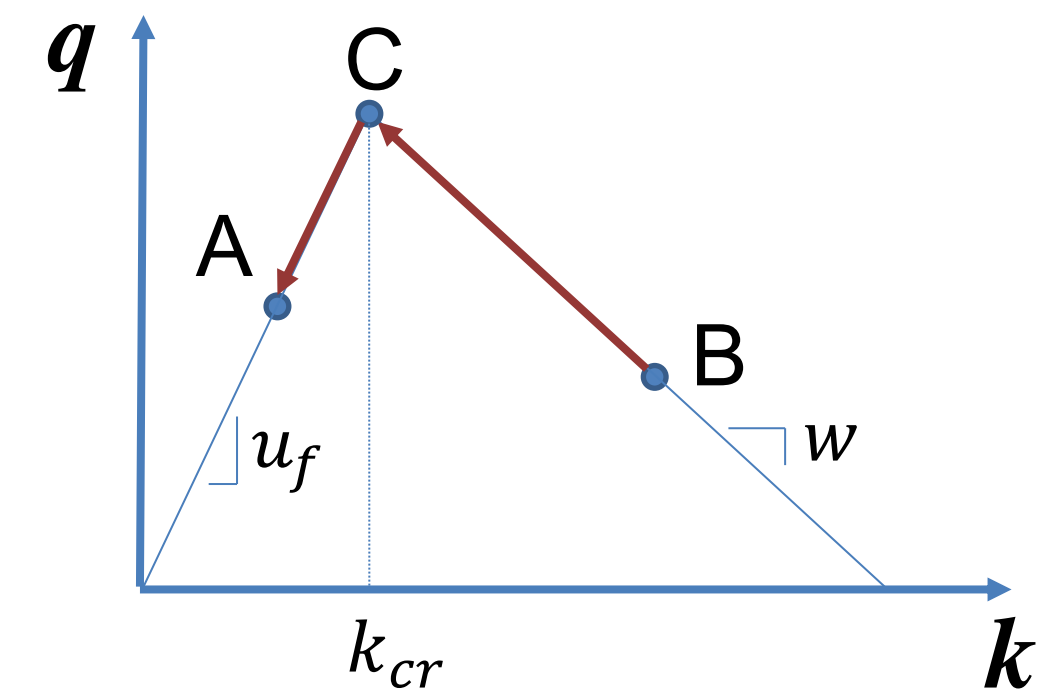
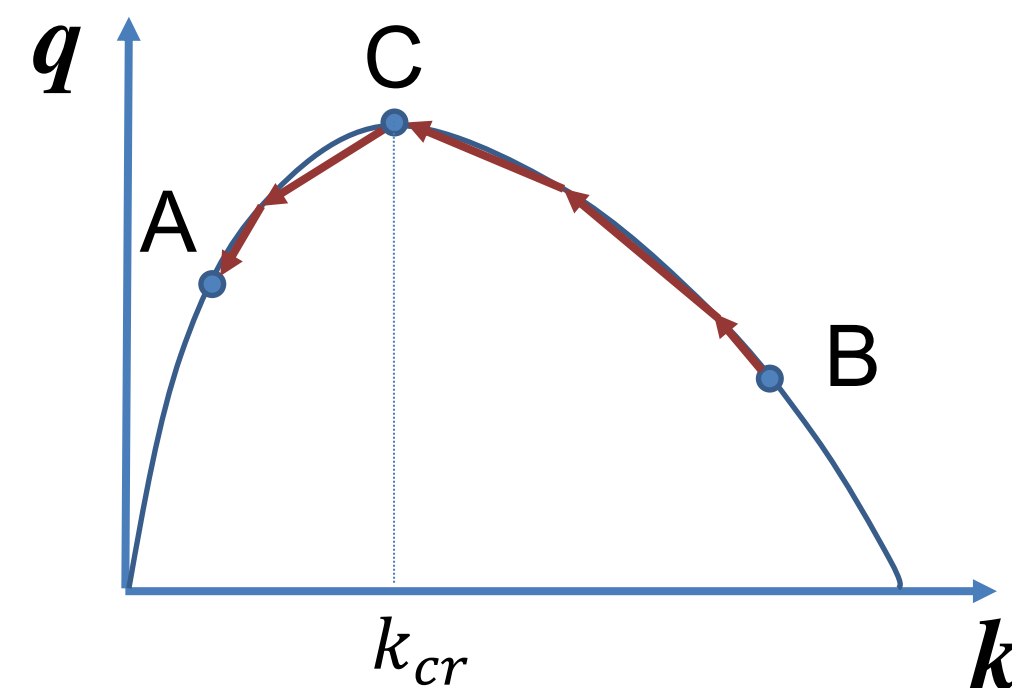
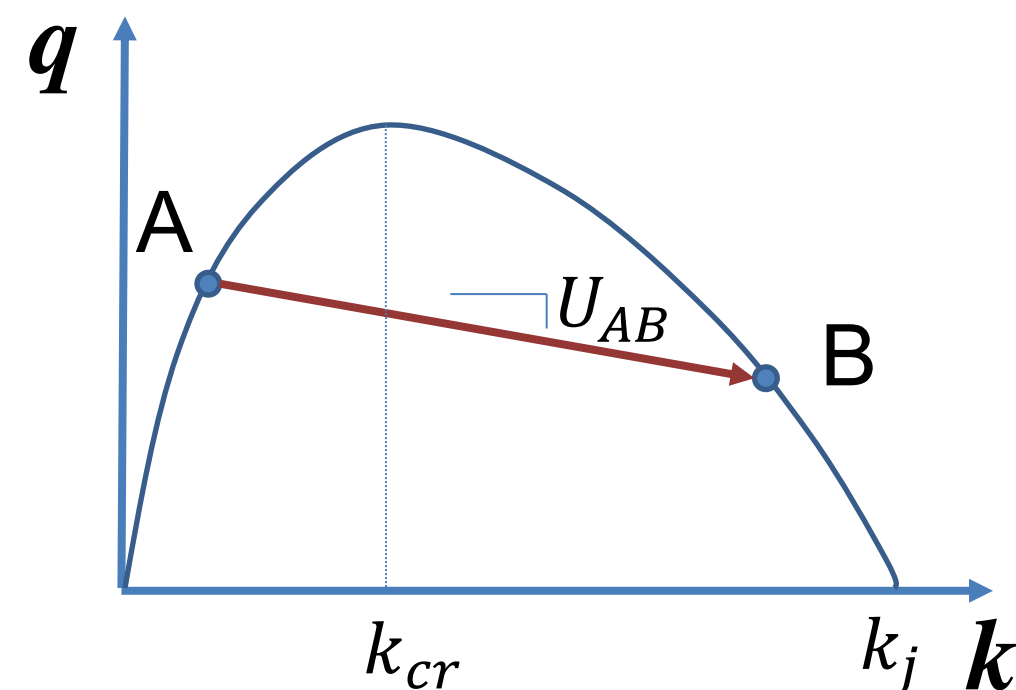
$$q = f(k) \quad (3)$$

Entropy condition: If there is a decreasing density profile, there are multiple solutions. Entropy condition helps to choose a single solution. Flow is maximized for a given density, meaning that a path following FD states is chosen.



Principles of LWR theory

- All possible states that can be observed in a road segment should belong in a FD (stationary conditions)
- When a traffic stream is moving from $A \rightarrow B$ with $k_A < k_B$ it follows a linear interface between A and B in the FD
- When a traffic stream is moving from $B \rightarrow A$ with $k_A < k_B$ follows a path **on the FD** (entropy conditions)
- If additionally $k_A < k_{cr} < k_B$ then the path passes through capacity state C (queues at active bottlenecks discharge at capacity)
- The speed of a shockwave between two states is $U_{AB} = \frac{q_B - q_A}{k_B - k_A}$
- If FD is triangular, then from $B \rightarrow A$, there are only characteristics with speeds u_f and/or w

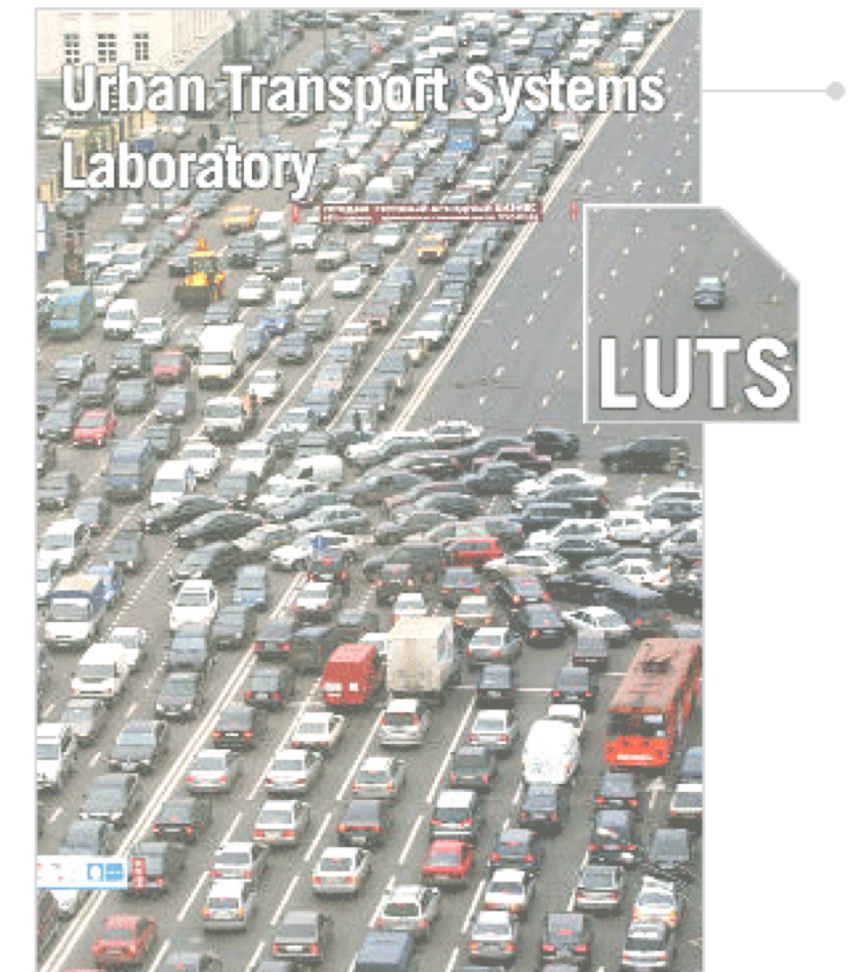


Traffic flow modeling

Examples of LWR Theory

Intro to traffic flow modeling and ITS

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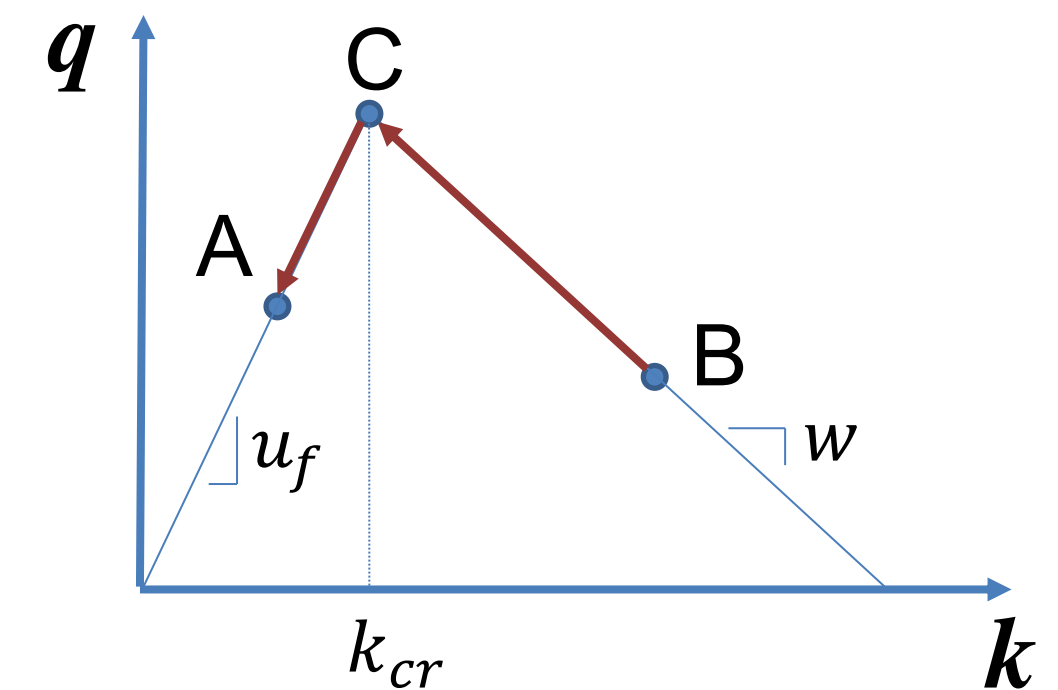
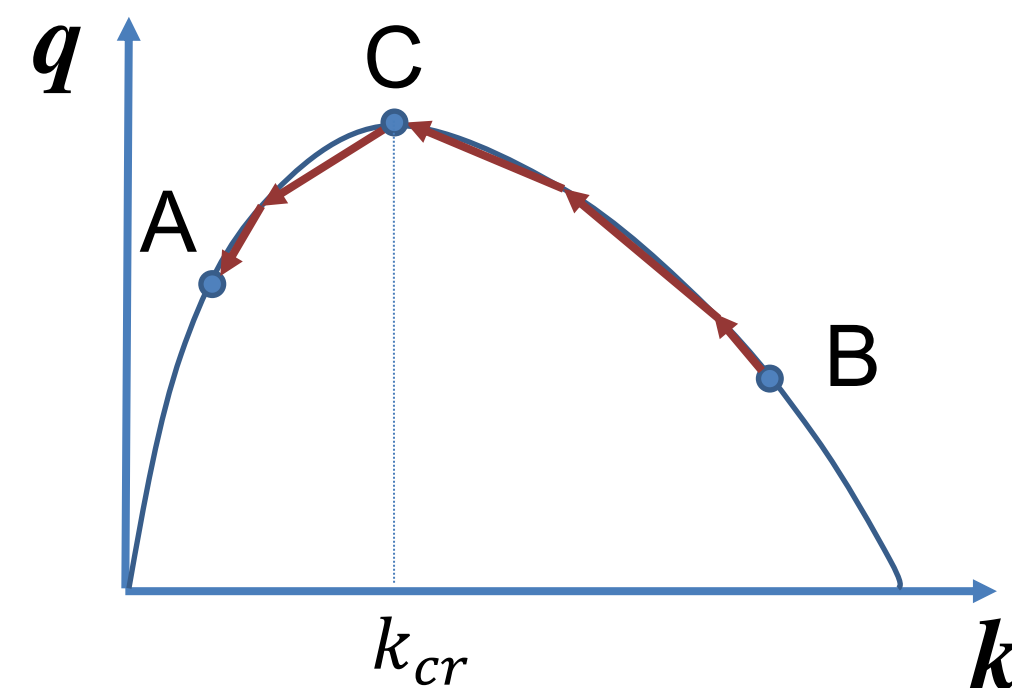
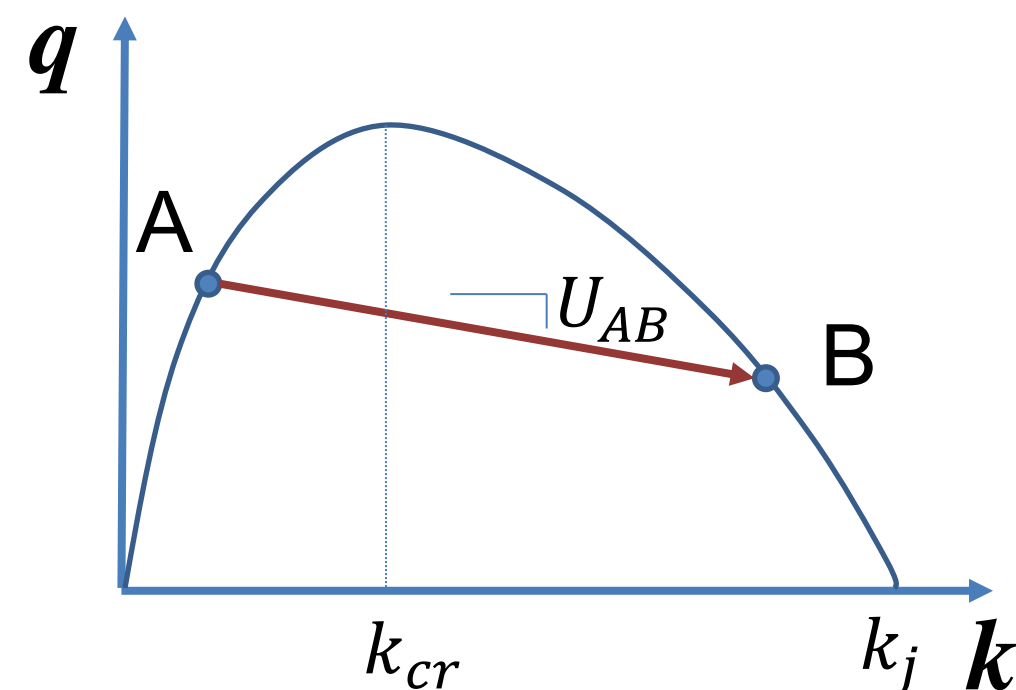


Welcome



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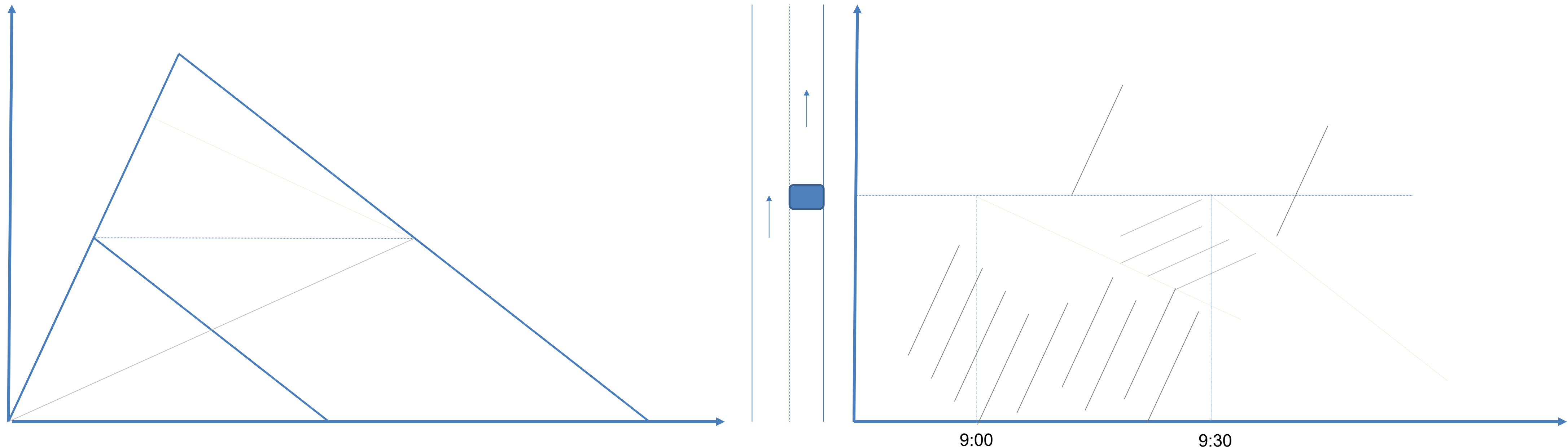


Example I: A freeway accident

Consider a two-lane freeway with a triangular FD with the characteristics below. Traffic is in the uncongested regime with flow $q=0.8c$. At 9am an accident happens that blocks one lane for 30min.

Estimate the maximum queue length.

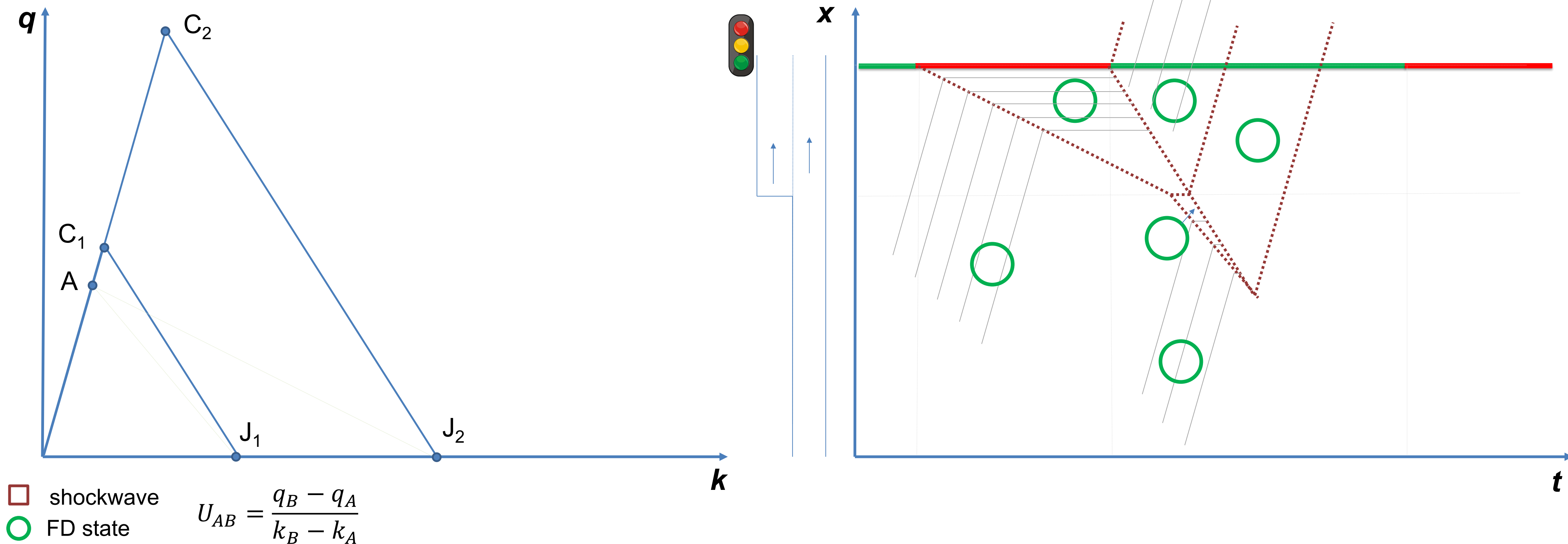
What is the clearance time of the accident?



Example II: A complicated traffic light

Consider an arterial road with a traffic light ($R=30\text{sec}$, $G=45\text{sec}$). The road is one-lane but at distance $L=150\text{m}$ upstream of the stop-line widens to two lanes. FDs are shown below. Vehicles approach the intersection from upstream at free-flow speed u_f and flow $q=0.85c$ (c is the road capacity of one lane).

1. What is the length of the queue?
2. What is the maximum number of cars that can be served over one cycle for a larger q by choosing a proper L^* ?



LWR Theory - Summary
