

An aerial photograph of Lausanne, Switzerland, showing the city's layout, the lake, and the surrounding mountains. The image is used as a background for the slide.

Machine Learning for Predictive Maintenance Applications: Federated learning / Explainable ML algorithms

Prof. Dr. Olga Fink

Which questions to follow to select an ML model

1. What is the nature of the problem?

- Is it a classification, regression, clustering, or recommendation problem?
- Are you dealing with supervised, unsupervised, or reinforcement learning?

2. What is the size and quality of the dataset?

- How many samples and features are available?
- Is the data clean, or does it contain a lot of noise and missing values?
- Is the data balanced, or are there significant class imbalances?

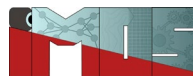
3. Is the training dataset representative of the expected operating / application conditions

- Is there a high diversity of operating conditions expected?

4. What are the characteristics of the data?

- Is the data structured or unstructured (e.g., text, images, audio)?
- Are the features numerical, categorical, or a mix of both?
- Do the features have a temporal or spatial component?

Which questions to follow to select an ML model



5. What are the performance requirements?

- Do you prioritize accuracy, interpretability, or computational efficiency?
- Is the problem domain one where explainability is crucial (e.g., healthcare, finance)?
- What are the acceptable trade-offs between bias and variance?

6. What is the computational complexity and resources available?

- How much time and computational power do you have for training?
- Do you have access to specialized hardware (e.g., GPUs)?

7. What are the specific goals and constraints?

- What is the end goal of applying the ML model (e.g., prediction, anomaly detection, optimization)?
- Are there specific business or application constraints to consider (e.g., real-time processing, deployment environment)?

8. What is the level of domain knowledge available?

- How well do you understand the domain and the problem?
- Is there domain expertise to help with feature engineering and model interpretation?

Which questions to follow to select an ML model

9. What is the expected model lifecycle?

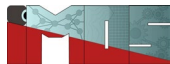
- How often will the model need to be updated or retrained?
- Is the model expected to handle concept drift (changes in the underlying data distribution over time)?

10. What is the potential for model interpretability?

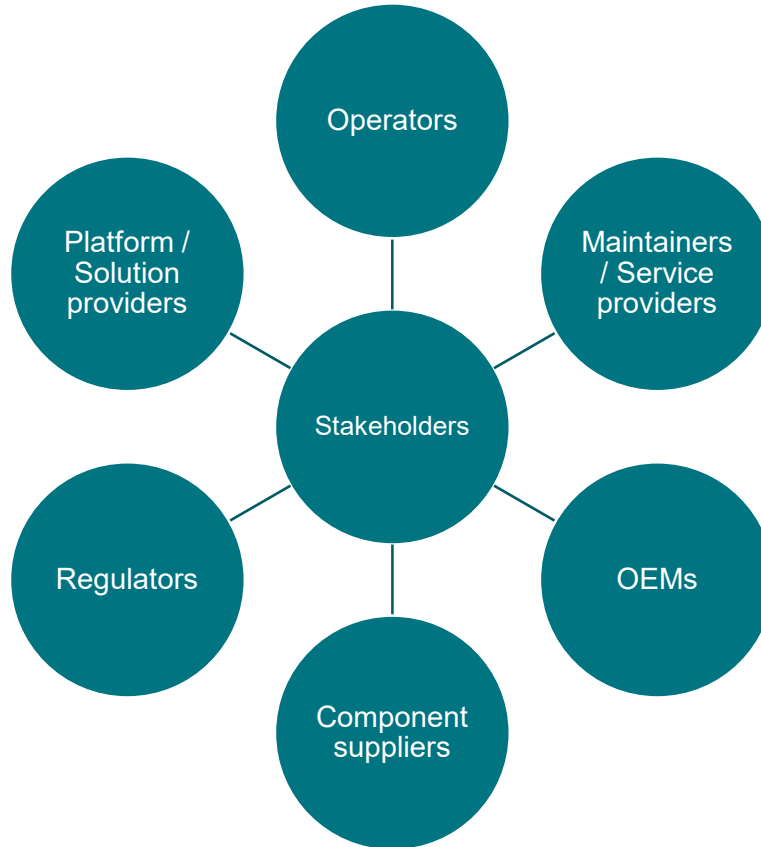
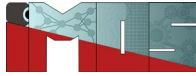
- Do stakeholders need to understand how the model makes decisions?
- Is there a regulatory requirement for transparency?

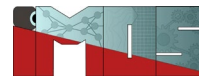
11. What are the available benchmarks or baselines?

- Are there existing solutions or benchmarks that can provide a performance reference?
- How do different algorithms perform on similar problems in literature or industry standards?



Data sharing/ Federated learning



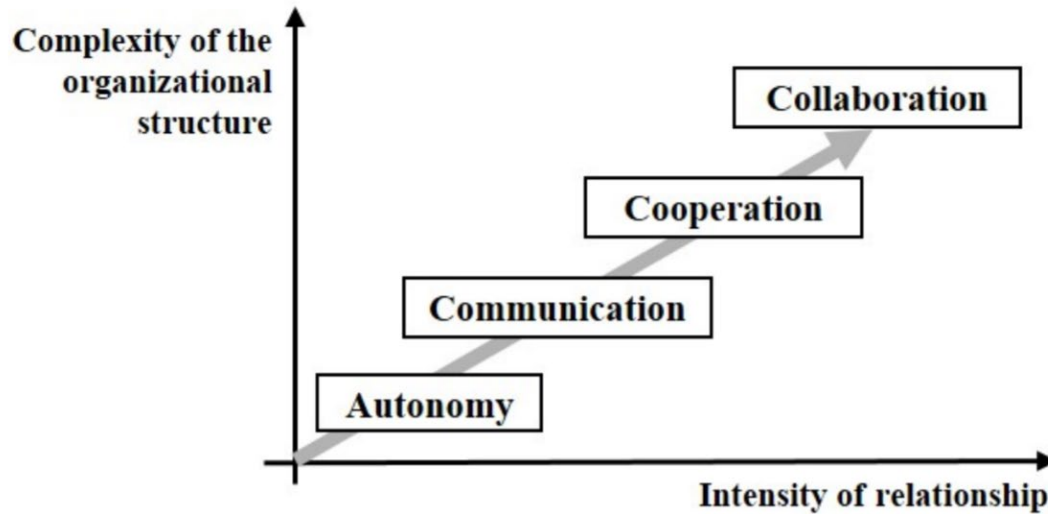
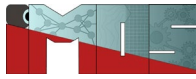


“The biggest obstacle to using advanced data analysis isn't skill base or technology; it's plain old access to the data.”

-Edd Wilder-James, Harvard Business Review

Source: Min Du, 2019

New forms of sharing and collaboration required



Source: Chebel-Morello, Nicod, Varnier, 2017

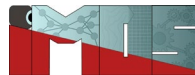
Data sharing

**How could data be shared
across stakeholders?**

Data sharing

Share the model instead of data across multiple stakeholders (also when the conditions are not the same)

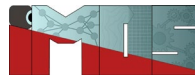
A new paradigm – Federated Learning



a synchronous update scheme that proceeds in rounds of communication

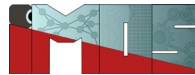
McMahan, H. Brendan, Eider Moore, Daniel Ramage, and Seth Hampson. "Communication-efficient learning of deep networks from decentralized data." *AISTATS*, 2017.

Source: Min Du, 2019



- **Federated learning** is a machine learning setting where multiple entities (clients) collaborate in solving a machine learning problem, under the coordination of a central server or service provider. Each client's raw data is stored locally and not exchanged or transferred; instead, focused updates intended for immediate aggregation are used to achieve the learning objective.

Source: *Advances and Open Problems in Federated Learning*
<https://arxiv.org/pdf/1912.04977.pdf>



1. Data Privacy and Security

- **Data Locality:** Raw data remains on local devices (e.g., smartphones, edge devices, or distributed servers) instead of being sent to a central server, enhancing privacy and security.
- **Secure Aggregation:** Only model updates (e.g., gradients) are sent to a central server, and these updates can be further encrypted or anonymized, reducing the risk of exposing sensitive information.
- **Privacy-Preserving Techniques:** Techniques like differential privacy or homomorphic encryption are often integrated to ensure that individual data points cannot be inferred from the shared updates.

2. Decentralized Training

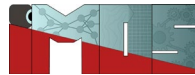
- **Local Training:** Each device trains a model locally on its own data, which means training occurs independently across a distributed network.
- **Global Model Aggregation:** After local training, model parameters are sent to a central server that aggregates these updates to form a new global model, which is then sent back to each local device to continue training.

3. Handling Data Heterogeneity

- **Non-IID Data:** In federated learning, data on different devices is often non-independent and identically distributed (non-IID), meaning data distributions may vary significantly between devices.
- **Variable Data Quality and Quantity:** Some devices may have abundant data, while others have minimal or noisy data, requiring federated learning algorithms to account for varying data quality and volume.

4. Communication Efficiency

- **Minimizing Data Transfer:** To limit network usage, federated learning focuses on minimizing the frequency and size of data transferred between the server and devices.
- **Compression Techniques:** Methods like quantization, sparsification, and pruning are used to reduce the size of model updates, which is essential for devices with limited bandwidth.



5. Device Heterogeneity and Scalability

- **Diverse Device Capabilities:** Federated learning systems are designed to work across a wide variety of devices, from smartphones to IoT devices, each with different computational capabilities, network stability, and battery life.
- **Scalability:** Federated learning is scalable, as it can handle thousands or even millions of devices simultaneously, with participants joining or leaving the training process dynamically.

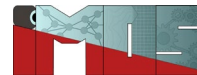
6. Model Personalization

- **Personalized Models:** Federated learning allows each device to maintain its own personalized version of the model, especially if local data significantly deviates from the global model's training data. This feature can improve the model's performance on individual devices.

7. Fault Tolerance

- **Robust to Device Failures:** Federated learning systems can continue training even if some devices drop out or are temporarily unavailable, making them resilient to intermittent connectivity and device churn.

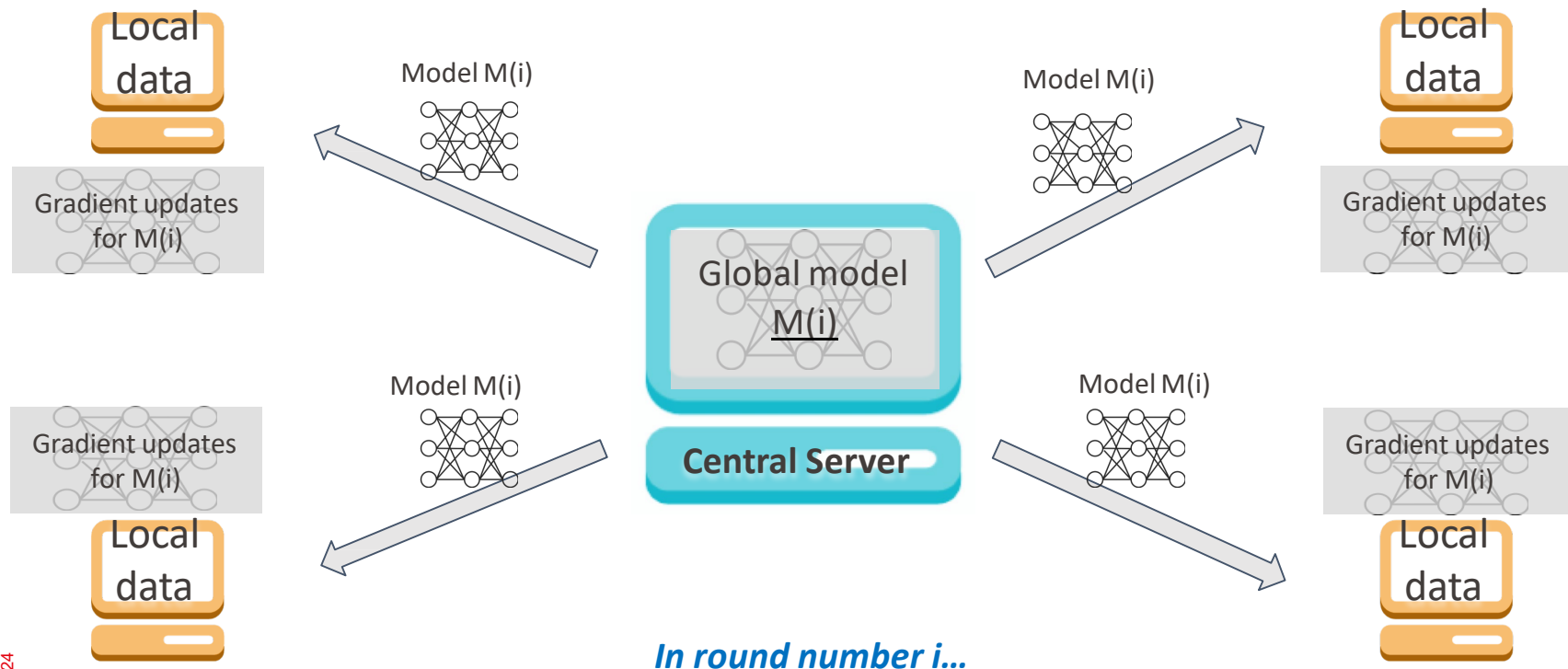
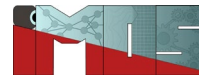
Federated Learning vs. Peer-to-peer learning



	Federated learning	Fully decentralized (peer-to-peer) learning
Orchestration	A central orchestration server or service organizes the training, but never sees raw data.	No centralized orchestration.
Wide-area communication	Typically a hub-and-spoke topology, with the hub representing a coordinating service provider (typically without data) and the spokes connecting to clients.	Peer-to-peer topology, with a possibly dynamic connectivity graph.

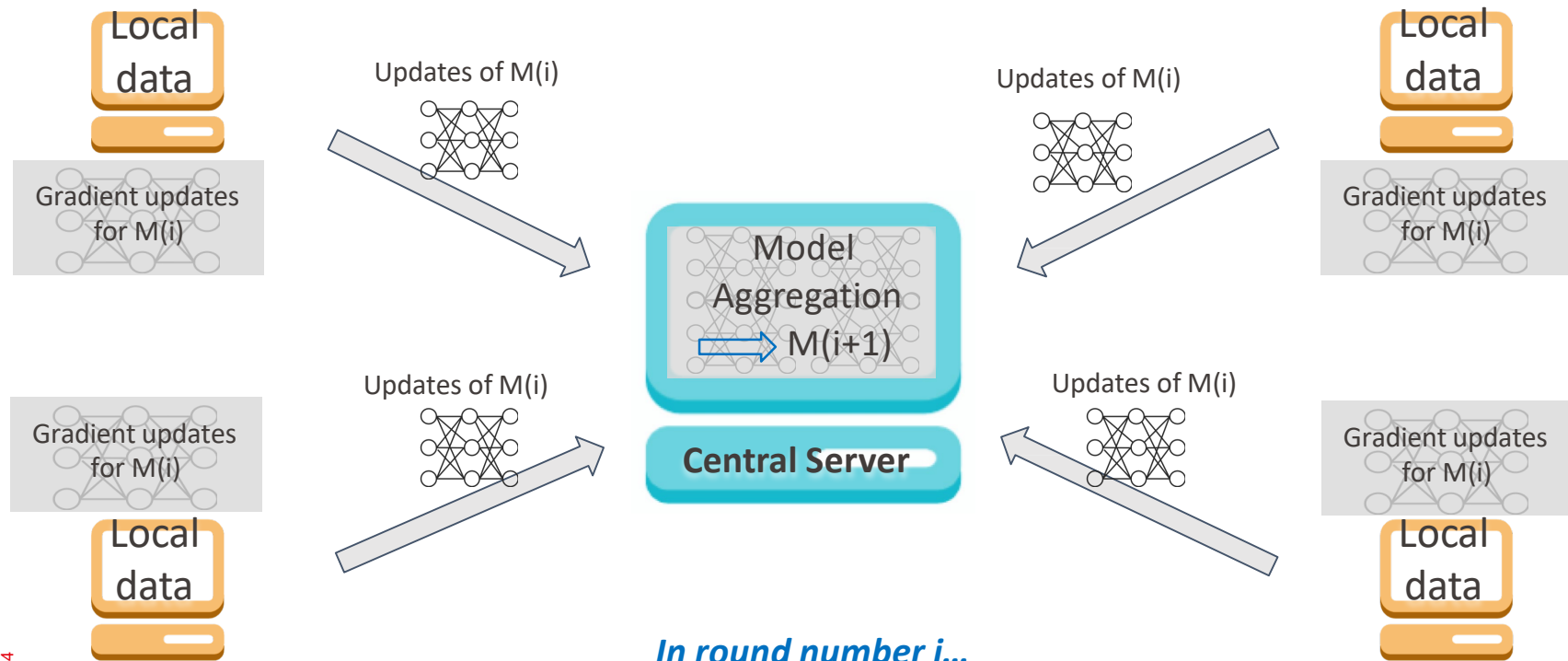
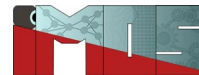
Source: *Advances and Open Problems in Federated Learning*
<https://arxiv.org/pdf/1912.04977.pdf>

Federated learning – overview



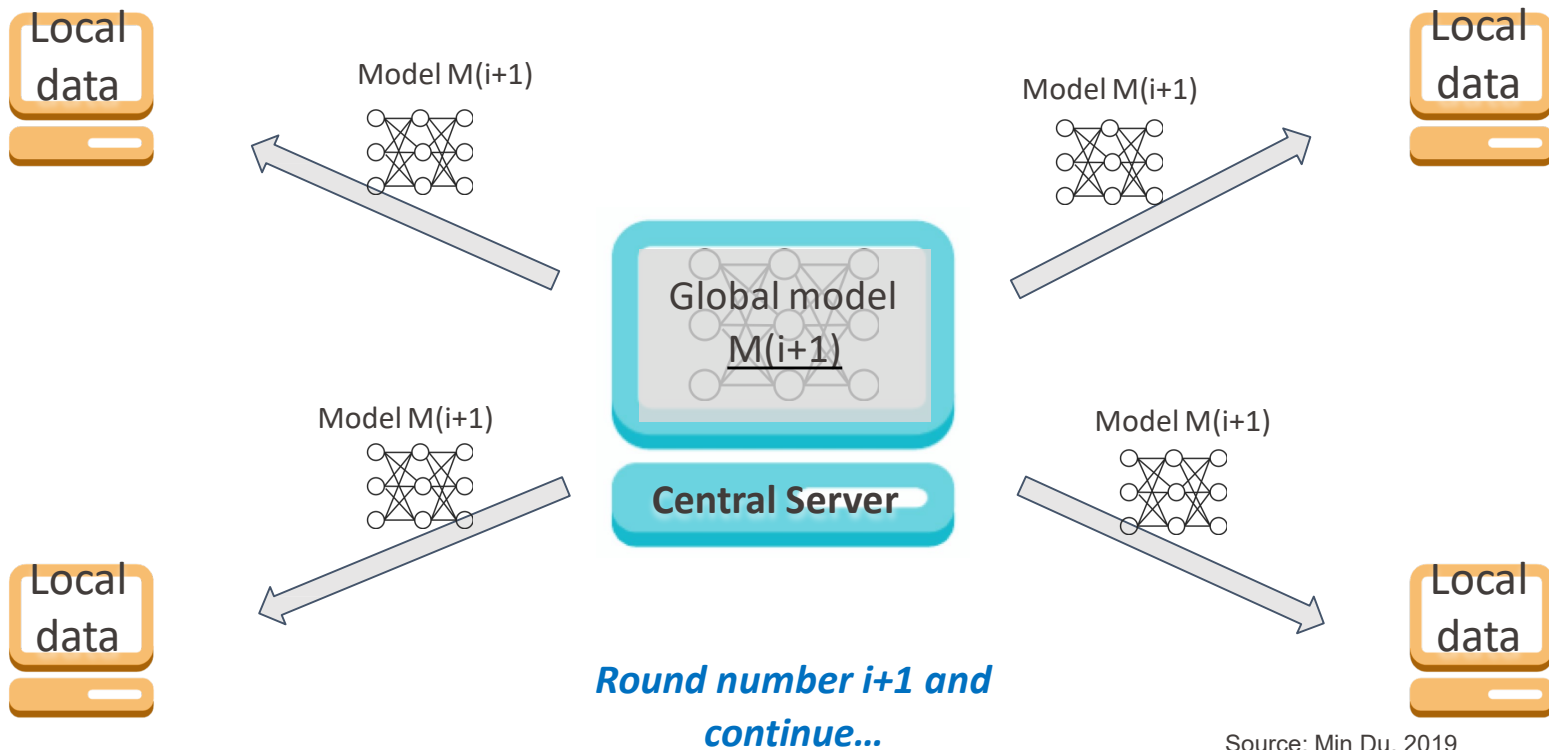
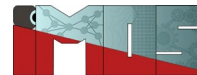
Source: Min Du, 2019

Federated learning – overview

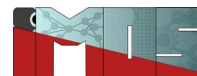


Source: Min Du, 2019

Federated learning – overview



Source: Min Du, 2019



- Recall in traditional deep learning model training
 - For a training dataset containing n samples (x_i, y_i) , $1 \leq i \leq n$, the training objective is:

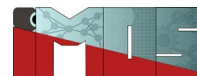
$$\min_{w \in \mathbb{R}^d} f(w) \quad \text{where} \quad f(w) \stackrel{\text{def}}{=} \frac{1}{n} \sum_{i=1}^n f_i(w)$$

$f(w) = l(x_i, y_i, w)$ is the loss of the prediction on example (x_i, y_i)

- Deep learning optimization relies on SGD and its variants, through mini-batches

$$w_{t+1} \leftarrow w_t - \eta \nabla f(w_t; x_k, y_k)$$

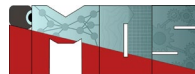
Source: Min Du, 2019



- In federated learning
 - Suppose n training samples are distributed to K clients, where P_k is the set of indices of data points on client k , and $n_k = |P_k|$
 - For training objective: $\min_{w \in \mathbb{R}^d} f(w)$

$$f(w) = \sum_{k=1}^K \frac{n_k}{n} F_k(w) \quad \text{where} \quad F_k(w) \stackrel{\text{def}}{=} \frac{1}{n_k} \sum_{i \in P_k} f_i(w)$$

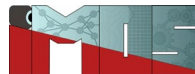
Source: Min Du, 2019



- A randomly selected client that has n_k training data samples in federated learning $\approx$ *A randomly selected sample in traditional deep learning*
- Federated SGD (FedSGD): a single step of gradient descent is done per round
- Recall in federated learning, a C -fraction of clients are selected at each round.
 - $C=1$: full-batch (non-stochastic) gradient descent
 - $C<1$: stochastic gradient descent (SGD)

Source: Min Du, 2019

FederatedSGD (FedSGD) / FederatedAveraging (FedAvg)



Learning rate: η ; total #samples: n ; total #clients: K ; #samples on a client k : n_k ;
clients fraction $C = 1$

- In a round t :
 - The central server broadcasts current model w_t to each client; each client k computes gradient: $g_k = \nabla F_k(w_t)$, on its local data.
 - Approach 1: Each client k submits g_k ; the central server aggregates the gradients to generate a new model:

$$w_{t+1} \leftarrow w_t - \eta \nabla f(w_t) = w_t - \eta \sum_{k=1}^K \frac{n_k}{n} g_k.$$

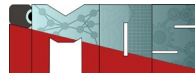
$$\text{Recall } f(w) = \sum_{k=1}^K \frac{n_k}{n} F_k(w)$$

- Approach 2: Each client k computes: $w_{t+1}^k \leftarrow w_t - \eta g_k$; the central server performs aggregation:

$$w_{t+1} \leftarrow \sum_{k=1}^K \frac{n_k}{n} w_{t+1}^k$$

For multiple times $\Rightarrow$ FederatedAveraging (FedAvg)

Source: Min Du, 2019

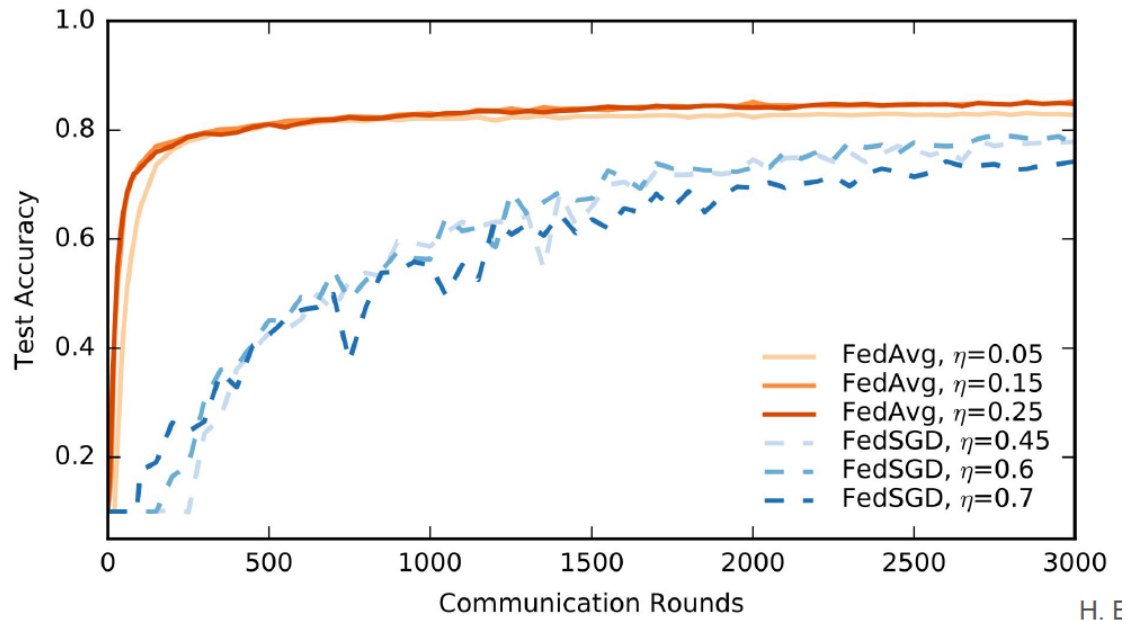
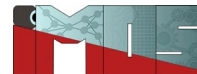


1. FederatedSGD (FedSGD)

- **Process:** In FedSGD, each device performs a single step of stochastic gradient descent (SGD) on its local data and then sends the computed gradients (i.e., updates) to the central server. The server then aggregates these gradients from all devices and applies them to the global model.
- **Communication:** FedSGD involves frequent communication between the devices and the server, as each gradient update requires synchronization with the server.
- **Advantages:** FedSGD ensures that each update to the global model reflects the most recent local gradient information from each device. This can sometimes lead to faster convergence if the communication overhead is manageable.
- **Drawbacks:** The high frequency of communication in FedSGD is a major drawback, especially in federated learning scenarios where devices might have limited bandwidth. Frequent communication also consumes more energy on devices, which is a concern for battery-powered devices like mobile phones.

2. FederatedAveraging (FedAvg)

- **Process:** In FedAvg, each device performs multiple local updates (i.e., several steps of SGD) on its local data before sending the updated model parameters to the central server. The server then averages the model parameters from all participating devices to update the global model.
- **Communication:** By performing multiple local updates before communicating, FedAvg significantly reduces the frequency of communication between devices and the server.
- **Advantages:** FedAvg is much more communication-efficient than FedSGD since each device communicates with the server only after several local updates. This makes it more suitable for federated learning, where communication costs are high. Additionally, local updates often lead to faster convergence in practical applications, as they allow each device to adapt the model more effectively to its own data before syncing.
- **Drawbacks:** FedAvg might converge more slowly or be less stable in scenarios where data on each device is highly heterogeneous (non-IID). In such cases, performing multiple local updates can lead to models that diverge from each other, making aggregation less effective.



Updates to reach 82%

SGD 31,000

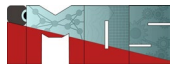
FedSGD 6,600

FedAvg 630

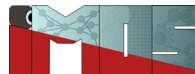
49x decrease in
communication
(updates) vs SGD

(IID and balanced data)

McMahan, H. Brendan, Eider Moore, Daniel Ramage, and Seth Hampson. "Communication-efficient learning of deep networks from decentralized data." *AISTATS*, 2017.

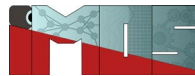


Example



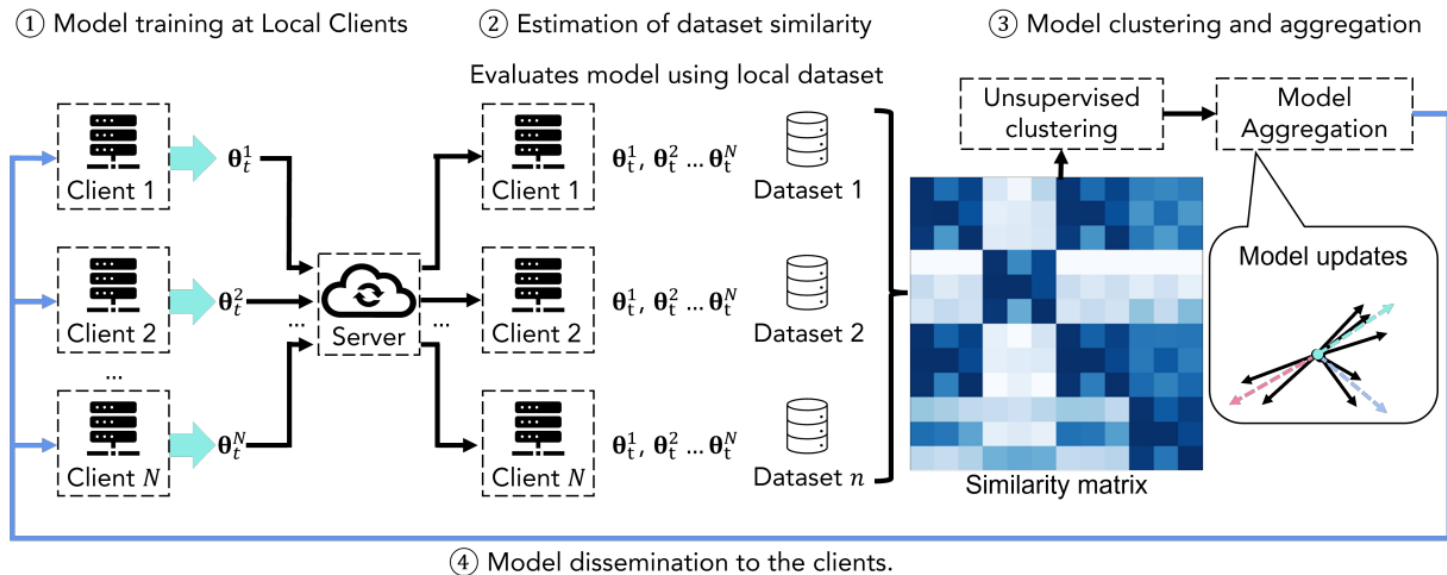
- **Data heterogeneity in industrial settings:**
 1. *Domain shift:* Clients do not share a similar data distribution.
 2. *Label heterogeneity:* Clients' datasets have a different number and types of faults.

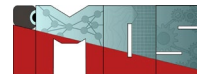
Federated learning adapted to the specificities of the unit



- Distance awareness: the model's ability to quantify the distance of a testing example from the training data.
- For personalized federated learning, during model aggregation → a local client would assign higher weights to the model that was trained using similar training data.
- Spectral-normalized Neural Gaussian Process (SNGP) used to quantify the prediction uncertainty

Federated Learning with Uncertainty-Based Client Clustering for Fleet-Wide Fault Diagnosis

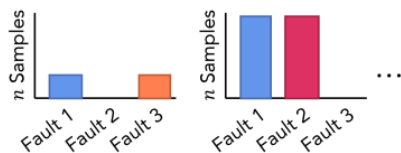




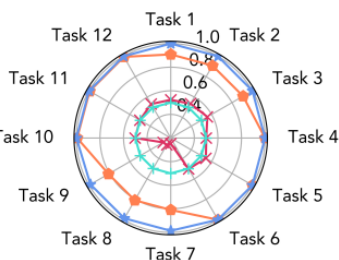
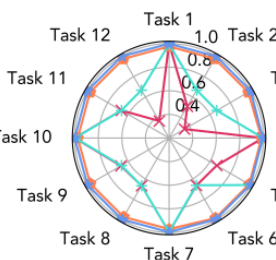
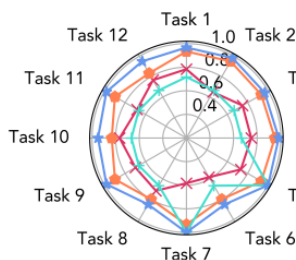
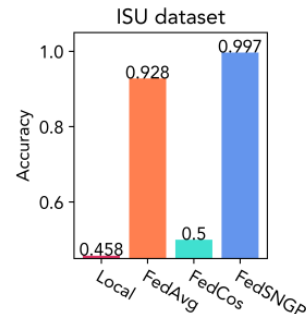
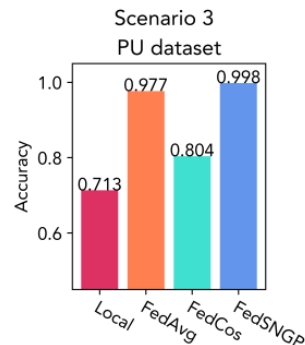
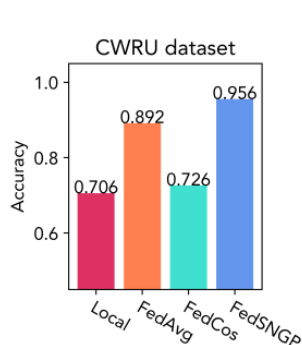
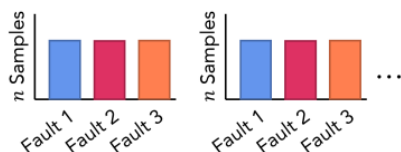
Scenario 3

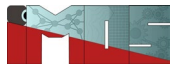
Datasets are heterogeneous in sample size, fault type, and exhibit domain shift from different working conditions.

Clients' datasets



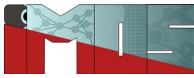
Evaluation datasets





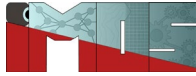
Explainability / Interpretability

Most of the time, the algorithms work really well but sometimes...

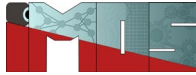


A refrigerator filled with lots of food and drinks

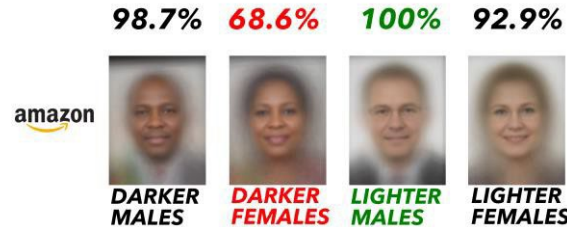
EPFL Tesla Autopilot Misidentified On-Road Horse-Drawn Carriage



Bias in algorithms



August 2018 Accuracy on Facial Analysis Pilot Parliaments Benchmark



Amazon Rekognition Performance on Gender Classification

<https://medium.com/@Joy.Buolamwini/response-racial-and-gender-bias-in-amazon-rekognition-commercial-ai-system-for-analyzing-faces-a289222eeced>

Machine Learning can amplify bias.

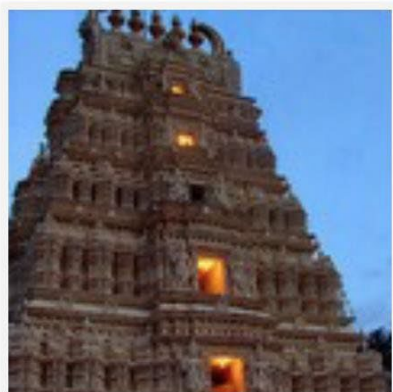
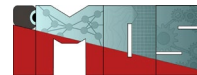


- Data set: 67% of people cooking are women
- Algorithm predicts: 84% of people cooking are women

<https://www.infoq.com/presentations/unconscious-bias-machine-learning/>

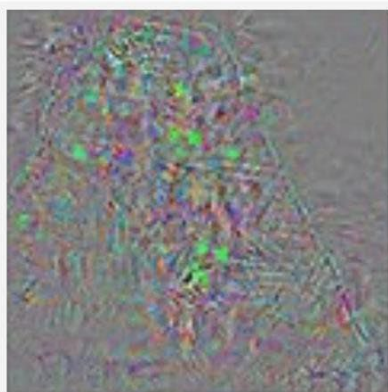
Source: Byron Wallace

Adversarial Examples

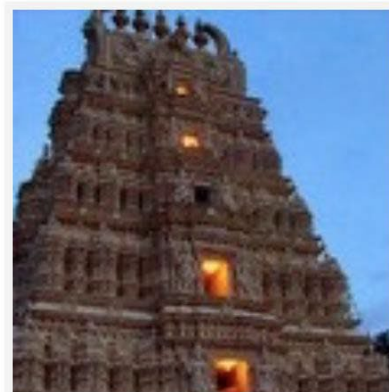


Original image

Temple (97%)



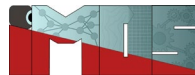
Perturbations



Adversarial example

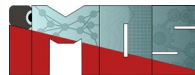
Ostrich (98%)

Current limitations of the ML algorithms



- Interpretability (Explainability, Transparency, Understanding, Trust)
- Physical consistency
- Complex and uncertain data
- Limited labels
- Bias
- (Computational demand)

What is interpretability?

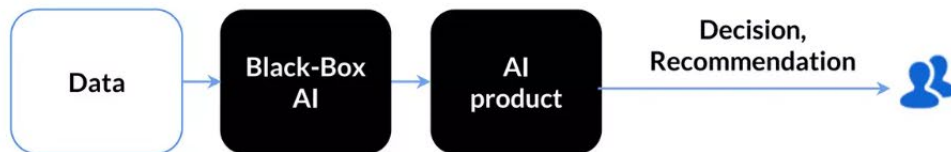


- *Ability to explain or to present a model in understandable terms to humans (Doshi-Velez 2017)*

Why explainable AI?



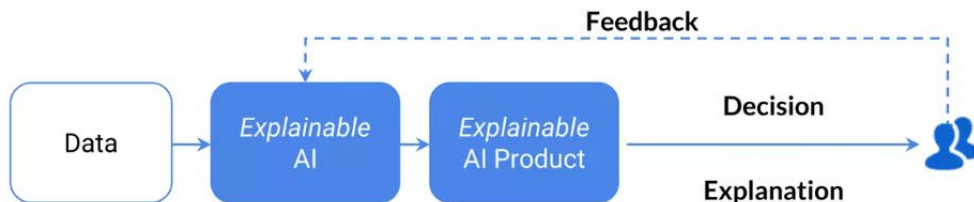
Black Box AI



Confusion with Today's AI Black Box

- Why did you do that?
- Why did you not do that?
- When do you succeed or fail?
- How do I correct an error?

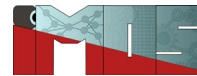
Explainable AI



Clear & Transparent Predictions

- I understand why
- I understand why not
- I know why you succeed or fail
- I understand, so I trust you

Simple explainability



- In pre-deep learning models, some models are considered “interpretable”

Dependent Variable $\rightarrow Y_i = \beta_0 + \beta_1 X_i + \varepsilon_i$

Population Y intercept $\rightarrow \beta_0$

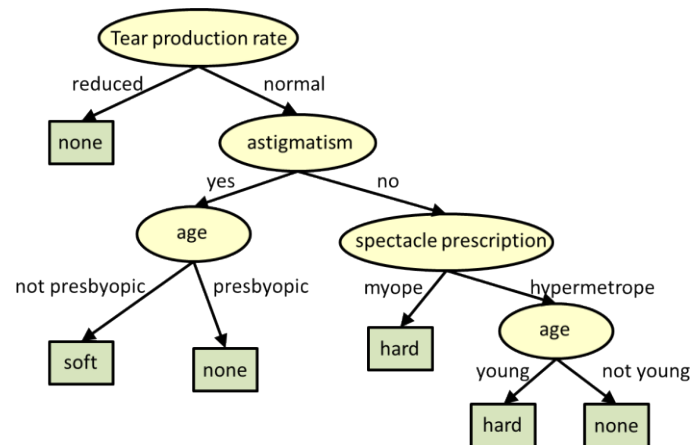
Population Slope Coefficient $\rightarrow \beta_1$

Independent Variable $\rightarrow X_i$

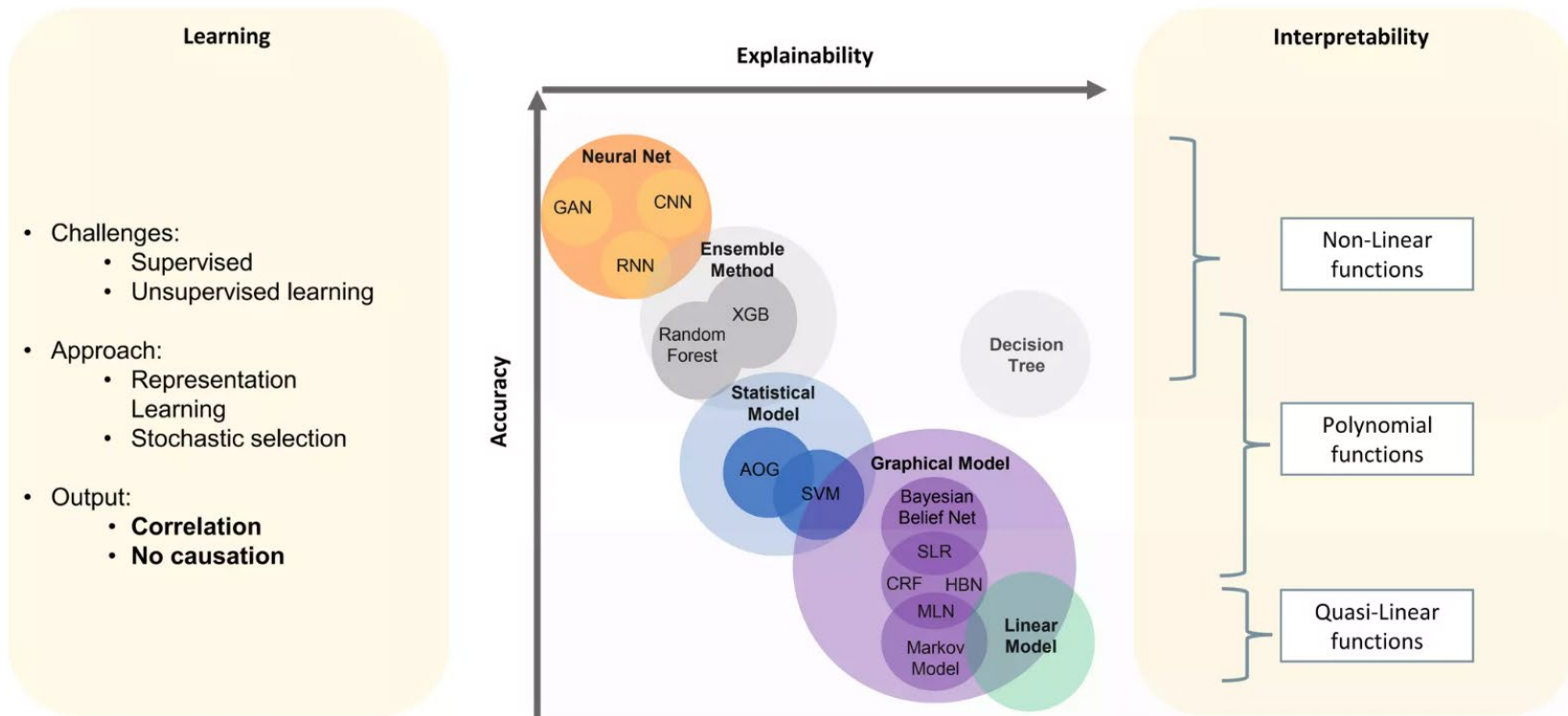
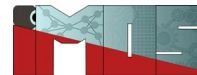
Random Error term $\rightarrow \varepsilon_i$

Linear component $\underbrace{\beta_0 + \beta_1 X_i}$

Random Error component $\underbrace{\varepsilon_i}$

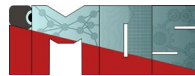


Source: Byron Wallace

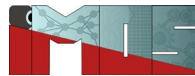


Source: WWW 2020 Tutorial

Different ways to achieve interpretability

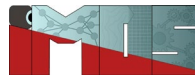


- Build interpretability into the model (e.g. by fusing physical models and machine learning or learning the underlying physics explicitly)
- Post-hoc approach to interpretability → trying to explain given models and their output



Some properties of Interpretations

- Faithfulness - how to provide explanations that accurately represent the true reasoning behind the model's final decision.
- Plausibility – Is the explanation correct or something we can believe is true, given our current knowledge of the problem ?
- Understandable – Can I put it in terms that end user without in-depth knowledge of the system can understand ?
- Stability – Do similar instances have similar interpretations ?

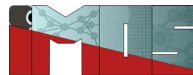


Evaluating Interpretability

- Application level evaluation – Put the model in practice and have the end users interact with explanations to see if they are useful .
- Human evaluation – Set up a Mechanical Turk task and ask non-experts to judge the explanations
- Functional evaluation – Design metrics that directly test properties of your explanation.

[Doshi-Velez 2017]

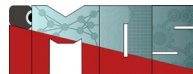
Global vs Local



- Do we explain individual prediction ?
- Example :
- Heatmaps
- Rationales

- Do we explain entire model?
- Example :
- Linear Regression
- Decision Trees

Inherent vs Post-hoc



- Is the explainability built into the model ?

- Examples:

- Linear Regression
- Decision Trees

- Is the model black-box and we use external method to try to understand it ?

- Examples:

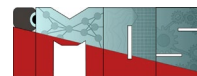
- Heatmaps (Some forms)

Model based vs Model Agnostic

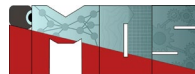
- Can it explain only few classes of models?
- Examples:
 - Decision Trees
 - Attention
 - Gradients (Differentiable Models only)
- Can it explain any model ?
- Examples:
 - LIME – Locally Interpretable Model Agnostic Explanations
 - SHAP – Shapley Values

Source: Byron Wallace

Different approaches to explain the behavior of ML approaches post-hoc



- Explaining with Surrogates
- Explaining with local perturbations
- Propagation-Based Approaches (Leveraging Structure)
- Meta-explanations
- Attribution-based methods
- Counterfactual explanation
- Interaction explanations
- Attention Mechanisms
- ...

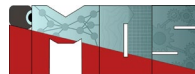


Feature Importance and Attribution Methods

- These methods identify the most influential features or components in making a prediction.
- **SHAP (SHapley Additive exPlanations)**: Based on cooperative game theory, SHAP assigns each feature a "Shapley value" that indicates its contribution to a particular prediction. SHAP values provide consistent and fair attribution by treating each feature as a "player" in a game.
- **LIME (Local Interpretable Model-agnostic Explanations)**: LIME approximates complex models by locally fitting an interpretable model (like linear regression) around a specific instance. It perturbs input features to see how predictions change, helping identify which features influence the prediction.
- **Integrated Gradients**: A technique for neural networks that calculates feature importance by integrating the gradients of a model's output with respect to its inputs, starting from a baseline (e.g., zero). Integrated gradients quantify each input's contribution to a model's prediction.
- **Permutation Feature Importance**: Measures feature importance by shuffling each feature in turn and observing the impact on model accuracy. If a feature's importance is high, shuffling its values will significantly degrade model performance.

Visualization Techniques

- Visualization is key to making model insights understandable for humans, especially in image and text processing.
- **Saliency Maps**: Often used in image processing, saliency maps highlight the parts of an image that have the most influence on a model's prediction. This can help in understanding what parts of an image a convolutional neural network (CNN) is focusing on.
- **Partial Dependence Plots (PDP)**: Show the relationship between one or two features and the predicted outcome, averaging out the effect of other features. PDPs help understand how the model's predictions change as the value of a feature changes.
- **Layer-wise Relevance Propagation (LRP)**: Assigns relevance scores to each neuron in the network, which can be aggregated to show which pixels or words are most influential in a decision. This technique is especially useful for deep neural networks.
- **t-SNE and UMAP**: Dimensionality reduction techniques that help visualize high-dimensional data in two or three dimensions, making it easier to observe clusters or patterns in the data that the model may have learned.



Surrogate Models

- **Surrogate Models:** These are simpler, interpretable models (like linear or decision tree models) trained to approximate a complex model's predictions. Surrogate models can provide a global understanding of a complex model's behavior by approximating its decision boundaries.

Counterfactual Explanations

- Counterfactual explanations help answer "what if" questions by indicating how a model's prediction would change if the input features were altered. For example, in loan applications, a counterfactual explanation might state, "If the applicant's income were \$5,000 higher, the loan would be approved." This type of explanation is valuable for understanding decision boundaries and fairness.

Causal Inference and Causal Models

- Causal inference goes beyond correlation by trying to understand causal relationships between variables. Causal models can help identify which factors genuinely influence predictions rather than merely correlate with the outcome. These methods are particularly important in applications where knowing causality is crucial, such as medicine or social sciences.

Rule-Based Explanations and Decision Rules

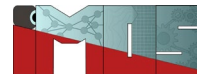
- Some models, such as decision trees and rule-based models, are naturally interpretable. These models use a series of if-then rules that are easy for humans to follow. For more complex models, rule extraction techniques can derive decision rules that approximate the model's decision process, making it more interpretable.

Prototype and Example-Based Explanations

- **Prototypes:** These are representative examples from the training set that encapsulate common patterns or features. Showing a prototype can help users understand typical cases within a class.
- **Influence Functions:** These methods determine which training examples are most responsible for a specific prediction. They help identify cases in the training data that the model relied on heavily, which can be especially useful for diagnosing model biases.

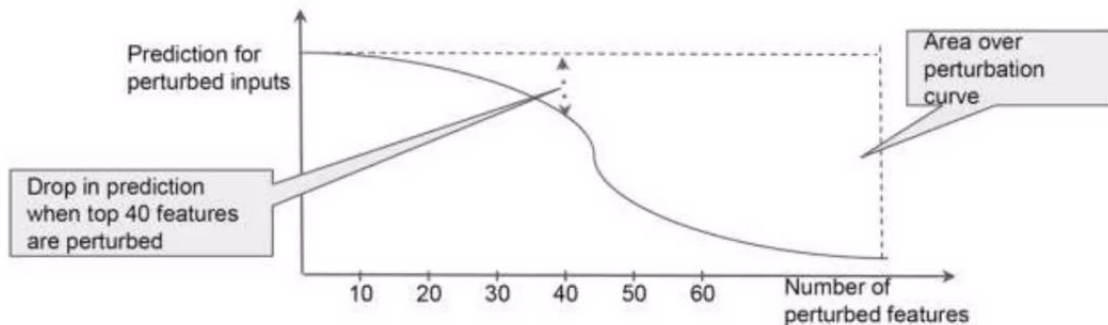
Bayesian and Probabilistic Approaches

- Probabilistic models, such as Bayesian networks, can inherently quantify uncertainty in their predictions. By providing a probabilistic interpretation of model decisions, these methods allow users to understand the confidence level associated with each prediction, helping to address questions of model reliability.

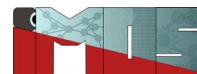


Perturb top-k features by attribution and observe change in prediction

- Higher the change, better the method
- Perturbation may amount to replacing the feature with a random value
- Samek et al. formalize this using a metric: **Area over perturbation curve**
 - Plot the prediction for input with top-k features perturbed as a function of k
 - Take the area over this curve

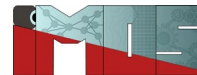


Source: KDD 2019 Tutorial

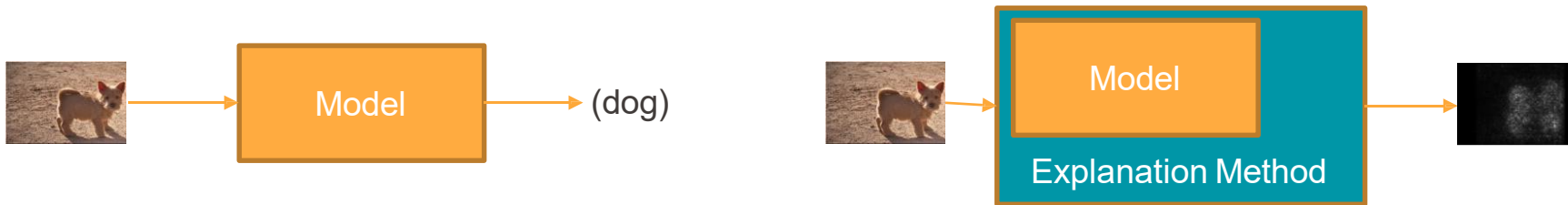


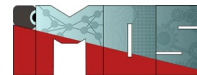
- Attribute a model's prediction on an input to features of the input
- Attribution methods
 - Ablations (drop each feature and attribute the change in prediction to that feature)
 - Gradient-based methods (attribution to a feature is feature value times gradient)
 - Score backpropagation based methods
 - **Guided BackProp**: Only consider ReLUs that are on (linear regime), and which contribute positively
 - **LRP**: Use first-order Taylor decomposition to linearize activation function
 - **DeepLift**: Distribute activation difference relative a reference point in proportion to edge weights

Saliency Based Methods



- Heatmap based visualization
- Need differentiable model in most cases
- Normally involve gradient

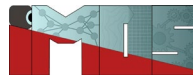




	Original Image	Gradient	SmoothGrad	Guided BackProp	Guided GradCAM	Integrated Gradients	Integrated Gradients SmoothGrad	Gradient $\odot$ Input
Junco Bird								
Corn								
Wheaten Terrier								

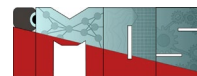
[Adebayo et al 2018]

Saliency Example - Gradients



$$f(x): R^d \rightarrow R$$

$$E(f)(x) = \frac{df(x)}{dx}$$



Saliency Example – Leave-one-out

$$f(x): R^d \rightarrow R$$

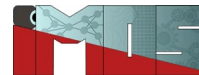
$$E(f)(x)_i = f(x) - f(x \setminus i)$$

How to remove ?

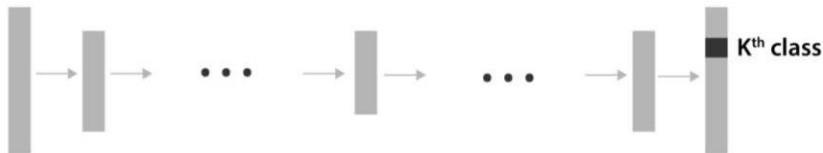
1. Zero out pixels in image
2. Remove word from the text
3. Replace the value with population mean in tabular data

Source: Byron Wallace

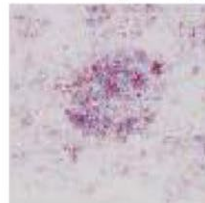
Sanity check: When predictions change, do the explanations change?



Original Image



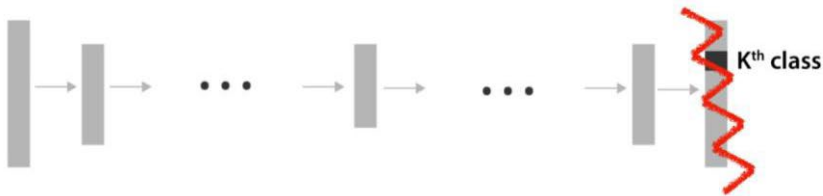
Saliency map



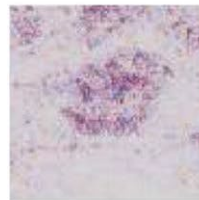
Original Image



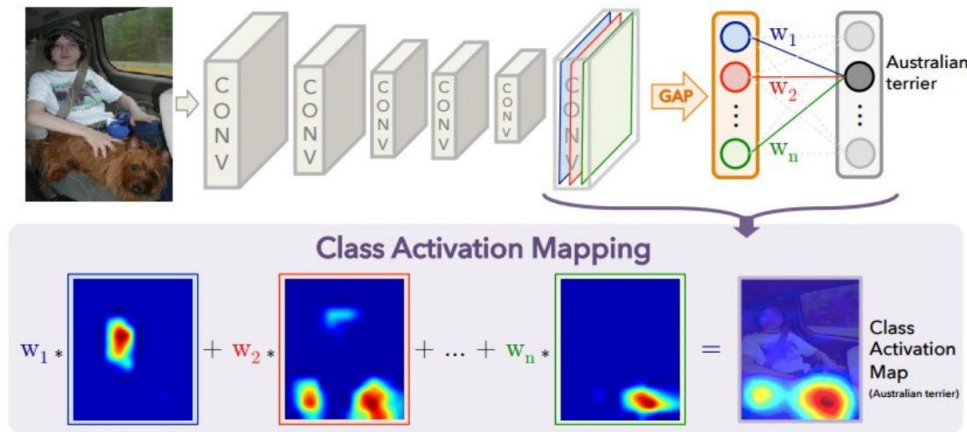
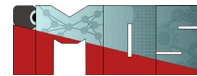
Randomized weights!
Network now makes garbage predictions.



!!!!!!??!?

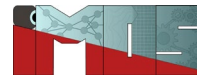


Source: Julius Adebayo



- GAP: Global average pooling
- We can identify the importance of the image regions by projecting back the weights of the output layer on the convolutional feature maps obtained from the last Convolution Layer.

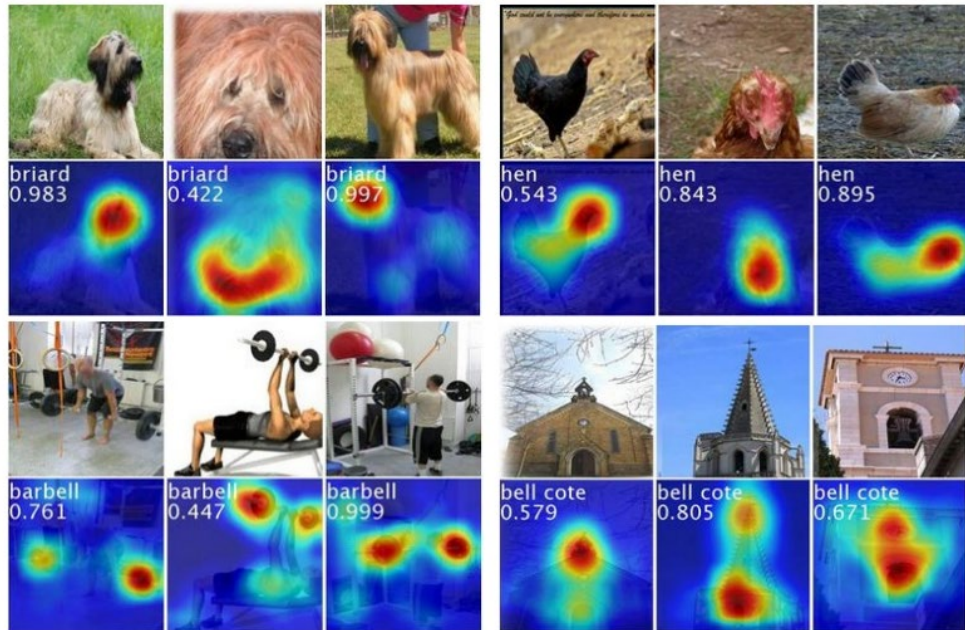
Class Activation Mapping: examples

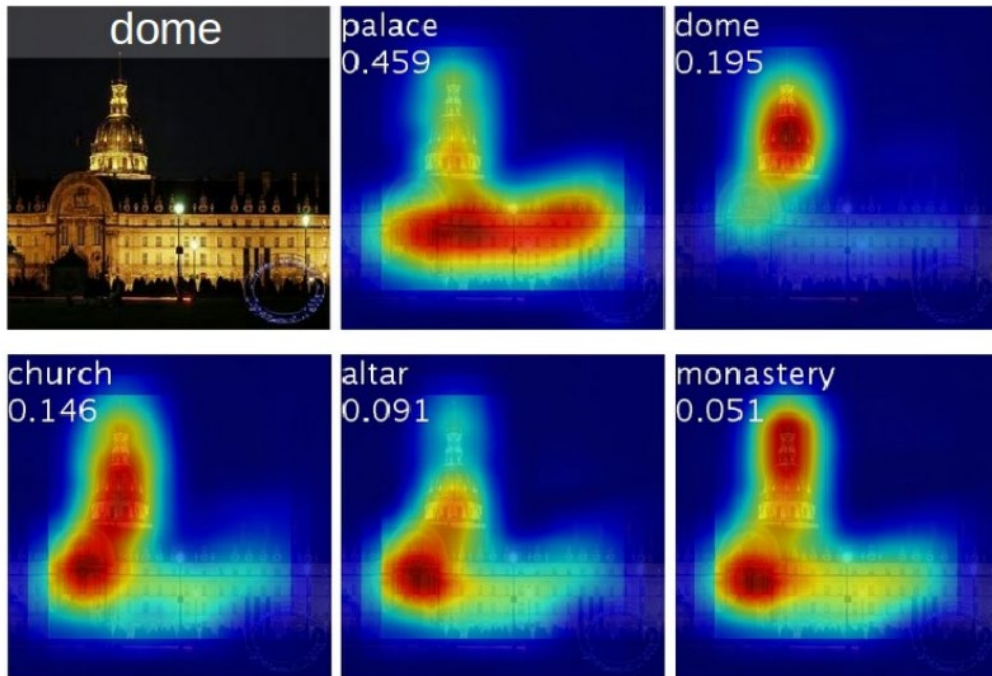
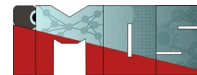


Brushing teeth

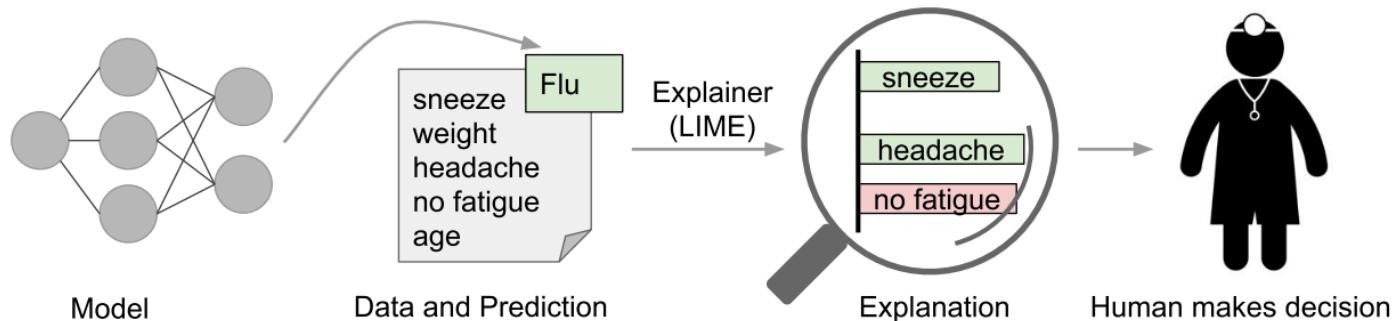


Cutting trees



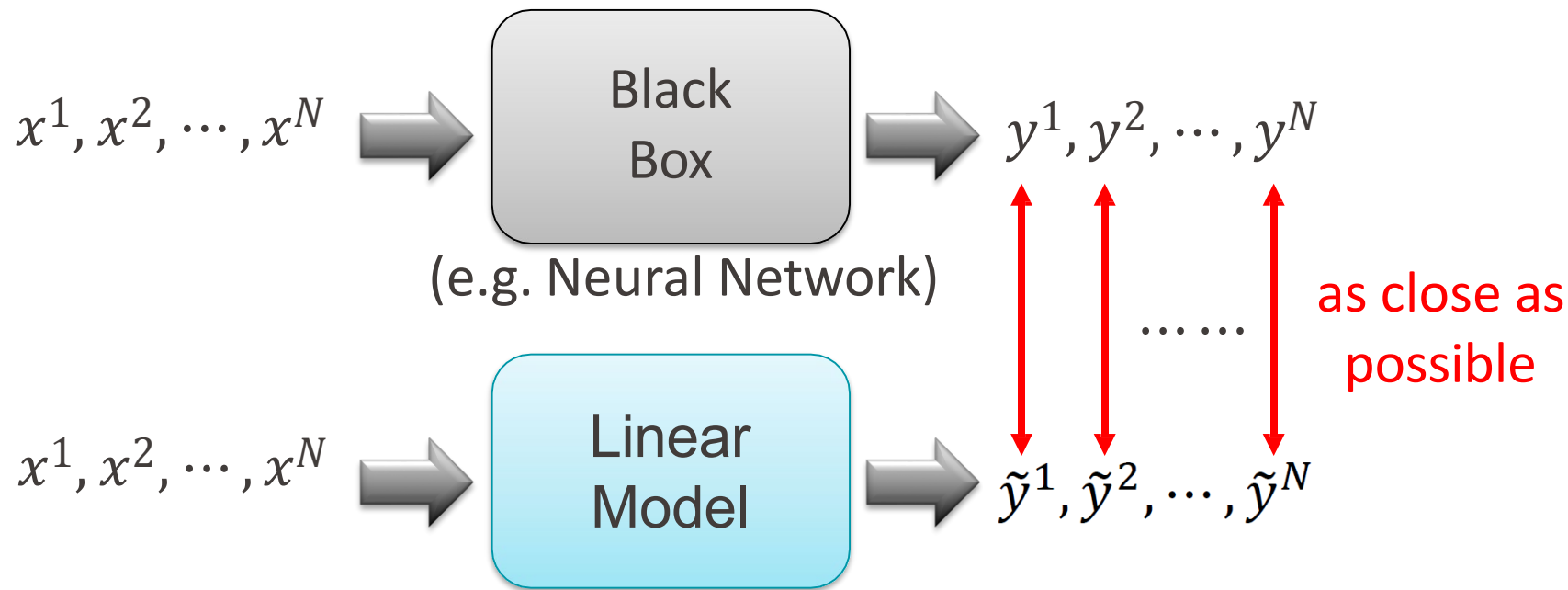
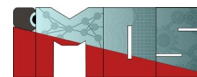


Local Interpretable Model-Agnostic Explanations (LIME): basic idea



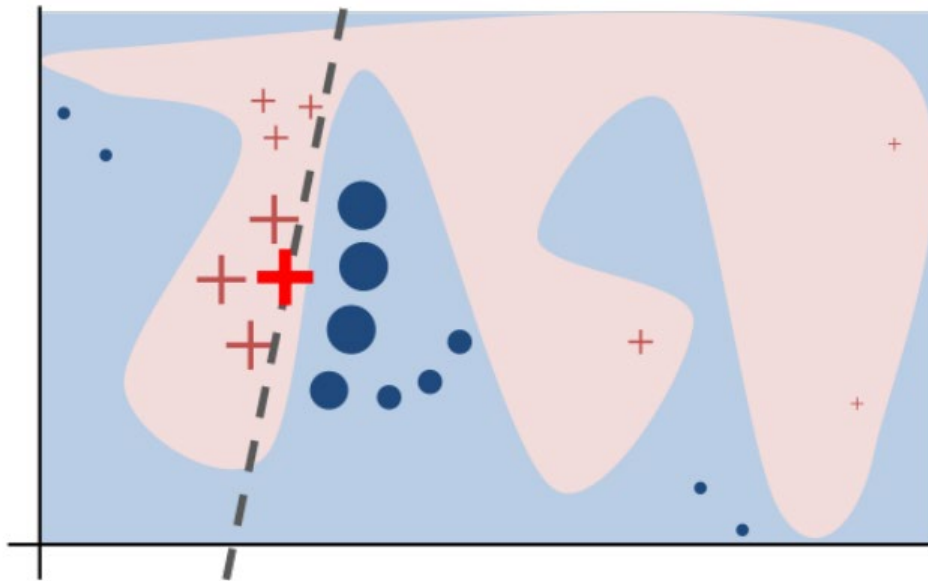
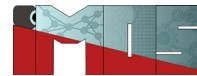
M. T. Ribeiro, S. Singh, and C. Guestrin, "Why should I trust you? Explaining the predictions of any classifier," in *Proceedings of the ACM SIGKDD International Conference on Knowledge Discovery and Data Mining*, 2016, vol. 13-17-Aug, pp. 1135–1144.

LIME – locally interpretable model agnostic

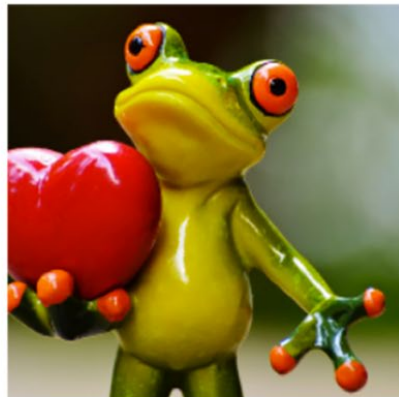
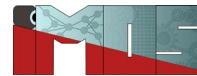


Can't do it globally of course, but locally ? Main Idea behind LIME

LIME: Toy example of the basic concept



LIME: divide images into interpretable components (contiguous superpixels)



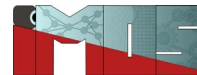
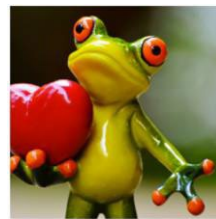
Original Image



Interpretable
Components

M. T. Ribeiro, S. Singh, and C. Guestrin, “‘Why should I trust you?’ Explaining the predictions of any classifier,” in *Proceedings of the ACM SIGKDD International Conference on Knowledge Discovery and Data Mining*, 2016, vol. 13-17-Aug, pp. 1135–1144.

LIME — Image

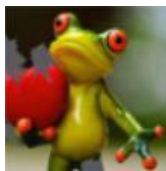


1. Given a data point you want to explain
2. Sample at the nearby - Each image is represented as a set of superpixels (segments).



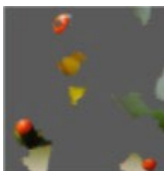
Black

0.85



Black

0.52



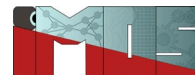
Black

0.01

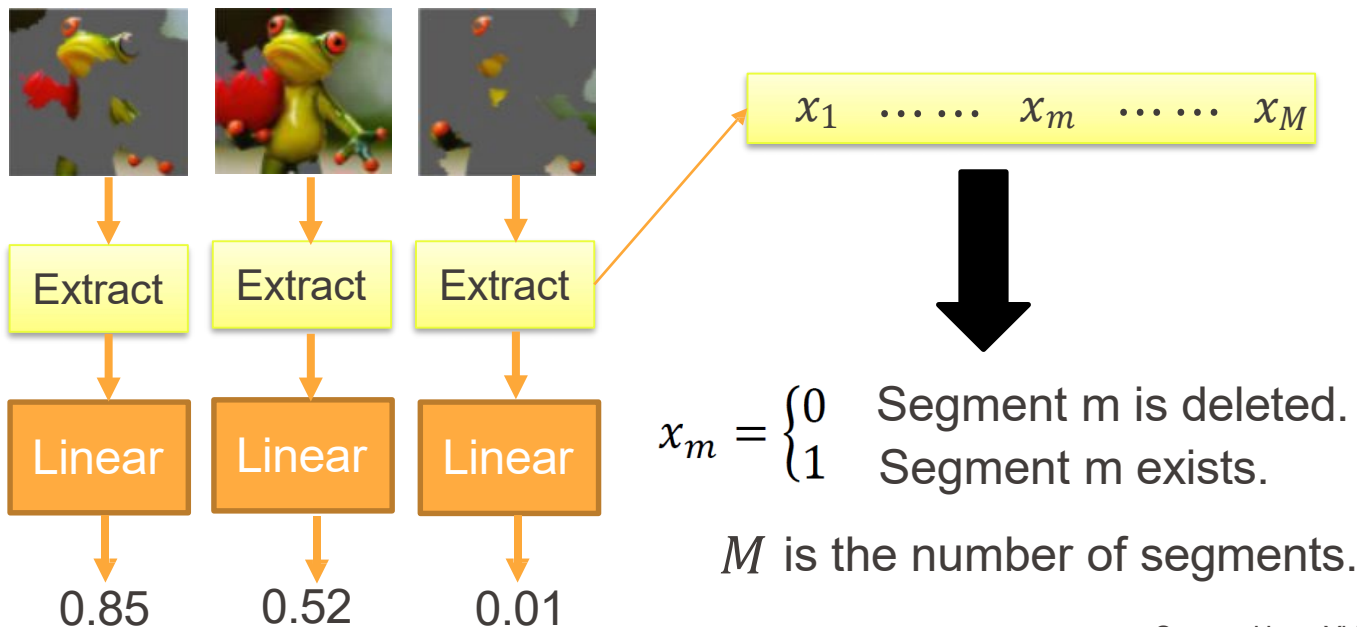
- Randomly delete some
- segments.

Compute the probability of “frog” by black box

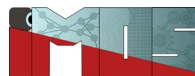
LIME — Image



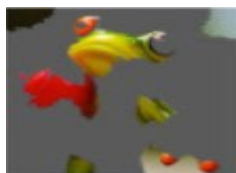
- 3. Fit with linear (or interpretable) model



LIME — Image



- 4. Interpret the model you learned



Extract

Linear

0.85

$$y = w_1x_1 + \dots + w_mx_m + \dots + w_Mx_M$$

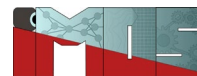
$$x_m = \begin{cases} 0 & \text{Segment } m \text{ is deleted.} \\ 1 & \text{Segment } m \text{ exists.} \end{cases}$$

M is the number of segments.

If $w_m \approx 0$  segment m is not related to “frog”

If w_m is positive  segment m indicates the image is “frog”

If w_m is negative  segment m indicates the image is not “frog”



Algorithm 1 Sparse Linear Explanations using LIME

Require: Classifier f , Number of samples N

Require: Instance x , and its interpretable version x'

Require: Similarity kernel π_x , Length of explanation K

$\mathcal{Z} \leftarrow \{\}$

for $i \in \{1, 2, 3, \dots, N\}$ **do**

$z'_i \leftarrow \text{sample_around}(x')$

$\mathcal{Z} \leftarrow \mathcal{Z} \cup \langle z'_i, f(z_i), \pi_x(z_i) \rangle$

end for

$w \leftarrow \text{K-Lasso}(\mathcal{Z}, K) \triangleright$ with z'_i as features, $f(z)$ as target

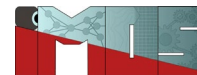
return w

Match interpretable
model to black box

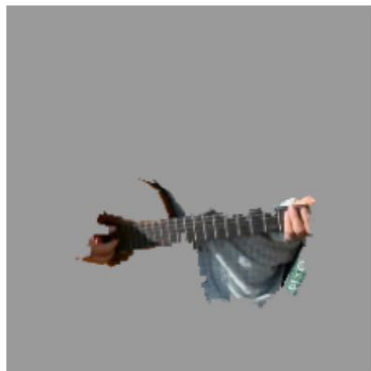
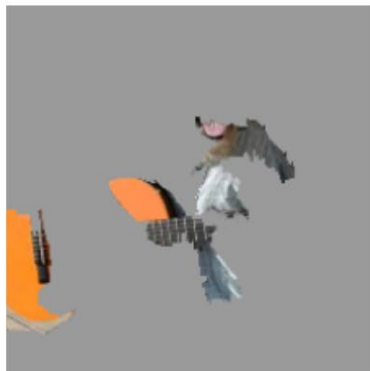
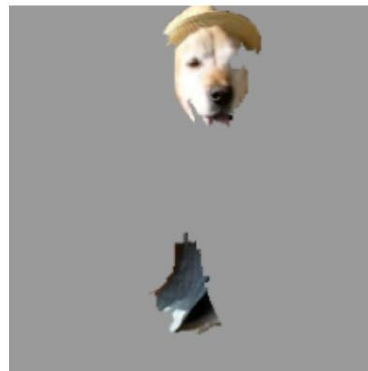
Control
complexity of the
model

$$\xi(x) = \operatorname{argmin}_{g \in G} \mathcal{L}(f, g, \pi_x) + \Omega(g)$$

$$\mathcal{L}(f, g, \pi_x) = \sum_{z, z' \in \mathcal{Z}} \pi_x(z) (f(z) - g(z'))^2$$

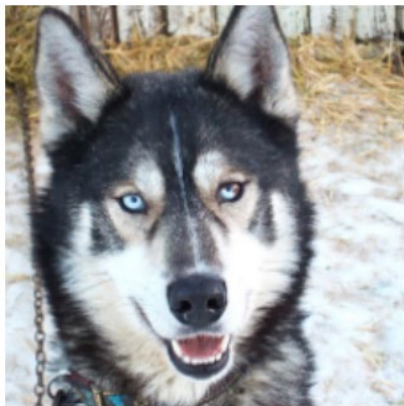
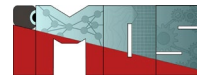


(a) Original Image

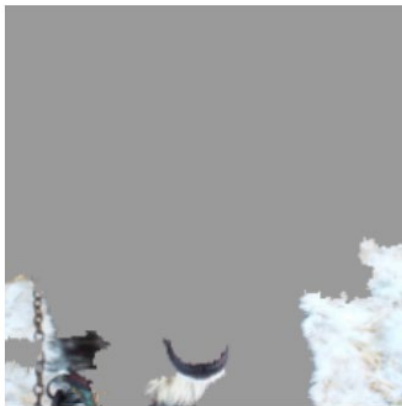
(b) Explaining *Electric guitar*(c) Explaining *Acoustic guitar*(d) Explaining *Labrador*

M. T. Ribeiro, S. Singh, and C. Guestrin, “‘Why should I trust you?’ Explaining the predictions of any classifier,” in *Proceedings of the ACM SIGKDD International Conference on Knowledge Discovery and Data Mining*, 2016, vol. 13-17-Aug, pp. 1135–1144.

LIME: bringing trust («Husky vs Wolf»)



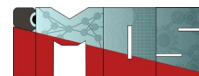
(a) Husky classified as wolf



(b) Explanation

	Before	After
Trusted the bad model	10 out of 27	3 out of 27
Snow as a potential feature	12 out of 27	25 out of 27

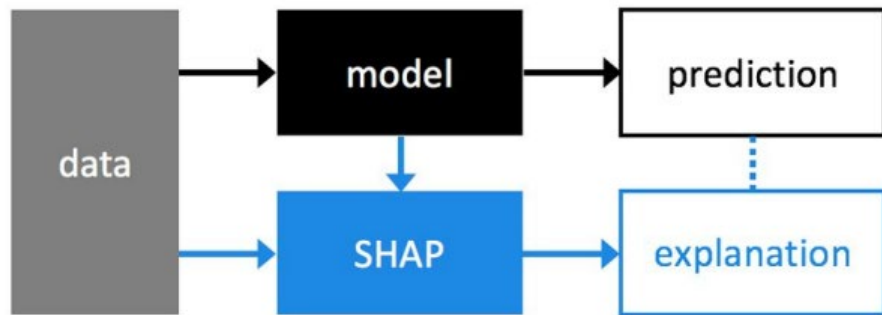
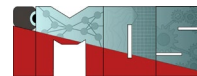
SHAP (Shapley values Additive exPlanations) – additive feature attribution method to explain the output of any ML model



Classic result in game theory on distributing gain in a **coalition game**

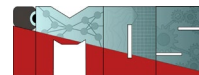
- **Coalition Games**
 - Players collaborating to generate some **gain** (think: revenue)
 - Set function $v(S)$ determining the gain for any subset S of players
- **Shapley Values** are a fair way to attribute the total gain to the players based on their contributions
 - Concept: **Marginal contribution** of a player to a subset of other players ($v(S \cup \{i\}) - v(S)$)
 - Shapley value for a player is a **specific weighted aggregation of its marginal** over all possible subsets of other players

SHAP (Shapley values Additive exPlanations) – additive feature attribution method to explain the output of any ML model



The Shapley value is a mathematical concept in game theory that was introduced by Lloyd Shapley in 1951.

Lundberg, S., & Lee, S. I. (2017). A unified approach to interpreting model predictions.



$$\phi_i = \sum_{S \subseteq F \setminus \{i\}} \frac{|S|!(|F| - |S| - 1)!}{|F|!} [f_{S \cup \{i\}}(x_{S \cup \{i\}}) - f_S(x_S)]$$

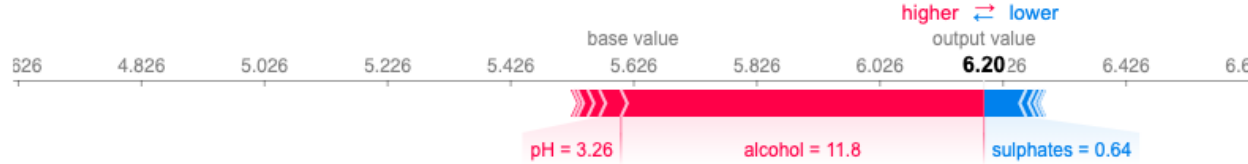
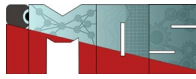
where S feature subset, F – set of all features, $S \subseteq F \setminus \{i\}$ all possible subsets

$f_{S \cup \{i\}}$ is trained with that feature present and f_S with that feature withheld

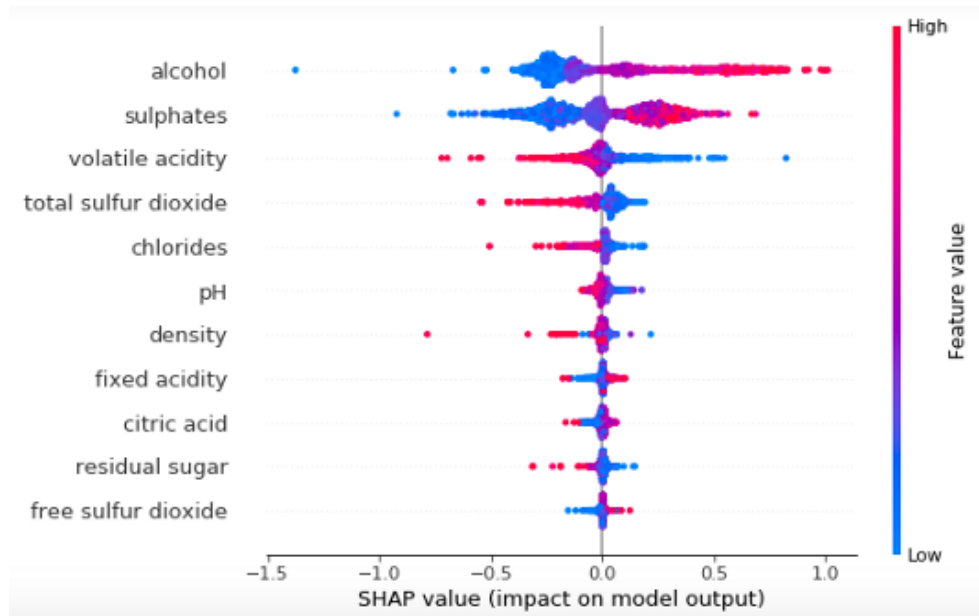
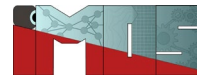
predictions from the two models are then compared $f_{S \cup \{i\}}(x_{S \cup \{i\}}) - f_S(x_S)$

Lundberg, S., & Lee, S. I. (2017). A unified approach to interpreting model predictions.

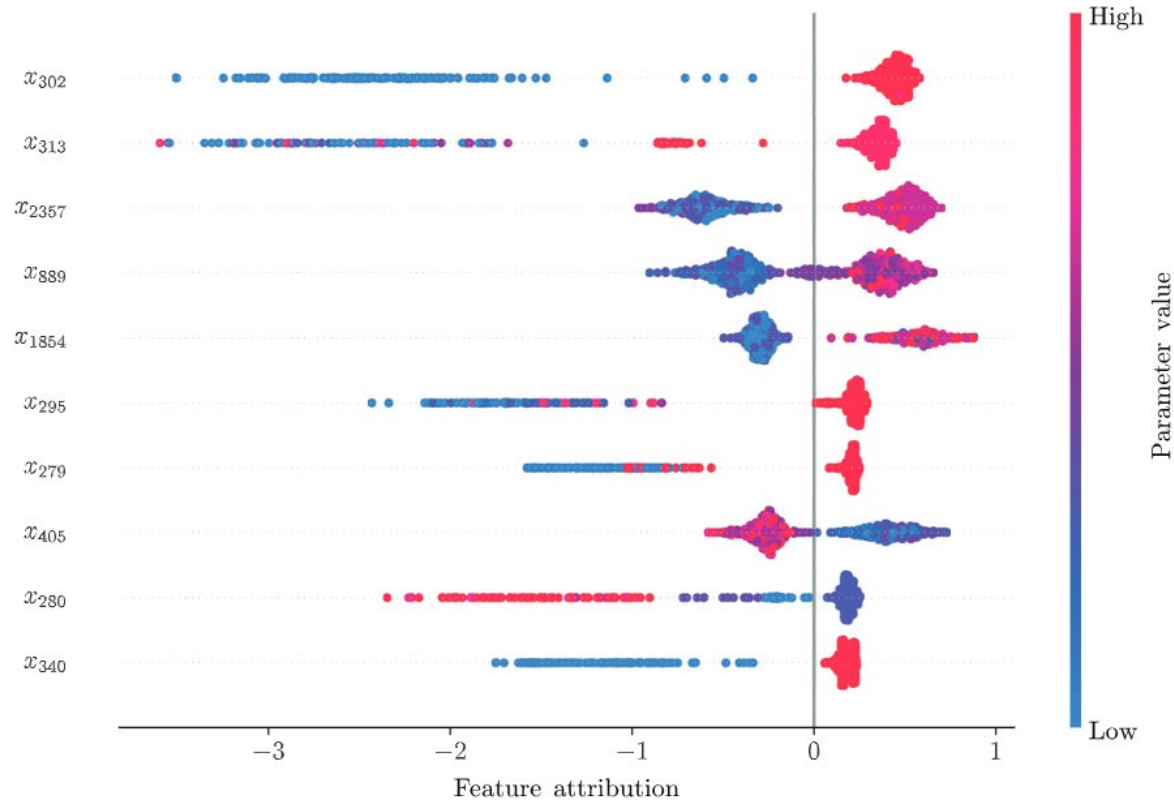
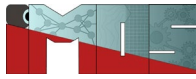
Individual SHAP value plot



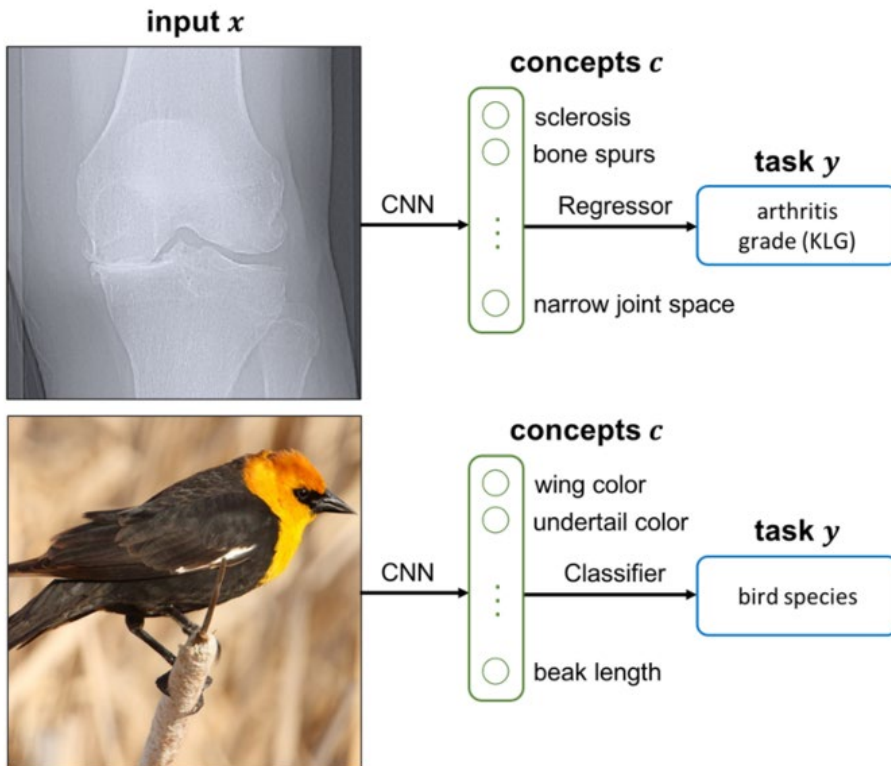
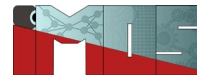
SHAP variables importance plot



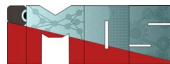
Drivers of the semiconductor production quality



Senoner, J., Netland, T., & Feuerriegel, S. (2022). Using explainable artificial intelligence to improve process quality: Evidence from semiconductor manufacturing. *Management Science*, 68(8), 5704-5723.

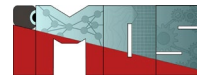


Koh, P. W., Nguyen, T., Tang, Y. S., Mussmann, S., Pierson, E., Kim, B., & Liang, P. (2020, November). Concept bottleneck models. In *International conference on machine learning* (pp. 5338-5348). PMLR.

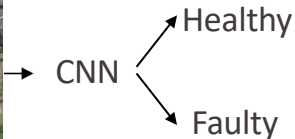


Example: Detecting defective insulators

Detecting defective insulators



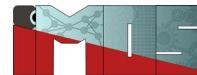
- XAI on Power Grid Insulators:
 - Fault detection → binary classifier
 - When faulty, apply XAI to show which part of the image led to the decision, highlighting the defect region



Interpretability

Fault localization

Evaluation of the prediction results



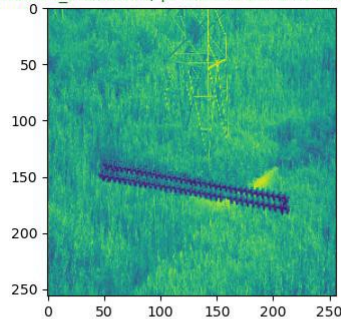
Test Accuracy = 96.4%

FPR = 3.6 %

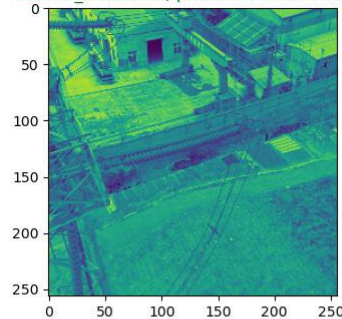
FNR = 3.8 %

Test Samples Examples
(defective $\rightarrow$ 0; Normal $\rightarrow$ 1)

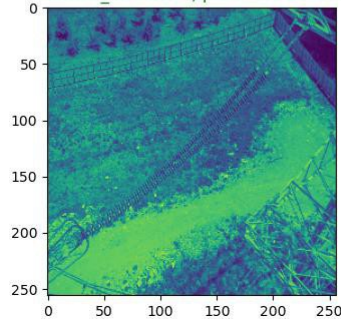
Defective_Insulators; predicted as: $3.0176452e-07$



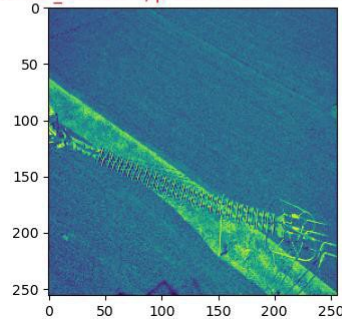
Normal_Insulators; predicted as: 0.999999

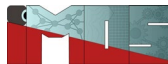


Normal_Insulators; predicted as: 1.0



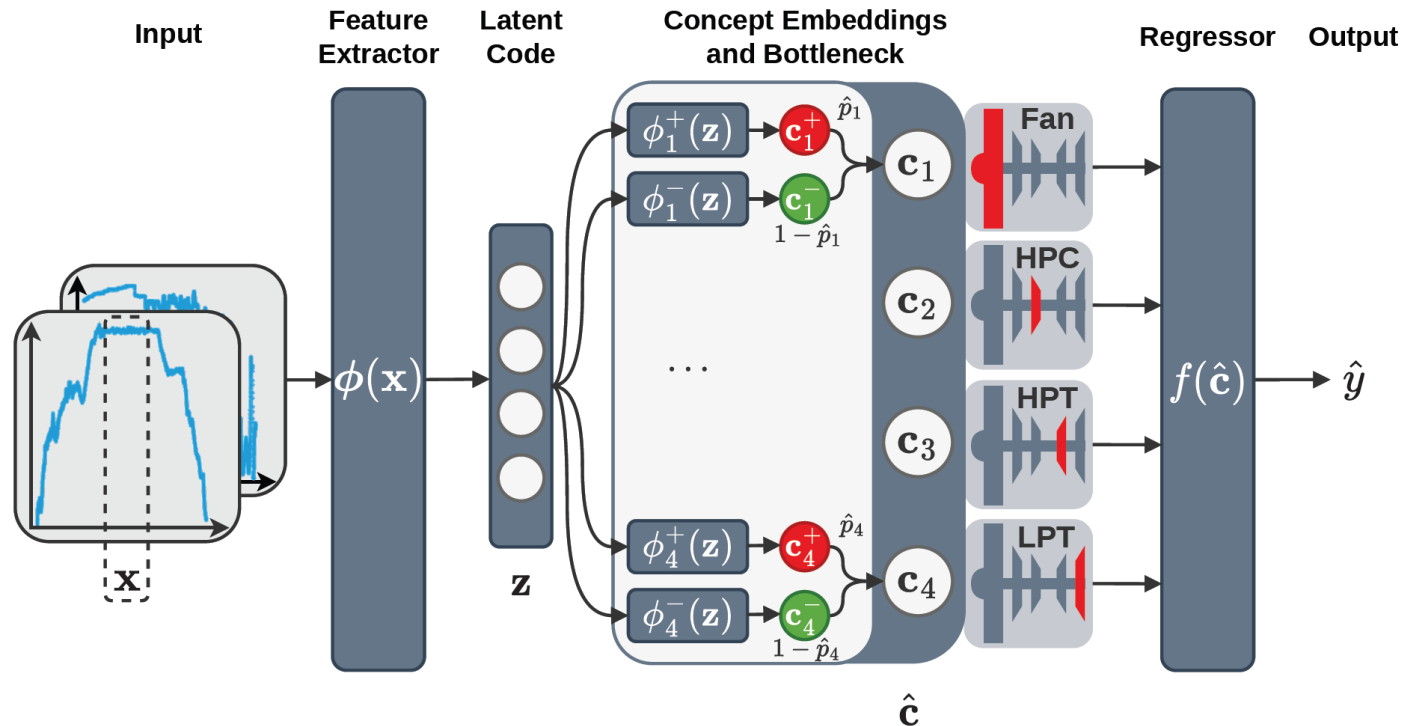
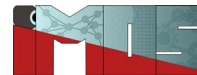
Normal_Insulators; predicted as: 0.0005989605





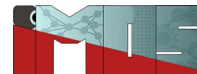
Example:

Integrated concept embeddings

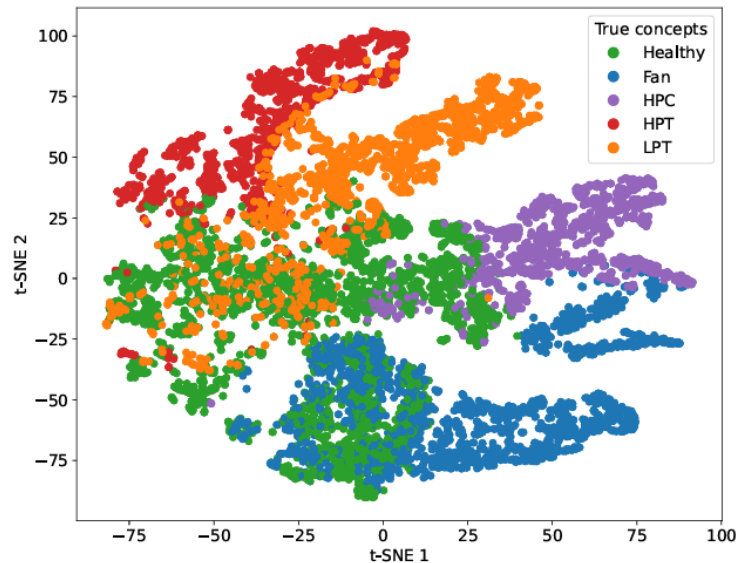
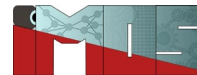


RUL prediction performance

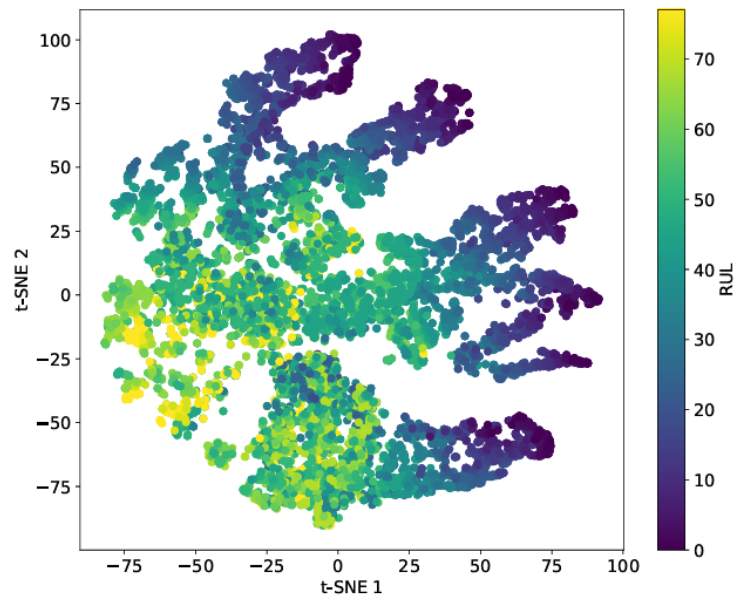
RMSE and NASA



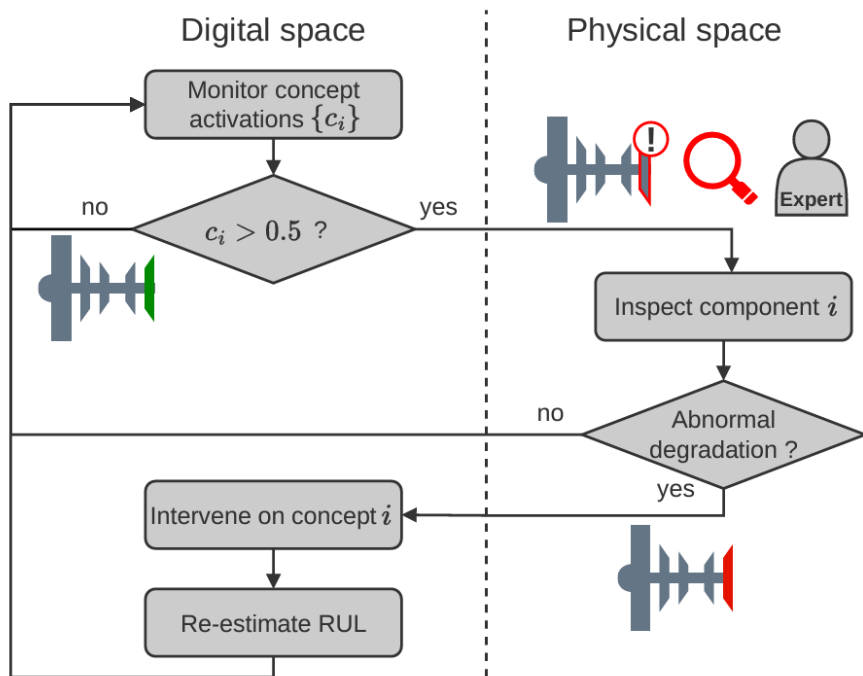
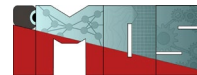
Method	RMSE	NASA score
CNN	6.79	0.851
CEM	6.15	0.752

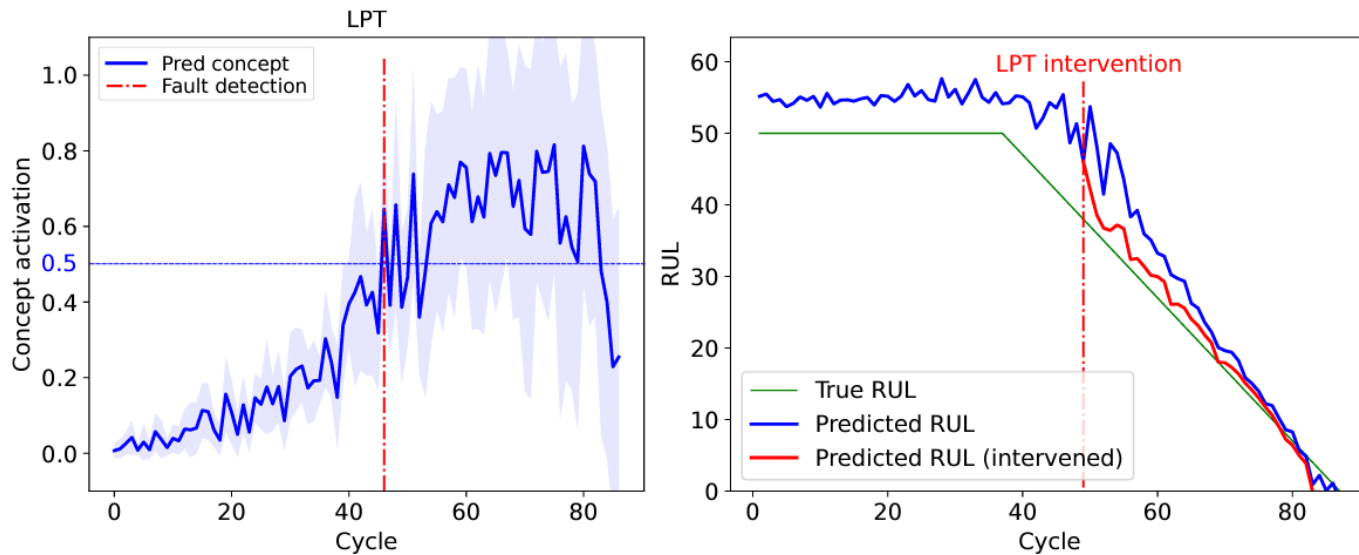
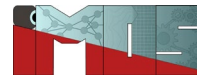


(a) Latent space colored by true concept.



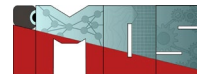
(b) Latent space colored by true RUL value.



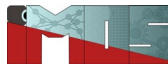


RUL prediction performance

RMSE and NASA



Method	RMSE	NASA score
CNN	6.79	0.851
CEM	6.15	0.752
CEM after intervention	5.96	0.692



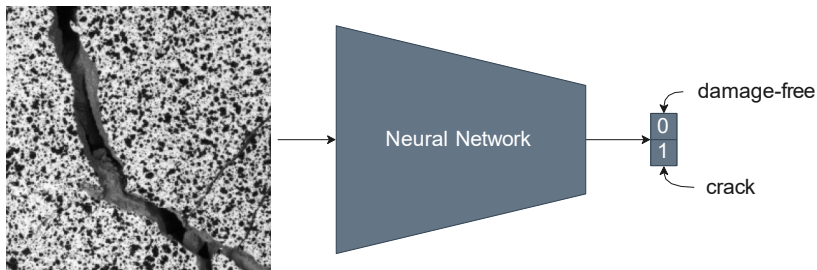
Example:

Using explanations for labeling

EPFL Machine learning for image-based crack detection

Data-driven approaches based on supervised deep learning have demonstrated excellent performance in detection of cracks in images, but they require **large annotated datasets** for training.

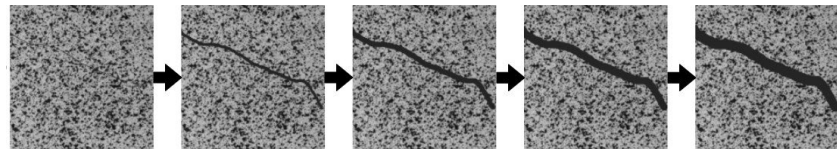
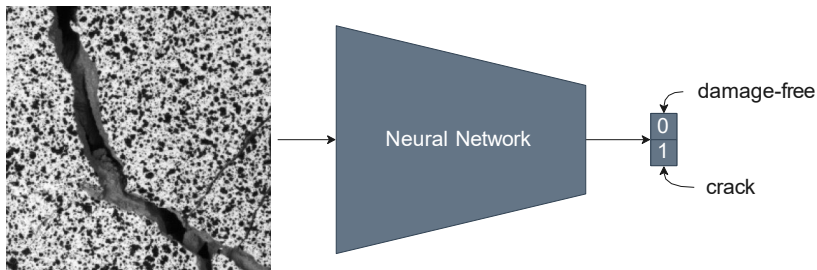
Classification task:



EPFL Machine learning for image-based crack detection

Data-driven approaches based on supervised deep learning have demonstrated excellent performance in detection of cracks in images, but they require **large annotated datasets** for training.

Classification task:

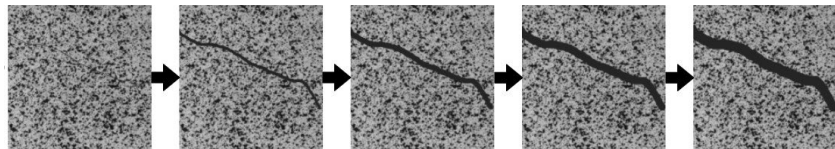
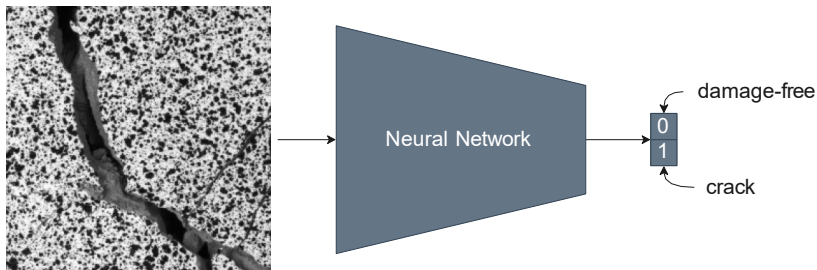


Severity quantification and monitoring is crucial for timely decision-making.

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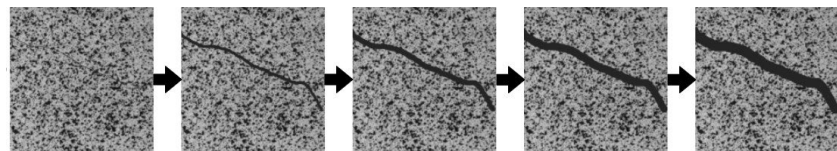
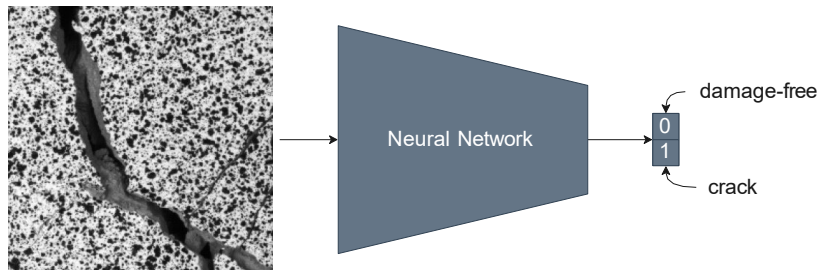
What we need:



EPFL Machine learning for image-based crack detection

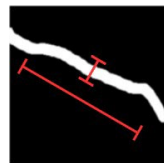
Data-driven approaches based on supervised deep learning have demonstrated excellent performance in detection of cracks in images, but they require **large annotated datasets** for training.

Classification task:



Severity quantification and monitoring is crucial for timely decision-making.

What we need:

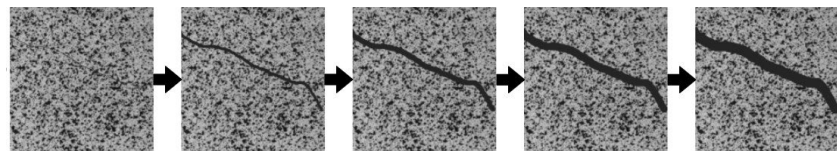
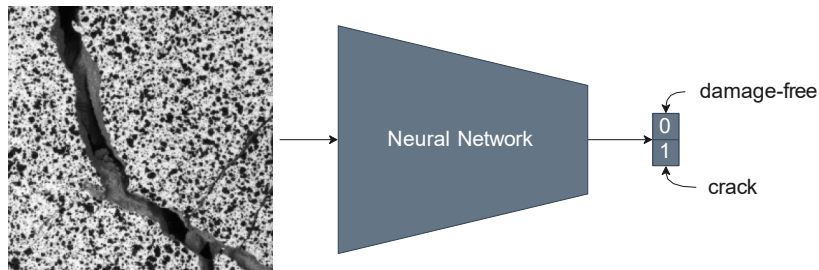


→ Severity metrics

EPFL Machine learning for image-based crack detection

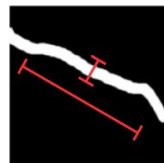
Data-driven approaches based on supervised deep learning have demonstrated excellent performance in detection of cracks in images, but they require **large annotated datasets** for training.

Classification task:



Severity quantification and monitoring is crucial for timely decision-making.

What we need: → Severity metrics

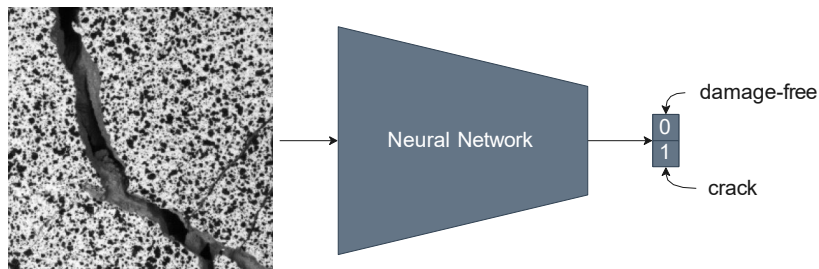


- ▶ Does not allow severity quantification
- ▶ Fast and easy image-level annotation (1 bit)

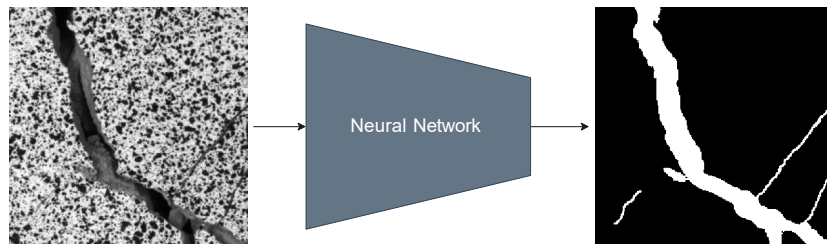
EPFL Machine learning for image-based crack detection

Data-driven approaches based on supervised deep learning have demonstrated excellent performance in detection of cracks in images, but they require **large annotated datasets** for training.

Classification task:

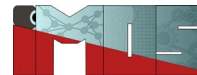


Semantic segmentation task:



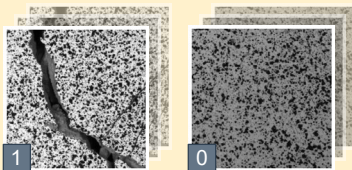
- ▶ Does not allow severity quantification
- ▶ Fast and easy image-level annotation (1 bit)

- ▶ Allows severity quantification and monitoring
- ▶ Tedious and costly pixel-level annotation ($256 \times 256 \rightarrow 2^{16} = 64 \text{ Kb}$)

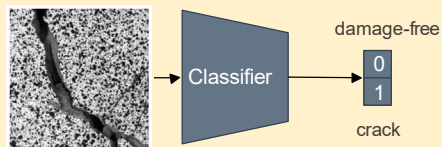


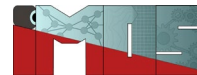
Proposed methodology:

1. Data collection and labeling (image-level)

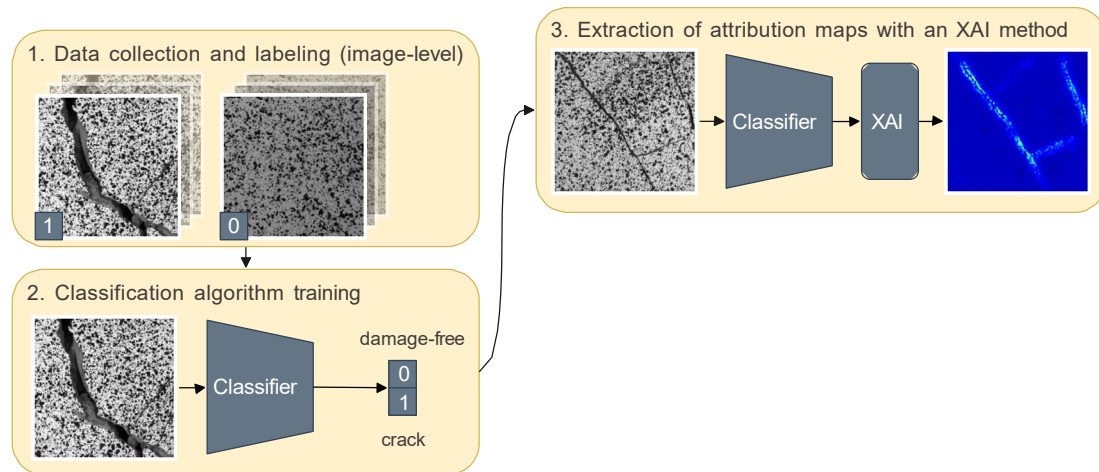


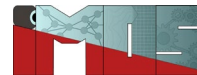
2. Classification algorithm training



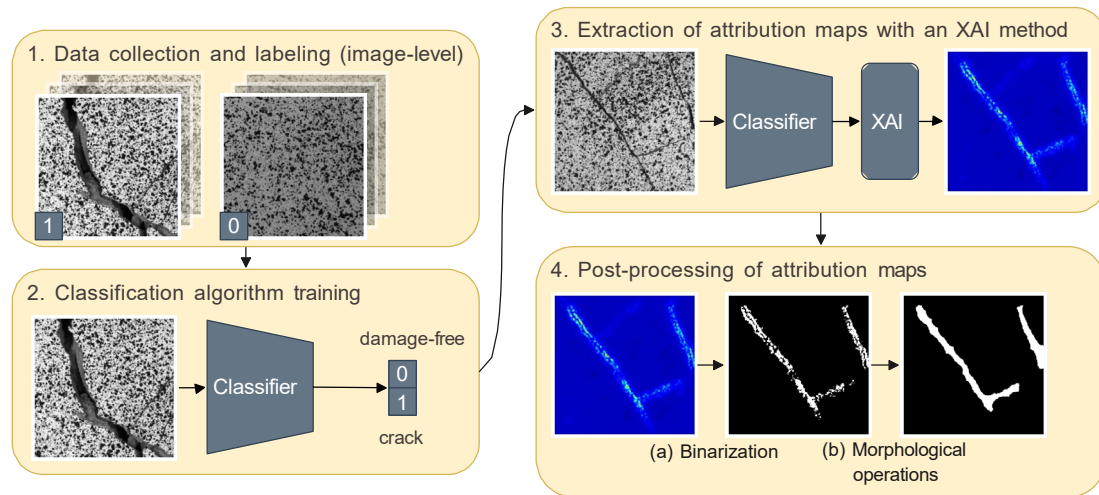


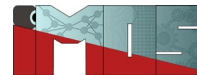
Proposed methodology:



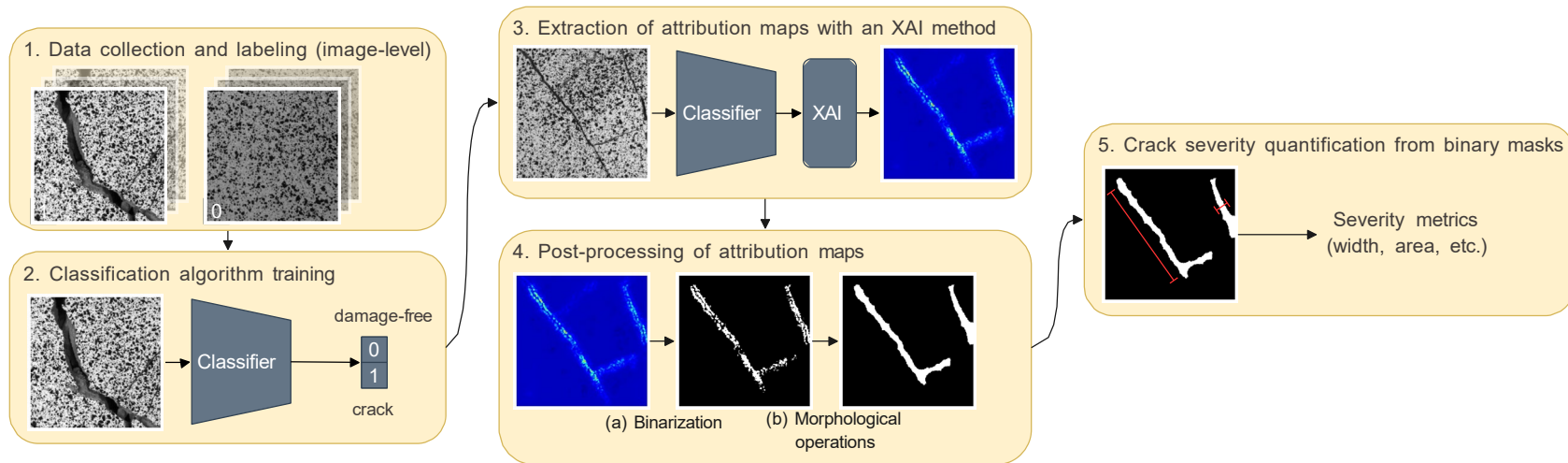


Proposed methodology:

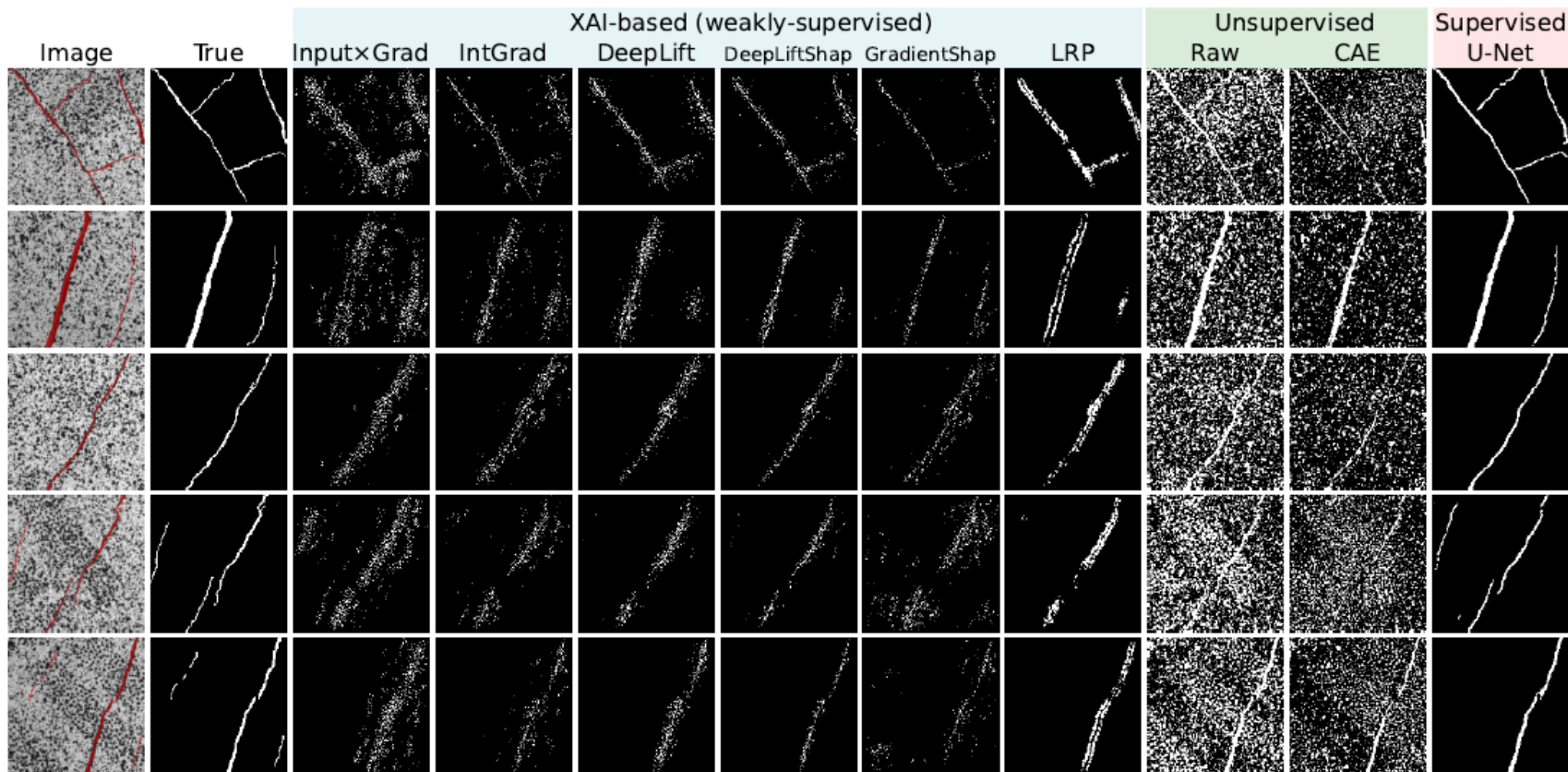




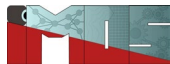
Proposed methodology:



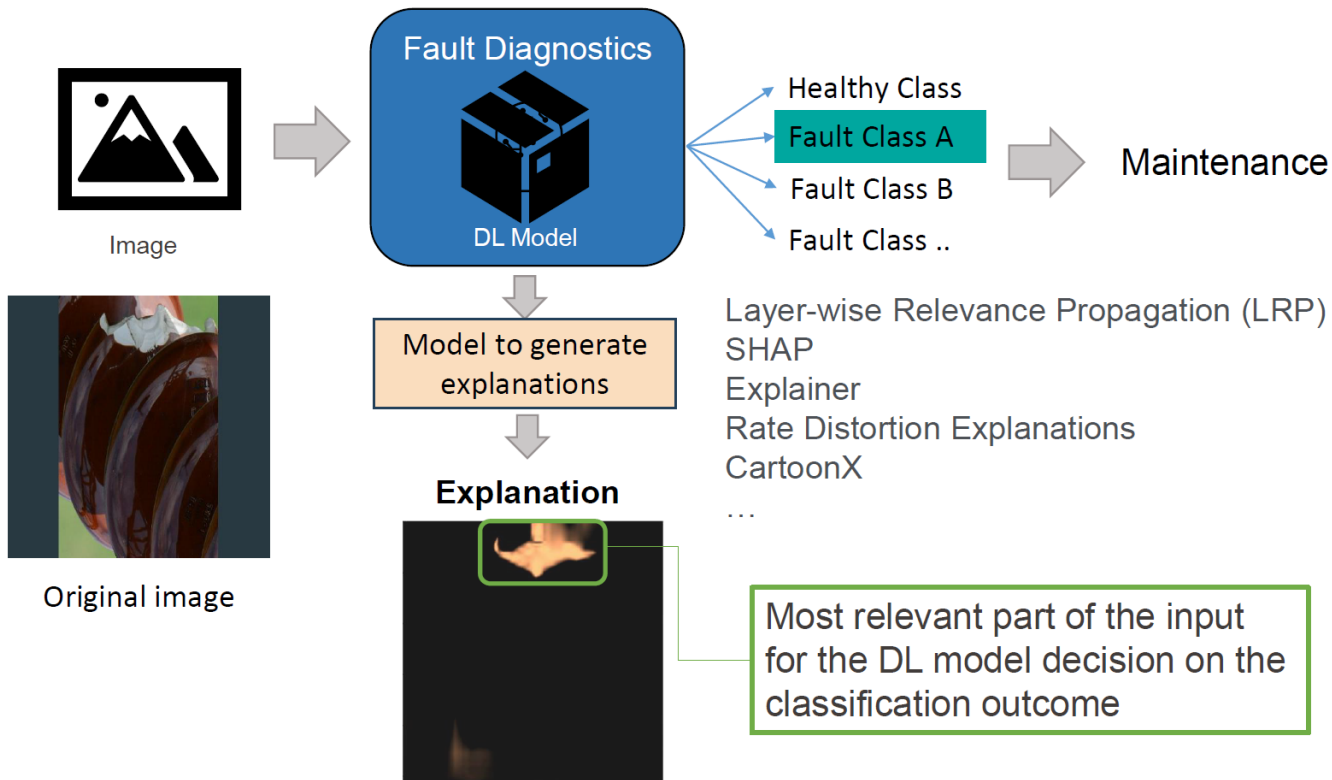
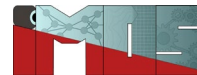
Visualization after binarization



Forest, F., Porta, H., Tuia, D., & Fink, O. (2023). From Classification to Segmentation with Explainable AI: A Study on Crack Detection and Growth Monitoring. Preprint

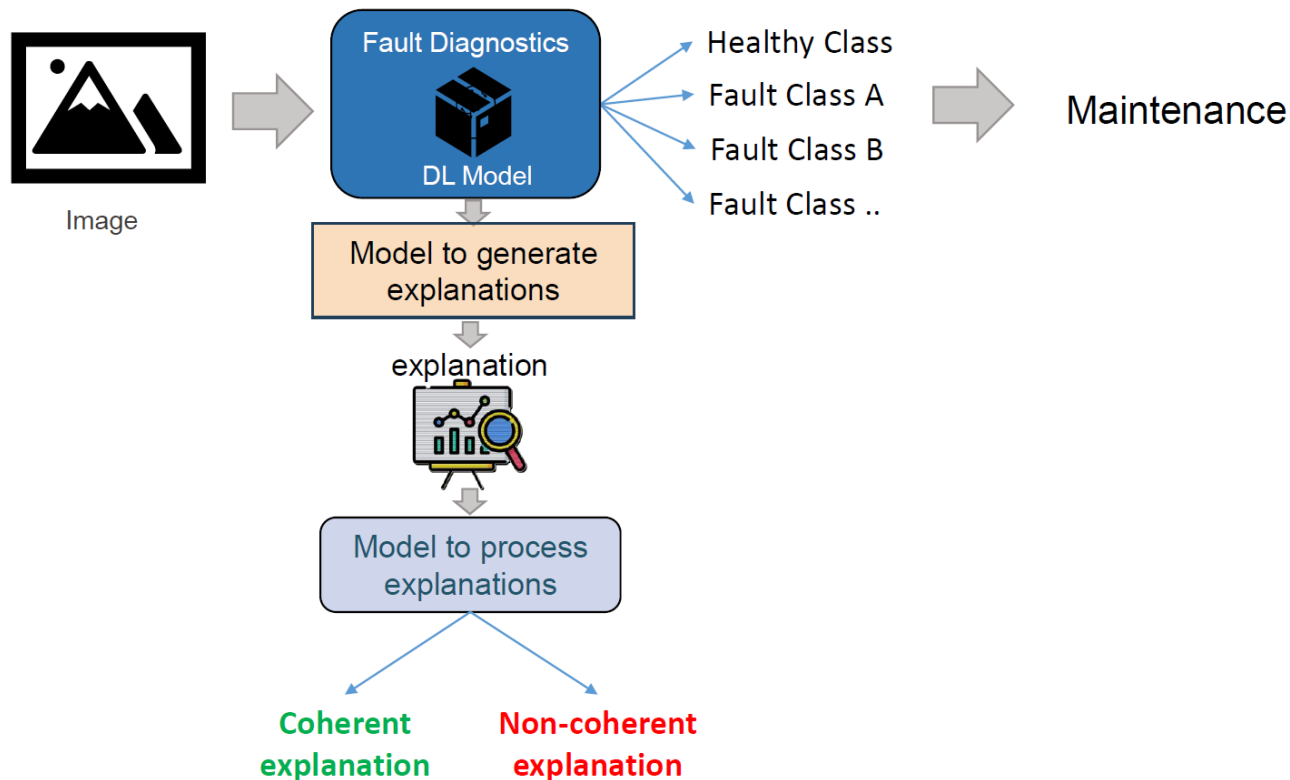
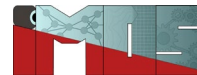


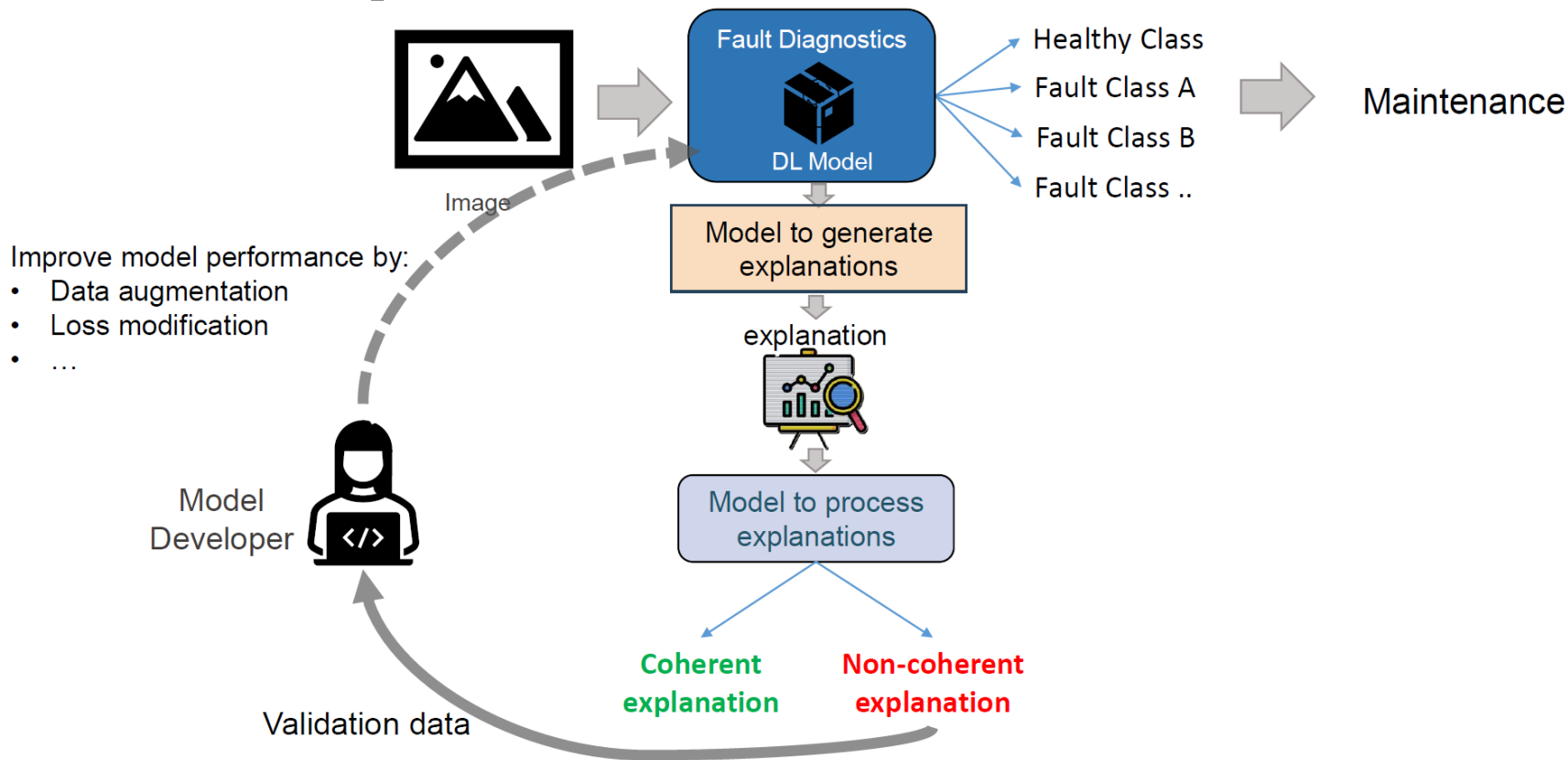
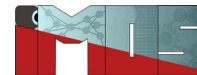
Automated explanation assessments

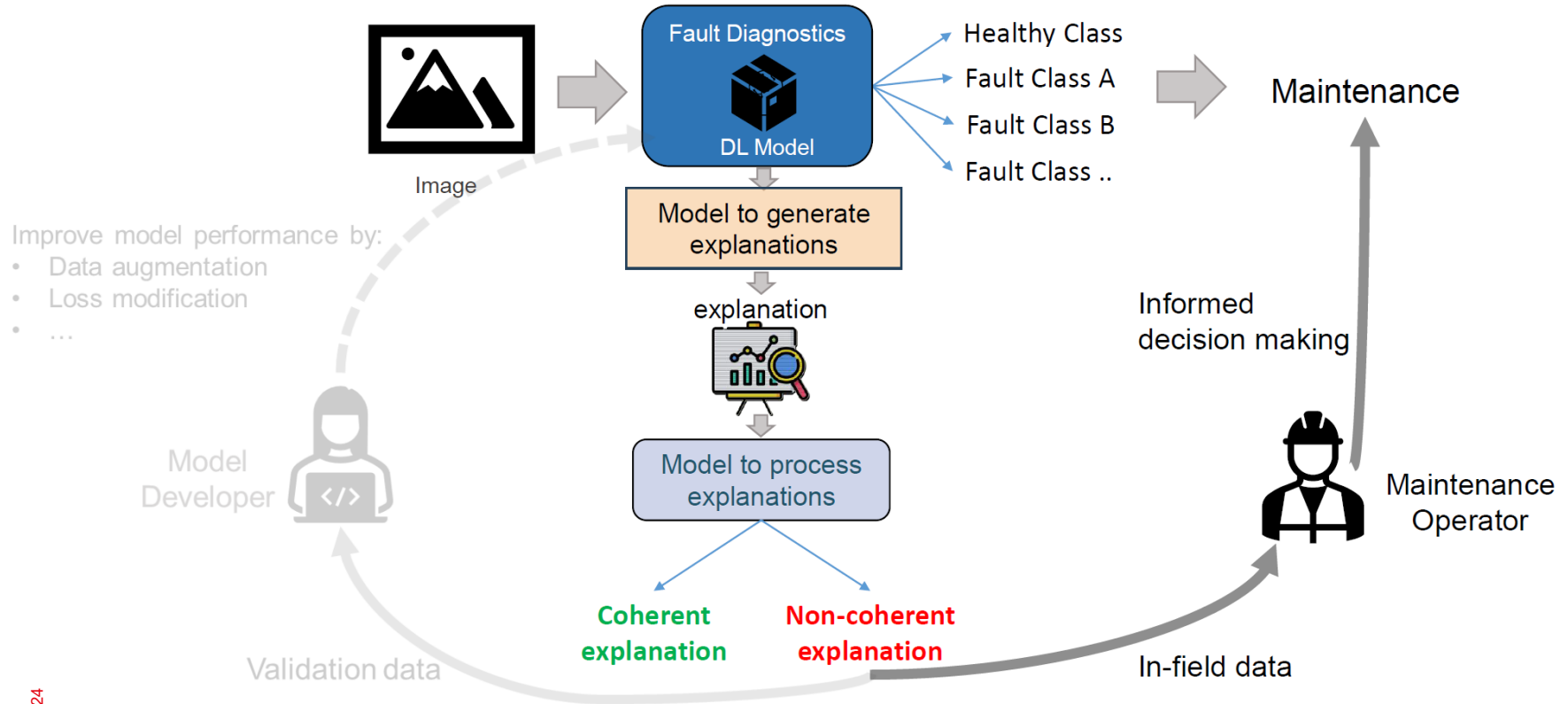
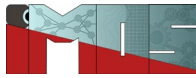


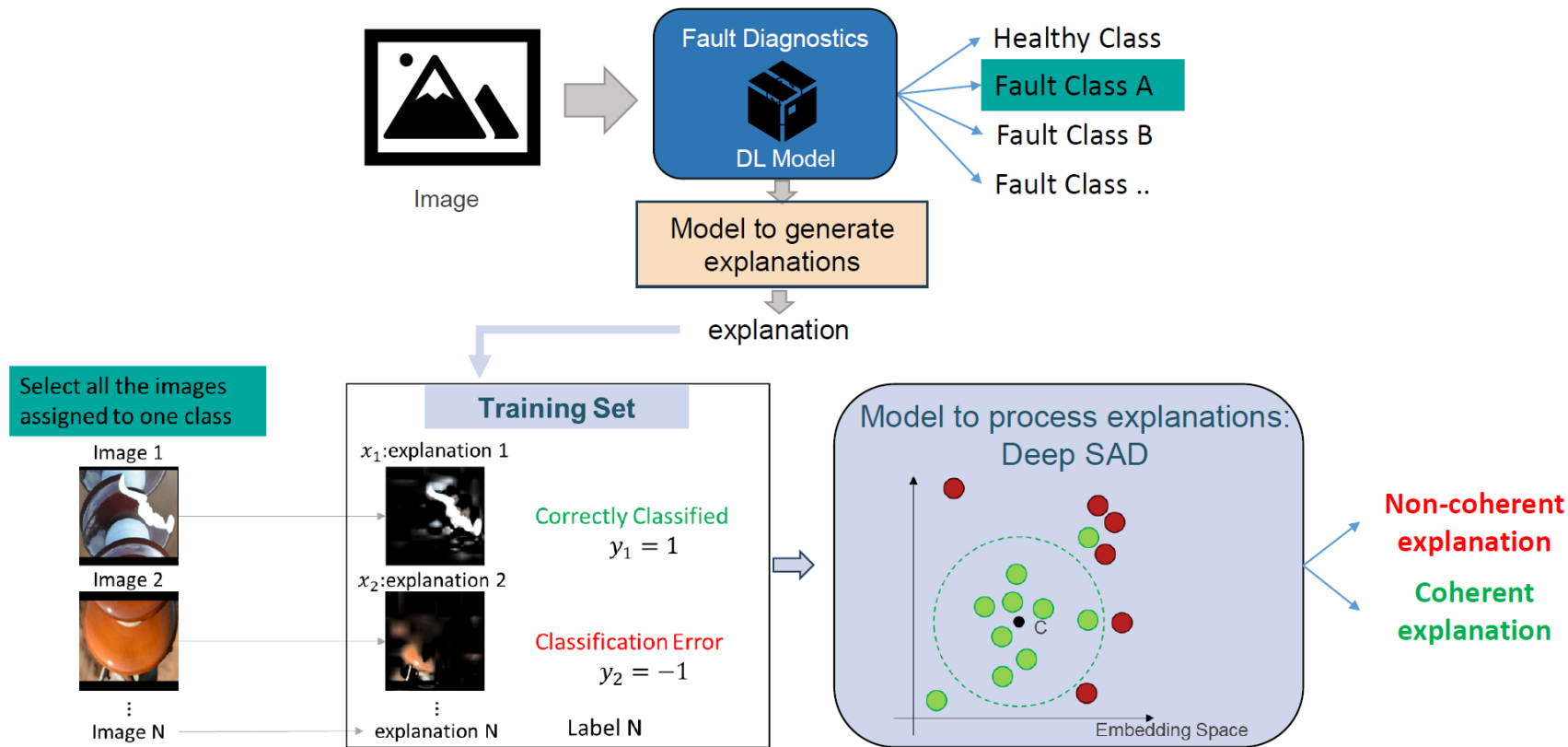
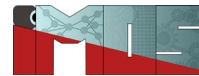
Floresale, G., P. Baraldi, E. Zio, O. Fink: Processing Explanations to Improve Performance and Enhance Trustworthiness of DL Models for Fault Diagnostics of Power Grid Components, in preparation

How can explanations be used?

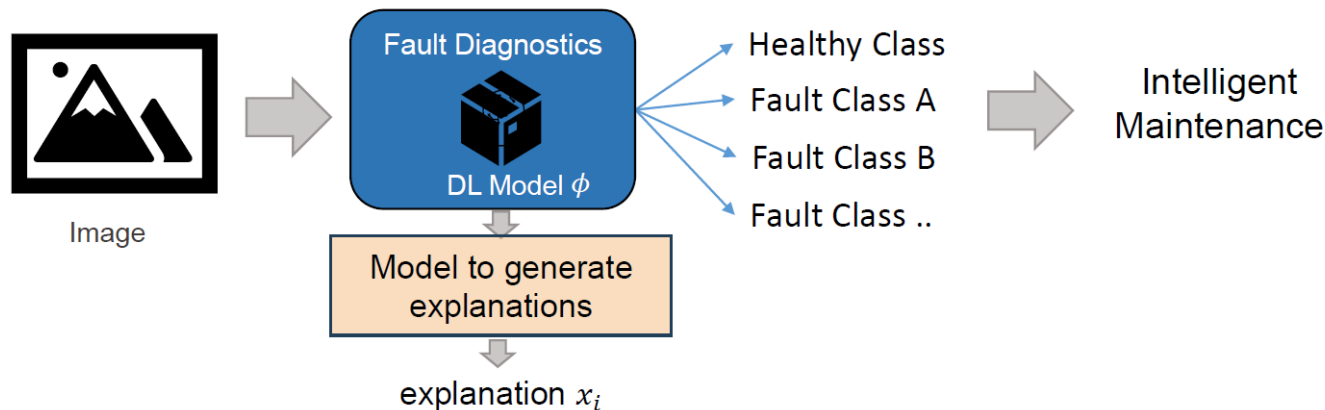






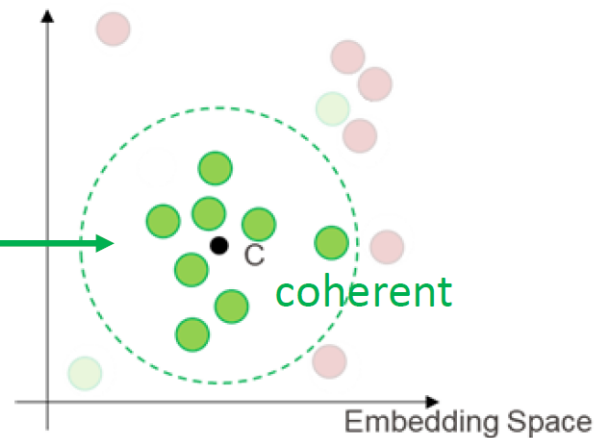


EPFL Proposed method: detecting unusual explanations



Embedding space definition: loss function

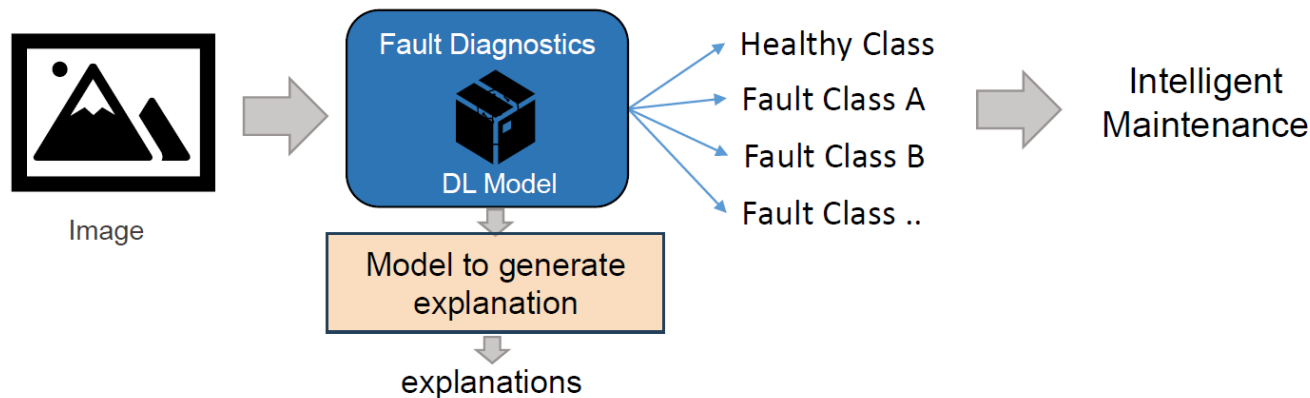
- Correct classifications: minimize the distance from the centre



$$\min_{\mathcal{W}} \frac{1}{n+m} \sum_{i=1}^n \|\phi(x_i; \mathcal{W}) - c\|^2$$

04.11.24

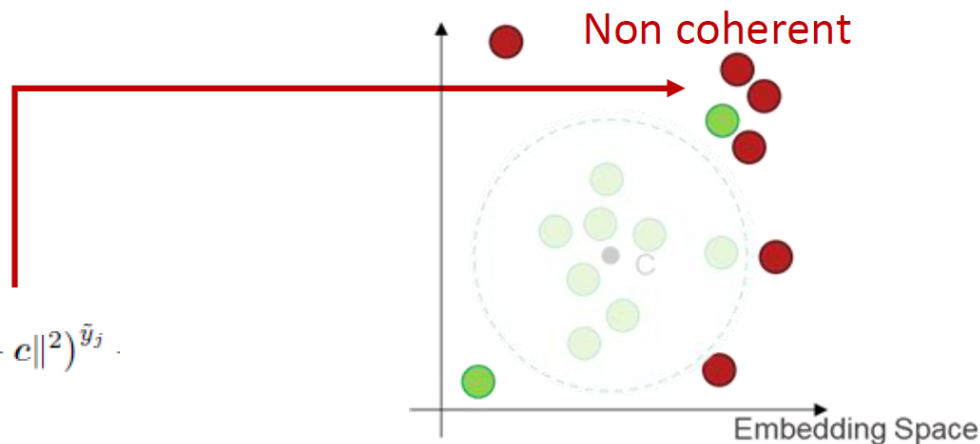
EPFL Proposed method: detecting unusual explanations



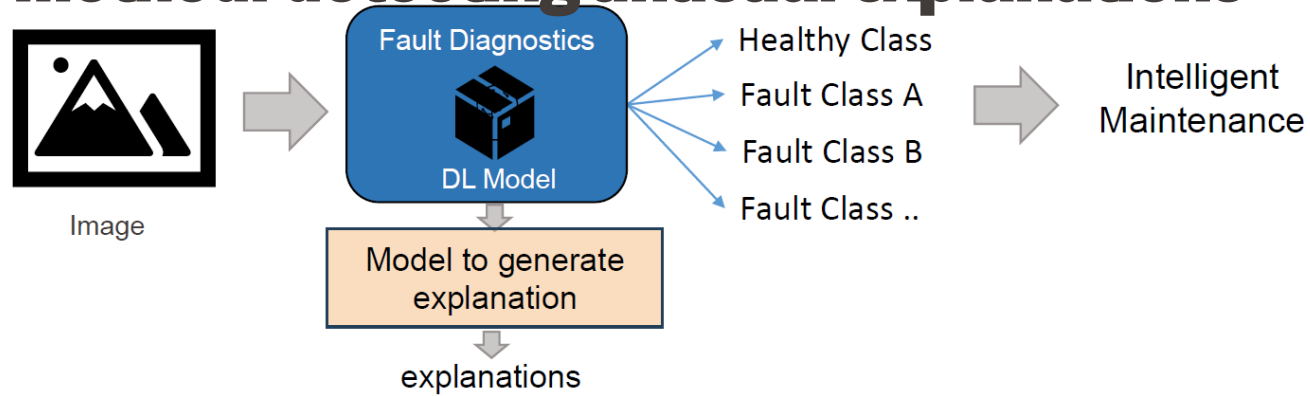
Embedding space definition: loss function

- Classifications errors: maximize the distance from the centre (hyperparameter η)

$$\min_{\mathcal{W}} \frac{1}{n+m} \sum_{i=1}^n \|\phi(x_i; \mathcal{W}) - c\|^2 + \frac{\eta}{n+m} \sum_{j=1}^m (\|\phi(\tilde{x}_j; \mathcal{W}) - c\|^2)^{\tilde{y}_j}.$$



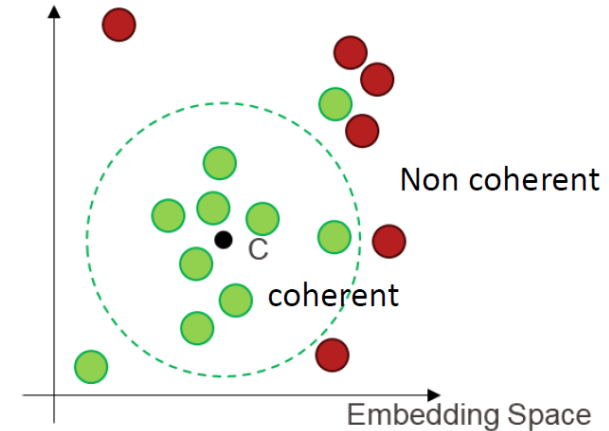
Proposed method: detecting unusual explanations

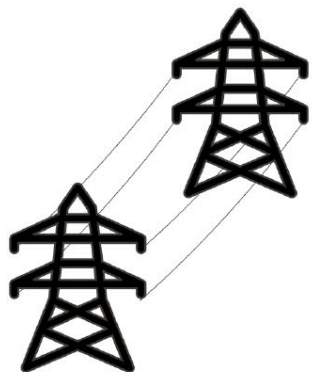
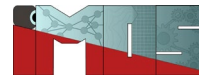


Embedding space definition: loss function

Regularization term to avoid overfitting
(hyperparameter λ)

$$\min_{\mathcal{W}} \frac{1}{n+m} \sum_{i=1}^n \|\phi(x_i; \mathcal{W}) - c\|^2 + \frac{\eta}{n+m} \sum_{j=1}^m (\|\phi(\tilde{x}_j; \mathcal{W}) - c\|^2)^{\tilde{y}_j} + \frac{\lambda}{2} \sum_{\ell=1}^L \|\mathcal{W}^{\ell}\|_F^2.$$





Power Grid



Critical Components:



Insulators

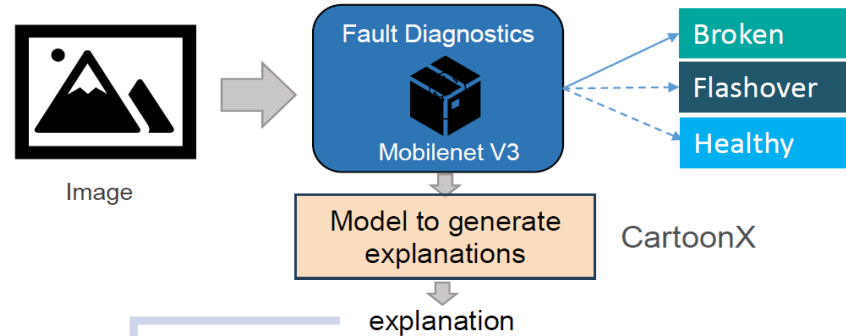
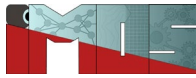


Drones

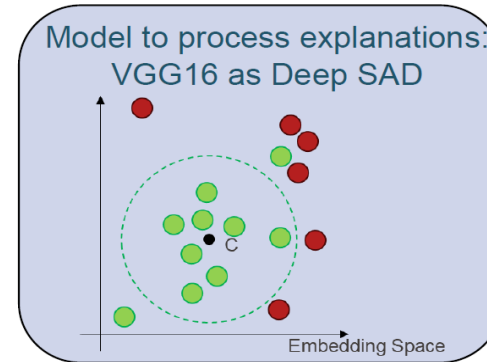
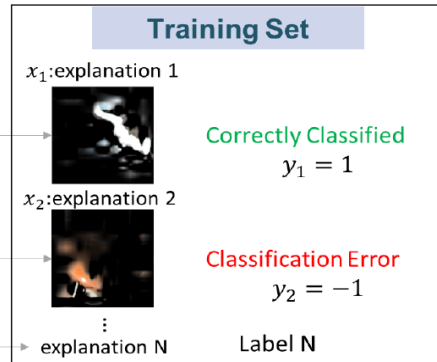


Shells' images

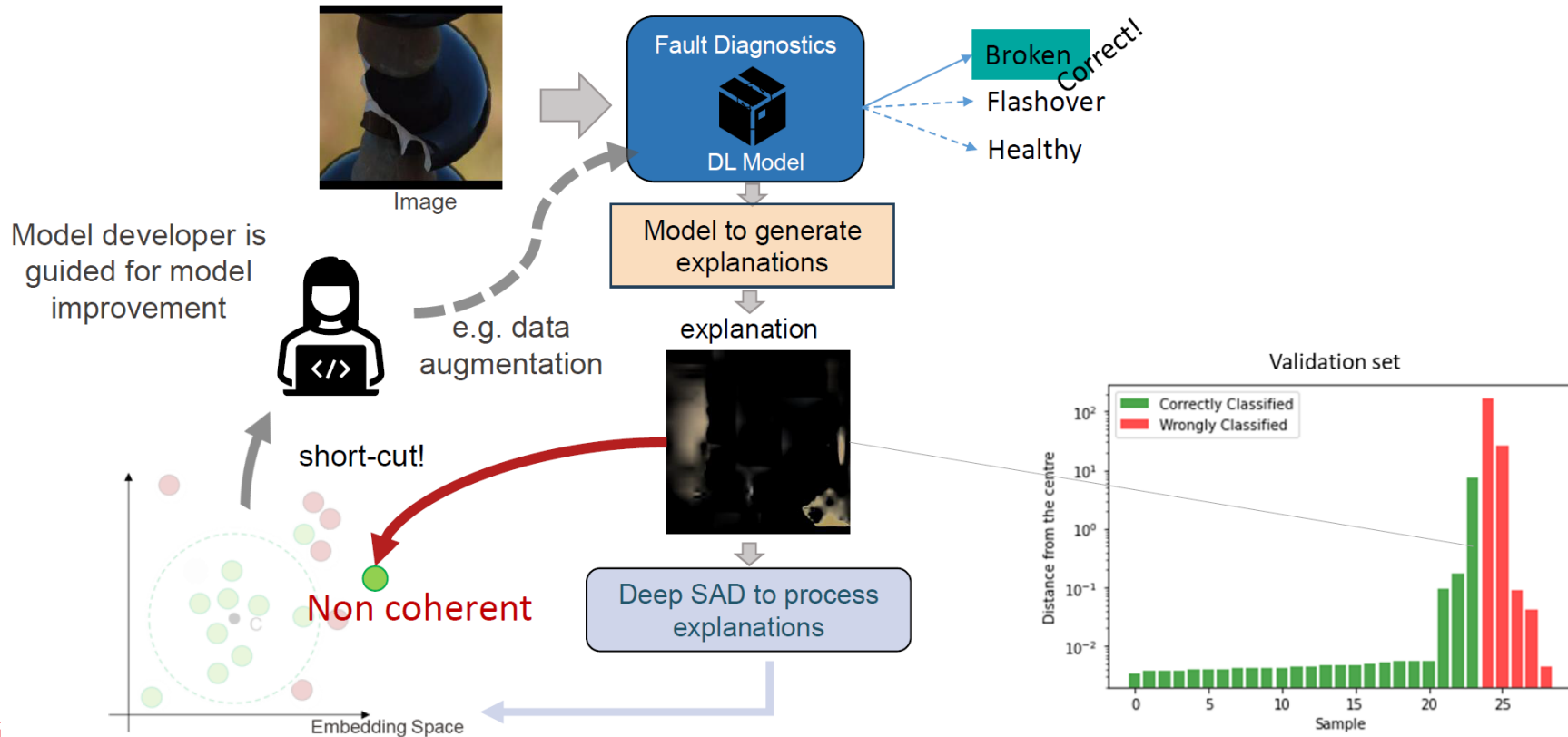
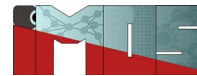
e.g. swiss power grid:
6700 km long → 12 000 pylons

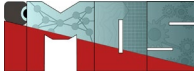


Select all the images assigned to one class

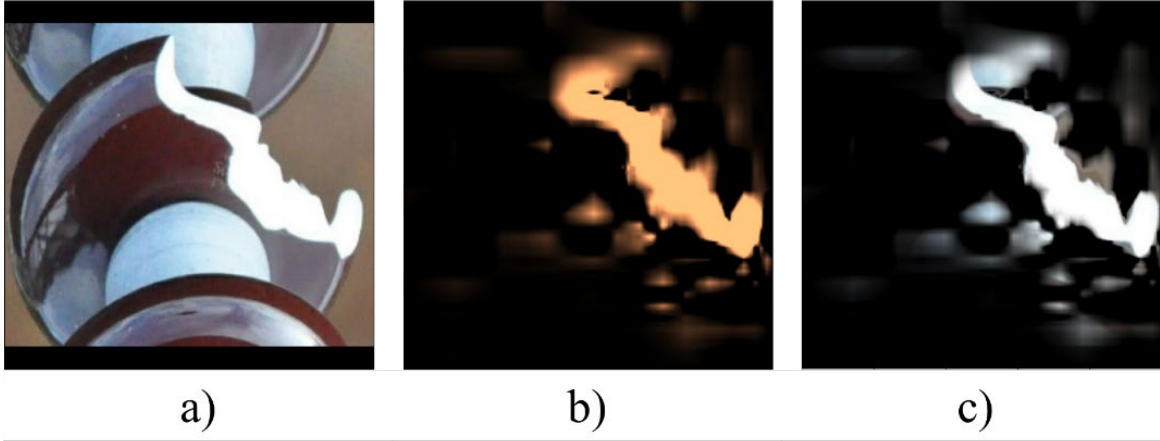


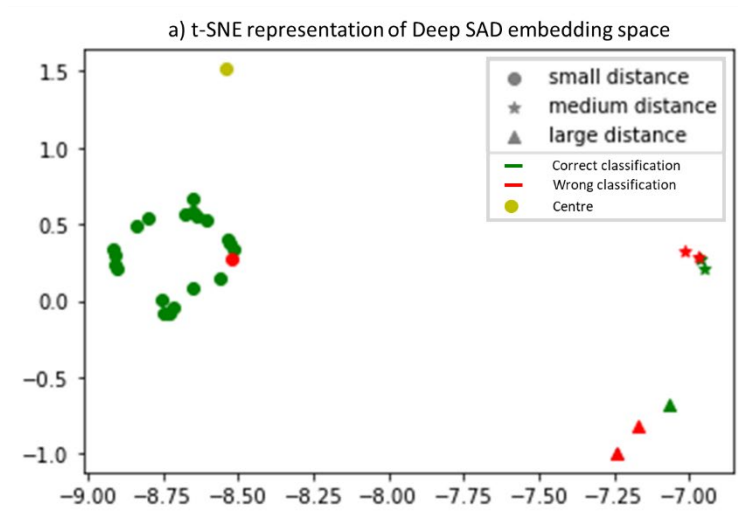
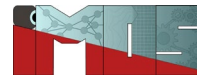
Non-coherent explanation
Coherent explanation



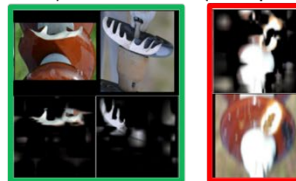


Example of one broken shell and its explanation

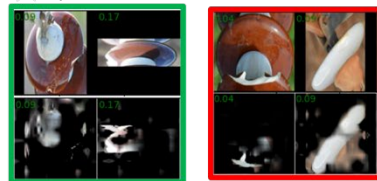




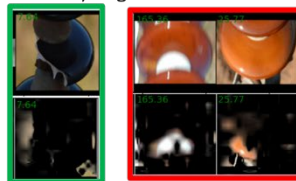
● b) small distance (examples)

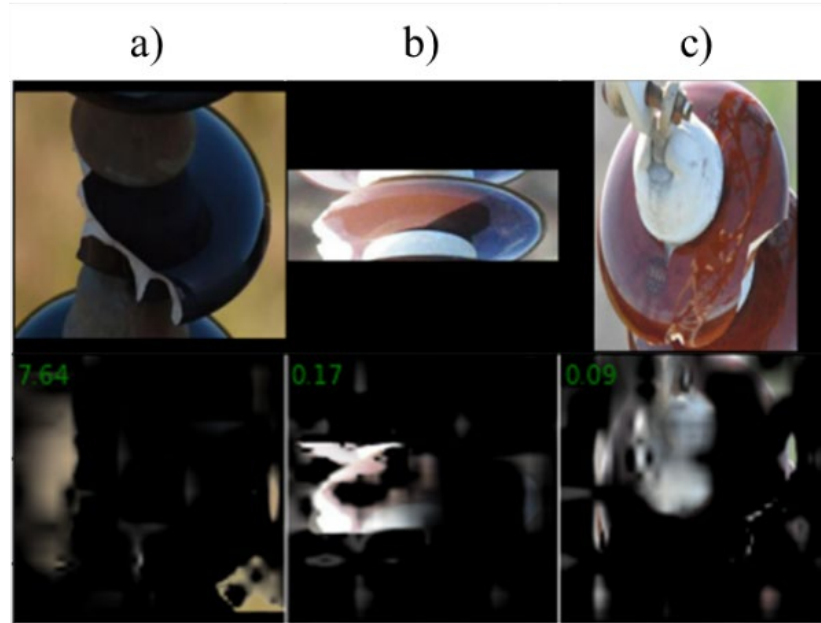
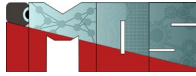


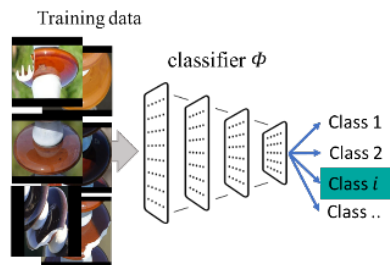
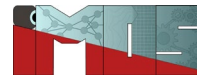
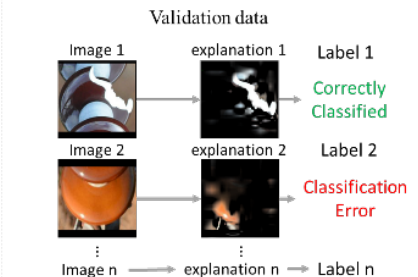
★ c) medium distance



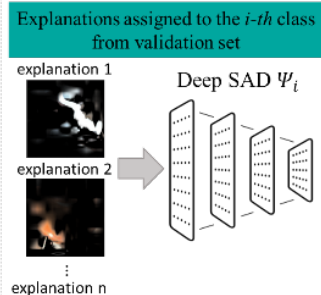
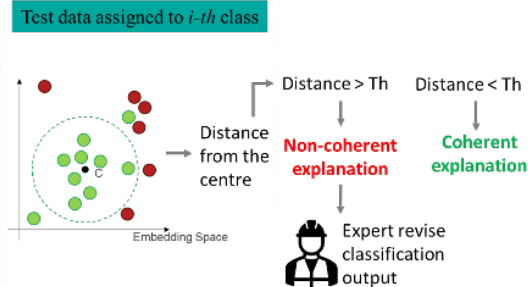
▲ d) large distance



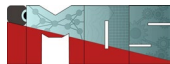


Step 1. Train the supervised classifier ϕ 

Step 2. Compute explanations and assign binary label for correct/incorrect classifications

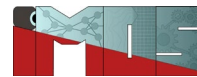
Step 3. Use labelled explanations to train Deep SAD model Ψ_i for the i -th classFor each i -th classStep 4. Apply Ψ_i to test data explanations and map them in the embedding space

Step 5. Apply threshold to spot non-coherent explanations and ask expert to revise them

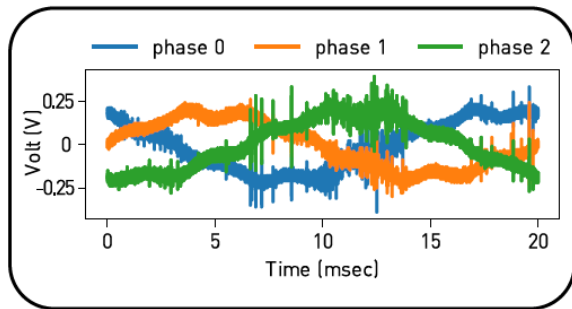


Example: Detection of Partial Discharge in Power Lines

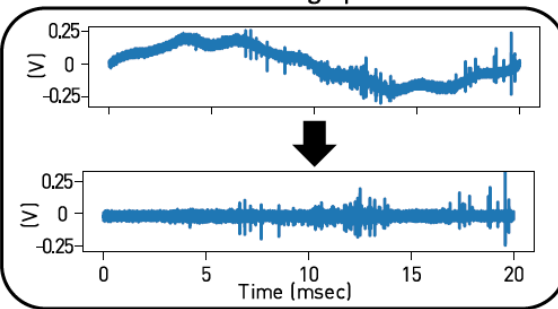
Interpretable Detection of Partial Discharge in Power Lines with Deep Learning → Framework



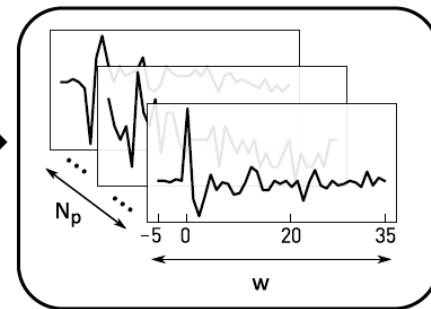
1 - Raw Data



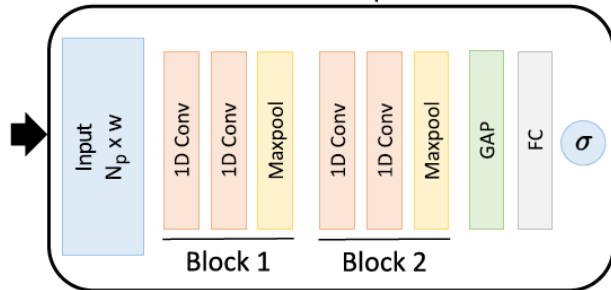
2 - Per Phase: High pass filter



3 - Per Phase: Extract Pulses



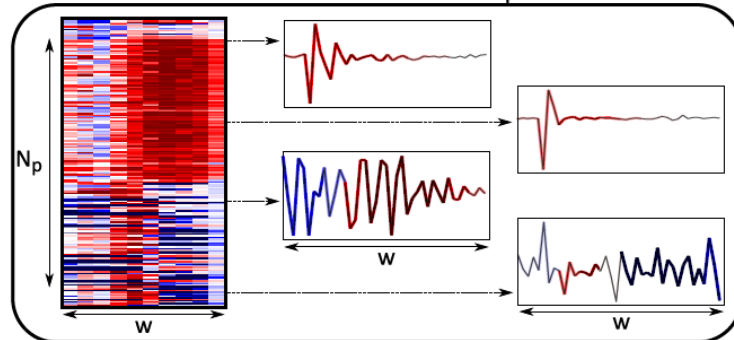
4 - Per Phase: Temporal CNN

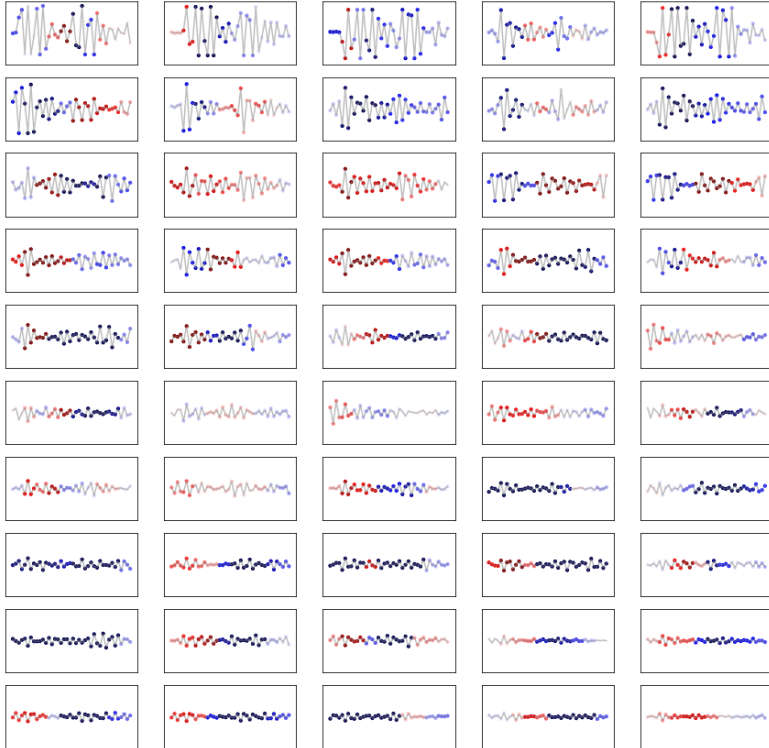
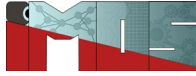


5 - 3-Phase Threshold

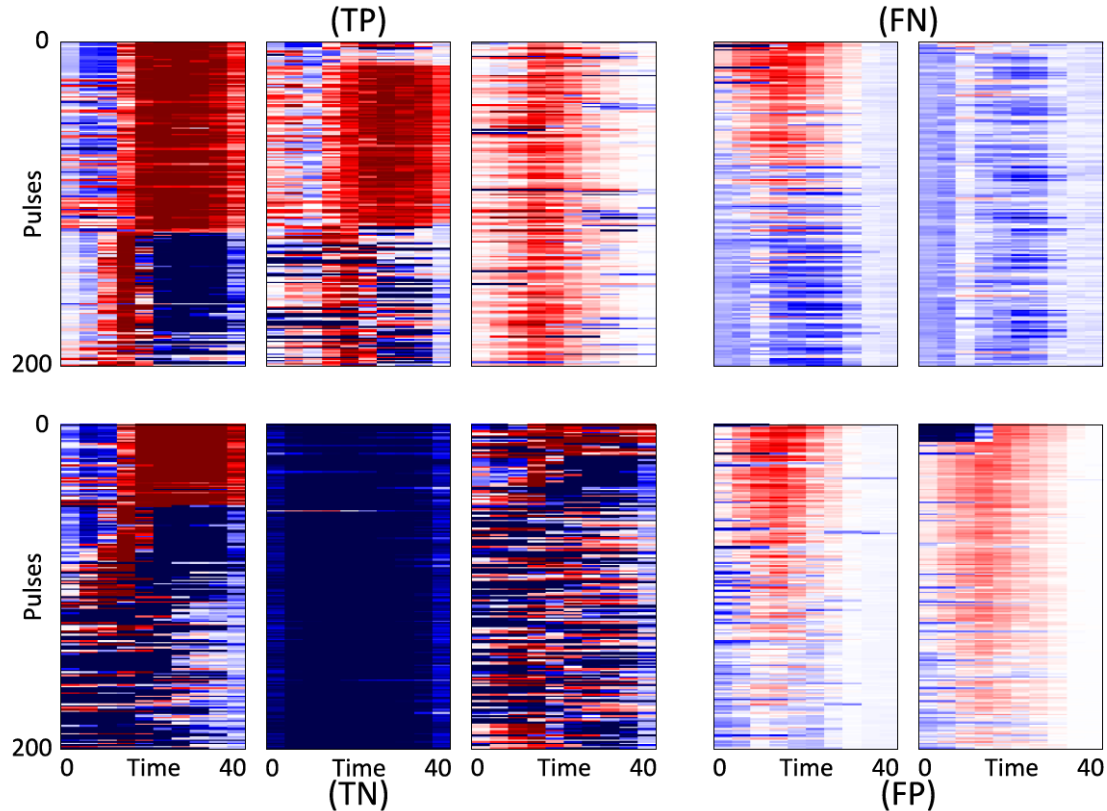
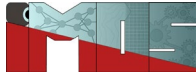


6 - Pulse Activation Map





Pulse Activation Maps (PAM)



Michau, Gabriel, Chi-Ching Hsu, and Olga Fink. "Interpretable Detection of Partial Discharge in Power Lines with Deep Learning." *Sensors* 21.6 (2021): 2154.