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Emergent collective behavior of active Brownian particles with visual perception†

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Systems comprised of self-steering active Brownian particles are studied *via* simulations for a minimal cognitive flocking model. The dynamics of the active Brownian particles is extended by an orientational response with limited maneuverability to an instantaneous visual input of the positions of neighbors within a vision cone and a cut-off radius. The system exhibits large-scale self-organized structures, which depend on selected parameter values, and, in particular, the presence of excluded-volume interactions. The emergent structures in two dimensions, such as worms, worm-aggregate coexistence, and hexagonally close-packed structures, are analysed and phase diagrams are constructed. The analysis of the particle's mean-square displacement shows ABP-like dynamics for dilute systems and the worm phase. In the limit of densely packed structures, the active diffusion coefficient is significantly smaller and depends on the number of particles in the cluster. Our analysis of the cluster-growth dynamics shows distinct differences to processes in systems of short-range attractive colloids in equilibrium. Specifically, the characteristic time for the growth and decay of clusters of a particular size is longer than that of isotropically attractive colloids, which we attribute to the non-reciprocal nature of the directed visual perception. Our simulations reveal a strong interplay between ABP-characteristic interactions, such as volume exclusion and rotational diffusion, and cognitive-based interactions and navigation.

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1 Introduction

Group formation and collective motion in form of swarms or flocks is a hallmark of living systems on length scales from bacteria and sperm to school of fish, flocks of birds, and animal herds.^{1–6} This behavior often emerges without central control and is rather governed by the response of individuals to the action of other group members or agents. Arising patterns and structures not only depend on the physical interactions between the various agents of an ensemble, but are often governed by a nonreciprocal information input, *e.g.*, by visual perception in case of birds and animals, processing of this information, and active response. Unravelling the underlying mechanisms and principles not only sheds light onto the behavior of biological systems, but provides concepts to design functional synthetic active systems, which are able to adapt to environmental conditions and perform complex tasks autonomously.⁷

In dry active matter systems—absence of hydrodynamic interactions—self-propulsion and volume-exclusion lead to motility-induced phase separation (MIPS), as demonstrated in

simulations of systems of active Brownian particles (ABPs)^{4,8–15} and in experiments.^{14,16–19} The presence of an embedding fluid, implying long-range hydrodynamic interactions, can suppress MIPS,^{20,21} but can also give rise to large scale collective effects^{22–26}—which depend on the presence or absence of thermal fluctuations²¹—and swarming motility.²⁷

Vision is the primary sensor for birds, and, as is established by now, a bird in a flock responds mainly to positions and motion of its seven nearest neighbors.^{1,28–30} The Vicsek model for flocking accounts for such interactions in a coarse-grained manner by a velocity alignment mechanism between nearby neighbors.³¹ By varying the mean density, the strength of the reorientational noise, and the interaction radius, a wide spectrum of structures is obtained, such as global polar order or flocks.^{32–34} This suffices to build up long-range orientational order in two dimensions^{35,36} and giant density fluctuations.²

Alternative approaches for emergent collective behaviors without velocity alignment have been proposed, relying on repulsion-attraction interactions,³⁷ elasticity-based interactions,³⁸ visual interactions with³⁰ and without coalignment,^{39,40} and aggregation based on chemical gradients.⁴¹ Not all models yield necessarily flocking, but particular phases and collective motion emerge, which are absent in “dumb” ABP-type systems, such as “vision”-based aggregation and cluster formation, and worm-like structures as in ref. 39.

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In this article, we study structure formation in systems of self-steering particles by applying the minimal cognitive flocking model proposed in ref. 39. Here, ABPs are additionally equipped with vision-based sensing, which allows them to detect the instantaneous positions of neighboring ABPs within a vision cone (VC) and a short-distances cutoff radius. The relaxation of their propulsion directions is governed by a redirection force of limited magnitude, implying a limited maneuverability, toward the centre of mass of the detected particles, which is in competition with rotational noise. Since the particles are able to sense and respond to their neighbors, we denote them as intelligent active Brownian particles (iABPs). The iABPs possess no memory and lack the velocity alignment of the Vicsek model. As an extension to previous studies,³⁹ we take into account excluded-volume interactions between the iABPs and solve the underdamped equations of motion in the presence of thermal noise for their translational motion.

Our simulations reveal various additional phases compared to those already presented in ref. 39, which originate from excluded-volume interactions, such as hexagonally close-packed aggregates, fluid-like aggregates, worms, worm-aggregate coexistence, and dilute and diffuse clusters at different parameters sets. The strength of the response to the visual signal, the vision angle, packing fraction, cutoff range, and active propulsion determine the location and extent of these phases in the phase diagram.

Moreover, our analysis of the cluster-growth process from a dilute isotropic state *via* nucleation and merging of smaller clusters into larger ones exhibits distinct difference to the process for systems of short-range attractive passive colloids.⁴² Specifically, the critical exponent of the dependence of the characteristic time for cluster growth on the number of particles in the cluster is larger than that of the passive colloidal system. The implemented perception rule slows down clustering and cohesion, which is attributed to the nonreciprocal visual interactions and the resulting directed motion.

2 Model and simulation approach

We consider a two-dimensional systems of N perceptive and responsive “intelligent” active Brownian particles (iABPs) at positions $\mathbf{r}_i(t)$ ($i = 1, \dots, N$) at time t , which are propelled by the active force $\mathbf{F}_i^a(t) = \gamma v_0 \mathbf{e}_i(t)$ with the velocity v_0 along the direction $\mathbf{e}_i(t)$. Their equations of motion are given by⁴³

$$m\ddot{\mathbf{r}}_i = -\gamma\dot{\mathbf{r}}_i + \gamma v_0 \mathbf{e}_i + \mathbf{F}_i + \mathbf{\Gamma}_i(t), \quad (1)$$

with the mass m , the friction coefficient γ , and the transitional Gaussian white noise $\mathbf{\Gamma}_i(t)$ of zero mean and the second moments $\langle \mathbf{\Gamma}_{\alpha i}(t) \mathbf{\Gamma}_{\beta j}(t') \rangle = 2\gamma k_B T \delta_{ij} \delta_{\alpha\beta} \delta(t - t')$ ($\alpha, \beta \in \{x, y\}$). The forces $\mathbf{F}_i$ account for excluded-volume interactions between the iABPs in terms of the short-range, truncated, and shifted Lennard-Jones potential

$$U(r) = \begin{cases} 4\varepsilon \left(\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right) + \varepsilon, & r \leq 2^{1/6} \sigma, \\ 0, & \text{otherwise} \end{cases} \quad (2)$$

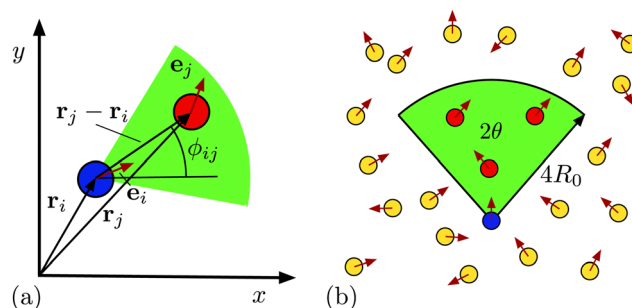


Fig. 1 (a) Graphical representation of the orientations $\mathbf{e}_i$ and $\mathbf{e}_j$ of the particles at the positions $\mathbf{r}_i$ and $\mathbf{r}_j$, and the definition of the angle ϕ_{ij} of the connecting vector with the x axis. (b) Schematics showing the vision cone of the blue particle with the vision angle θ and the cutoff radius $4R_0$. The vision cone is colored in green and the blue particle interacts with particles (red) within this cone.

where $r = |\mathbf{r}|$ is the distance between two particles, σ represents their diameter, and ε is the energy determining the strength of repulsion. Individual perception and noise lead to a change of the propulsion direction of the iABPs. Representing the propulsion directions in terms of polar coordinates, $\mathbf{e}_i = (\cos \phi_i, \sin \phi_i)^T$, yields the equations of motion for the angles ϕ_i

$$\dot{\phi}_i = \frac{\Omega}{N_{c,i}} \sum_{j \in VC} e^{-r_{ij}/R_0} \sin(\phi_{ij} - \phi_i) + A_i(t), \quad (3)$$

where $N_{c,i}$ is the number of iABPs in the vision cone (VC),

$$N_{c,i} = \sum_{j \in VC} e^{-r_{ij}/R_0}. \quad (4)$$

The A_i are Gaussian and Markovian stochastic processes with zero mean, the second moments $\langle A_i(t) A_j(t') \rangle = 2D_R \delta_{ij} \delta(t - t')$, and the rotational diffusion coefficient D_R . The sum in eqn (3) describes the preference of an iABP to move toward the iABPs in its “vision” cone (VC), with Ω the maneuverability strength. In a vision-based picture, the sum corresponds to the projection of the positions of all N_c particles within the VC onto the “retina” of particle i , with ϕ_{ij} the polar angle of the vector $(\mathbf{r}_j - \mathbf{r}_i)/|\mathbf{r}_j - \mathbf{r}_i| = (\cos \phi_{ij}, \sin \phi_{ij})^T$ between particle i and j .^{30,39} The condition for particles j to lie within the vision cone of particle i is

$$\frac{\mathbf{r}_i - \mathbf{r}_j}{|\mathbf{r}_i - \mathbf{r}_j|} \cdot \mathbf{e}_i \geq \cos(\theta), \quad (5)$$

where θ —denoted as vision angle in the following—is half of the opening angle of the vision cone and $\mathbf{e}_i$ its orientation.³⁹ The exponential function limits the range of the interaction with the characteristic length R_0 . In addition, we limit the vision range to $|\mathbf{r}_i - \mathbf{r}_j| \leq 4R_0$ and treat all further apart particles as invisible (Fig. 1).

3 Parameters

In the simulation, we measure energies in units of the thermal energy $k_B T$, lengths in units of σ , and time in units of



$\tau = \sqrt{m\sigma^2/(k_B T)}$. The activity of the iABPs is characterized by the Péclet number

$$\text{Pe} = \frac{\sigma v_0}{D_T}, \quad (6)$$

where $D_T = k_B T/\gamma$ is the translational diffusion coefficient. Explicitly, we choose $\gamma = 10^2 \sqrt{mk_B T/\sigma^2}$ and the rotational diffusion coefficient $D_R = 8 \times 10^{-2}/\tau$, which yields the relation $D_T/(\sigma^2 D_R) = 1/8$. We set $\varepsilon/k_B T = (1 + \text{Pe})$ to ensure a nearly constant iABP overlapping even at high activities. The iABP density is measured in terms of the global packing fraction $\Phi = \pi\sigma^2 N/(4L^2)$, with L the length of the quadratic simulation cell. Periodic boundary conditions are applied and the equations of motion (1) are solved with a Velocity-Verlet-type algorithm suitable for stochastic systems,⁴⁴ with the time step $\Delta t = 10^{-3}\tau$. We perform 10^6 equilibration time steps and collect data for additional 10^7 steps. For certain averages, up to 10 independent realizations are considered.

For ABPs, the above choice of the friction and rotational diffusion coefficients ensures that inertia does not affect MIPS. As shown in ref. 45, for the ratio $M = mD_R/\gamma = 8 \times 10^{-4}$ and the considered Péclet numbers, we do not expect MIPS. In case of emerging dense clusters, the position of phase boundaries seems to depend slightly on the presence of inertia. This aspect deserves a more detailed analysis.

If not indicated otherwise, the number of particles is $N = 625$, the characteristic radius $R_0 = 1.5\sigma$, $\Omega/D_R = 62.5$, and the opening of the vision cone $\pi/24 \leq \theta \leq \pi/2$.

Initially, the iABPs are typically arranged on a square lattice, with iABPs distances equal to their diameter σ in the center of the periodic simulation square.

4 Structural and dynamical properties

4.1 Low packing fraction

4.1.1 Phases and phase diagrams. Fig. 2 displays snapshots of emerging structures for various vision angles at the very small packing fraction $\Phi = 0.00785$, indicating an aggregate, mobile worms, worm-aggregate coexistence, and a dilute phase.

To characterize the various phases, we calculate the cluster-size distribution function^{46,47}

$$\mathcal{N}(n) = \frac{1}{N_N} n p(n), \quad (7)$$

which is the average fraction of particles in clusters of size n , and $p(n)$ is the number of clusters of size n . The distribution is normalized such that $\sum_n \mathcal{N}(n) = 1$, which determines N_N . The distribution function $\mathcal{N}(n)$ is sometimes referred to as weighted cluster-size distribution function due to the factor n .⁴⁸ We use a distance criterion to define a cluster, where an iABP belongs to a cluster when its distance to another iABP of the cluster is within a radius σ_0 . Since we mainly focus here on dilute systems and worms, we set $\sigma_0 = 2\sigma$.

Fig. 3 presents cluster-size distribution functions for various vision angles. They are fitted by

$$\mathcal{N}(n) = A n^{-\mu} e^{-n/n_0} \quad (8)$$

a functional form observed in various cluster-forming processes.^{27,49} The function interpolates between the power-law decay found for percolating clusters and an exponential suppression of larger clusters. The respective fit parameters μ and n_0 are summarized in Table 1. As long as the vision angle $\theta \lesssim \pi/10$, decays exponentially with a characteristic cluster size $n_0 \approx 1$. For $\theta > \pi/10$, a power-law decay at small n appears, followed by an exponential cut-off for larger clusters. This indicates longer-range correlations in the system, but no large clusters.^{27,46} In fact, the average cluster sizes, represented by the characteristic value n_0 , are rather small and the power-law regime is negligibly small for $\theta \lesssim \pi/8$. A significant power-law regime exists for $\theta = \pi/6$ only; the exponent $\mu = 0.34$ is related to the break-up and merging process of worms, a process which requires further study in the future.

To classify the various phases of Fig. 2, we calculate the radius of gyration,

$$\langle R_g^2 \rangle = \frac{1}{n} \sum_{i=1}^n \langle (r_i - r_{\text{cm}})^2 \rangle, \quad (9)$$

of the cluster of size n , where r_{cm} is the center-of-mass position of the cluster. In order to avoid counting configuration which

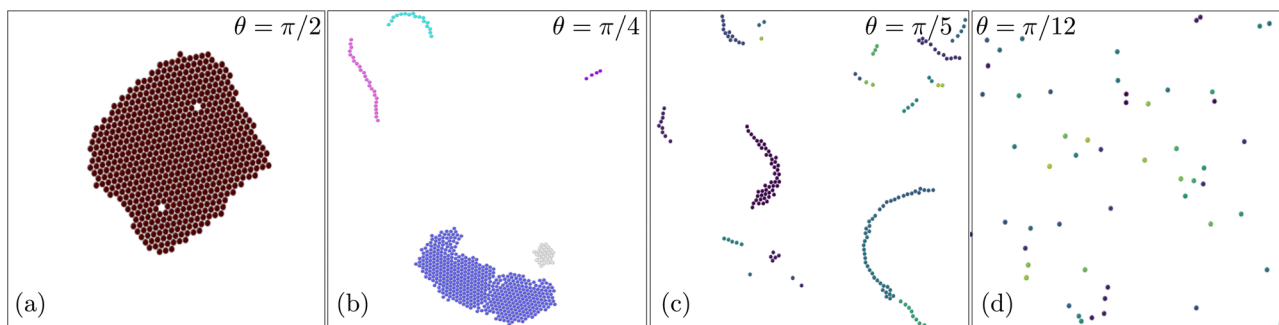


Fig. 2 Snapshot of iABP structures for various vision angles: (a) hexagonal-closed packed structure, $\theta = \pi/2$, (b) worm-aggregate coexistence, $\theta = \pi/4$, (c) worms, $\theta = \pi/5$, and (d) dilute fluid, $\theta = \pi/12$. The Péclet number is $\text{Pe} = 200$, the strength of the perceptive interaction $\Omega/D_R = 62.5$, and the packing fraction $\Phi = 7.85 \times 10^{-3}$. The various colors represent different clusters or worms. See movies M1 and M2 (ESI†).



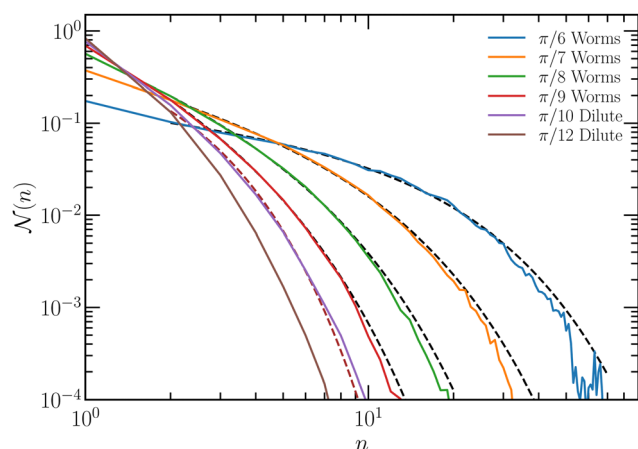


Fig. 3 Cluster-size distribution function $\mathcal{N}(n)$ as a function of the cluster size n at $Pe = 200$, $\Omega/D_R = 62.5$, and packing fraction $\Phi = 7.85 \times 10^{-3}$. The dashed lines are fits of the function $\mathcal{N}(n)$ of eqn (8) with the parameters of Table 1.

Table 1 Values of the fit parameters μ and n_0 of the function eqn (8) for various vision angles

θ	$\pi/6$	$\pi/7$	$\pi/8$	$\pi/9$	$\pi/10$
μ	0.34	0.8	1.1	1.4	0
n_0	13.4	7.1	3.8	2.3	1

occur very rarely, we only consider realizations which appear in more than 1% of recorded configurations. As displayed in Fig. 4, the data collapse on two branches with the distinct power laws $\langle R_g^2 \rangle \sim n^{1.4}$ and n^1 , respectively, for the various vision angles. All data points for $\theta \lesssim \pi/5$ are approximately on the line with the exponent $n^{1.4}$, whereas the radii of gyration for

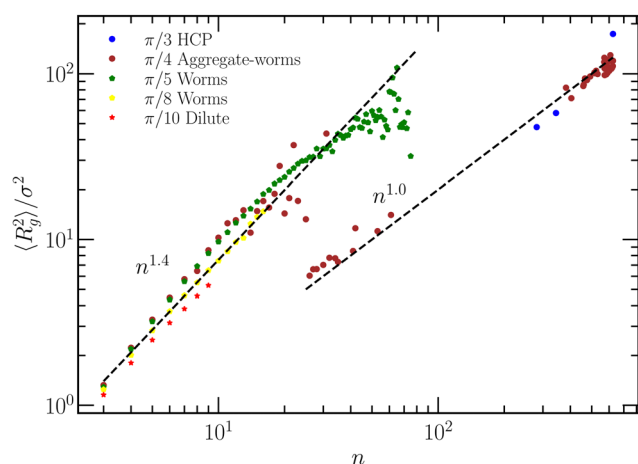


Fig. 4 Radius of gyration as a function of the cluster size at $Pe = 200$, $\Omega/D_R = 62.5$, and the packing fraction 7.85×10^{-3} for various vision angles. The two distinct power-law regimes characterize worms ($n^{1.4}$) and aggregates (n). Worm-aggregate coexistence is indicated by a crossover from the worm power-law at smaller clusters to the aggregate one at larger clusters.

$\theta = \pi/3$ exhibit a linear increase with n . The system for $\theta = \pi/4$ shows different features for $n \lesssim 20$ and $n \gtrsim 20$.

For a disc-like dense packing of n iABPs, its radius, r , increases as $r^2 \sim n$. Hence, the linear increase of $\langle R_g^2 \rangle$ is consistent with a dense aggregate of iABPs. Thus, we expect dense clusters of iABPs for $\theta = \pi/3$ and $\pi/4$ for larger n , which is confirmed by visual inspection (Fig. 2(a)). Larger exponents correspond to more open structures. In particular, a linear arrangement of iABPs in a rod-like manner would correspond to $\langle R_g^2 \rangle \sim n^2$. Visual inspection indeed shows the presence of wormlike structures, which, however, are not rodlike, but rather curvilinear, hence, $\langle R_g^2 \rangle \sim n^\alpha$ with $\alpha < 2$ (Fig. 2(c)). In the system with $\theta = \pi/4$, wormlike structures and dense aggregates coexist (Fig. 2(b)).

Based on the radius-of-gyration results and the cluster-size distributions, we construct the phase diagram of Fig. 5 for various Pe and Ω . Four phases can be clearly identified: (i) a dilute phase ($\theta \lesssim \pi/10$ in Fig. 5(a)), (ii) a phase of mobile worms for a narrow range of somewhat larger θ , (iii) a coexistence of worms and aggregates, denoted as worm-aggregate phase, and (iv) a phase with hexagonally closed-packed aggregates, denoted as HCP phase, at large θ .

In the dilute phase, $\theta \lesssim \pi/10$, the system is homogeneous and isotropic. The vision angle and range are too small to allow for persistent sensing of neighboring particles, and the noise dominates over maneuverability. For the parameters of Fig. 5(a), this behavior depends only weakly on Pe , with an extension of the dilute phase toward somewhat larger θ at larger Péclet numbers. As θ increases, worms appear, where an iABP is trailed by several others. Similar structures have previously been observed in ref. 39 for pointlike particles. As indicated in Fig. 2 and 4, the worms can be quite long, comprising up to 80 iABPs. Here, the truncated perception cone is sufficiently large to allow for a persistent tracking and chain formation. The directional dynamics of the worm is determined by the leading iABP, since it does not see other iABP and the orientational dynamics is governed by its rotational noise. The stretch of the worm phase depends on the Péclet number and extends to larger θ at higher Pe . Even wider vision cones lead to formation of aggregates, which coexist with worms—the worm-aggregate phase. The presence of a wider vision cone implies a preferred motion of more particles toward each other, and the emergent locally higher density stabilizes the clusters. Again, the extent of this phase depends on Pe . Finally, a densely packed aggregate is obtained for large θ , comprising essentially all iABPs. Our analysis shows that the local structure in the aggregate is hexagonally closed packed (Fig. S4, ESI†). iABPs always discern sufficiently many neighbors to stay close to them. Only for large Pe , iABPs are able to escape, trailing other particles, and form worms.

To investigate possible finite-size effects, we consider also a larger system of $N = 10^3$ iABPs at the same density, for $Pe = 200$ and $\theta = \pi/4$, where worm-aggregate coexistence is observed in Fig. 5. As displayed in Fig. S7 (ESI†), we obtain the same structures, with the sizes of aggregates and worms increasing proportionally with the overall particle number N . This



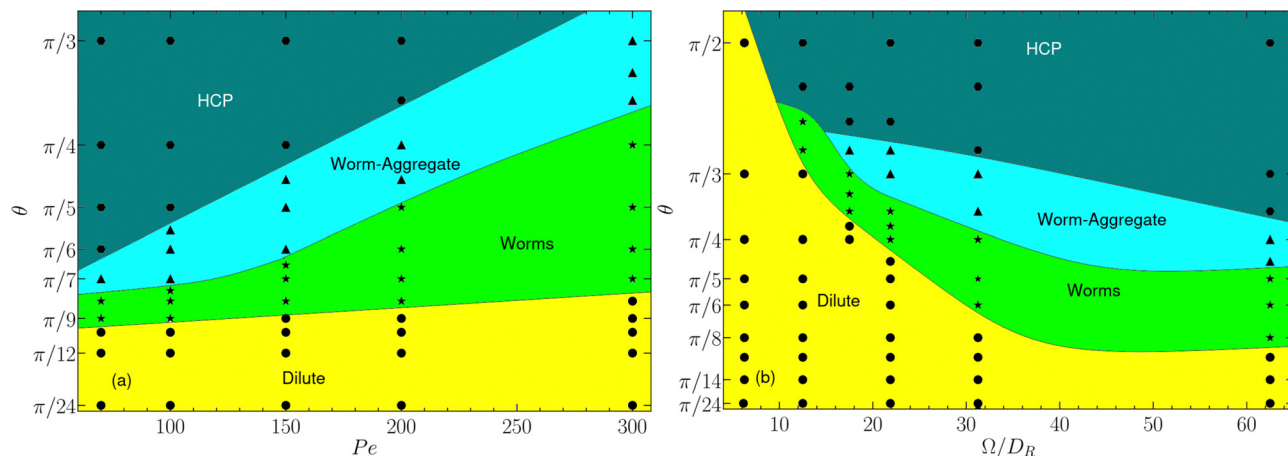


Fig. 5 (a) Vision angle-Péclet number (θ - Pe) state diagram for the packing fraction $\Phi = 0.00785$, $\Omega/D_R = 62.5$, and $R_0 = 1.5\sigma$. (b) Vision angle- Ω (Ω - Pe) state diagram for $Pe = 200$, and otherwise the same parameters as in (a). The individual phases are indicated by different colors and symbols. HCP: navy ●, worm-aggregate: blue ▲, worm: green ★, dilute: yellow ●. The “phase” borders are guides for the eye.

indicates that finite-size effects are small. A calculation of the full phase diagram at the higher N is very demanding in terms of computational time, and thus has not been attempted here.

Here, a comment on the stationary-state properties of the observed structures is in order. The identified worm-aggregate, worm, and dilute phase are stationary, and do not depend on the initial arrangement of the ABPs. These structures are very dynamic, they form, break apart, and reform. The situation is less clear for the HCP phase. Here, the initial arrangement never breaks apart, and it is not clear whether it is stable or not. However, when starting from a dilute-phase as initial condition, clusters are formed, which slowly merge into larger ones as described in more detail in Section 5, but the possible final state of a single large cluster cannot be observed in simulations in general due to the very slow merging process.

The extension of the various phases in the phase diagram depends on the maneuverability strength Ω , as displayed in Fig. 5(b). At very small value of Ω , noise dominates the orientational dynamics, and the iABPs are not able to persistently move toward sensed other iABPs—the system is in the dilute phase. For larger Ω , the maneuverability begins to dominate over rotational noise, iABPs can move into the sensed direction, and, depending upon the vision angle, can form HCP, worm-aggregate, worm phases.

4.1.2 Collective dynamics. We characterize dynamical correlations by the spatial velocity correlation function⁵⁰

$$C_v(r) = \frac{\sum_{i,j \neq i} \langle \mathbf{v}_i \cdot \mathbf{v}_j \delta(\mathbf{r} - |\mathbf{r}_i - \mathbf{r}_j|) \rangle}{c_0 \sum_{i,j \neq i} \langle \delta(\mathbf{r} - |\mathbf{r}_i - \mathbf{r}_j|) \rangle}, \quad (10)$$

where $\mathbf{v}_i$ is the velocity of particle i and $c_0 = \langle \sum_i v_i^2 \rangle / N$. Fig. 6 presents $C_v(r)$ for various vision angles. At the angle $\theta = \pi/2$, in the HCP phase, there is no significant spatial velocity correlation. The propulsion directions are independent, because iABPs inside a cluster see the same environment in any direction. The

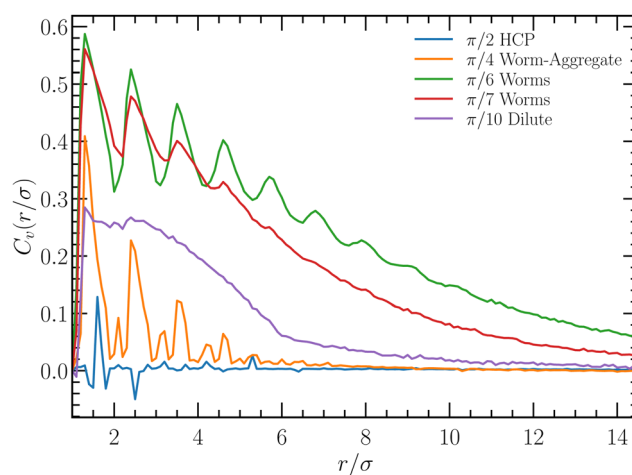


Fig. 6 Spatial velocity autocorrelation function of ABPs at $Pe = 200$, $\Omega/D_R = 62.5$, vision range $R_0 = 1.5\sigma$, and the packing fraction $\Phi = 7.85 \times 10^{-3}$.

non-zero value of C_v for $\theta = \pi/10$, and its extent over several iABP diameters, indicates significant velocity correlations already in the dilute phase. Hence, the dilute phase is different from the fluid phase of a passive system, as is also reflected in the spatial pair distribution function (Fig. S4, ESI†). Long-range correlations are inherent in worms. Naturally, the trailing of iABPs in worms is only possible with strong velocity correlations. The maxima in C_v correspond to preferred distances between iABPs at multiples of 1.25σ , as also displayed by the pair distribution function. Minima appear approximately at multiples of σ . The distance 1.25σ is consistent with visual inspection, and suggest that the distance between subsequent iABPs in a worm is larger than their diameter, *i.e.*, the typically do not touch. Worms are often nonlinear assemblies, with touching particles forming clusters moving together. The velocities of such additional iABPs are not necessarily fully aligned along the main worm direction, giving rise to smaller values of the velocity



correlation function. This explains the oscillations of C_v for $\theta = \pi/6$ and $\pi/7$.

4.1.3 Mean square displacement. The translational motion of the ABPs is characterized by their mean-square displacement (MSD)

$$\langle r^2(t) \rangle = \frac{1}{N} \sum_{i=1}^N \langle (r_i(t) - r_i(0))^2 \rangle. \quad (11)$$

Theoretical calculations for individual overdamped ABPs in two dimensions yield^{4,51}

$$\langle r^2(t) \rangle = 4D_T t + \frac{2v_0^2}{D_R^2} (D_R t - 1 + e^{-D_R t}), \quad (12)$$

with a short time diffusive regime, an active ballistic regime, and a crossover to an activity dominated diffusion for $D_R t > 1$. Fig. 7 displays MSDs for various vision angles, $Pe = 200$, and $\Omega/D_R = 62.5$. As long as $\theta \lesssim \pi/6$, which corresponds to the worm and dilute phase, the MSDs are well described by the expression of independent and noninteracting iABPs, with the set values $D_R = 0.08\tau$ and $Pe = 200$. This is not surprising, because the leading ABP of a worm does not see any other ABP for most of the time, and thus, behaves as a free ABP. The trailing ABPs follow the “leader” on essentially the same random trajectory. Thus, worm conformations roughly resemble the trajectories of individual ABPs. The presence of aggregates changes the diffusive behavior. In the worm-aggregate phase, the MSD is also well described by the theoretical expression for ABPs, but with the reduced active velocity $v'_0 = 0.4\sqrt{k_B T/m} = v_0/5$, determined by the fraction of iABPs in aggregates. The dynamics of the ABPs in the aggregates are slower than free ABPs, but ABPs are able to split off, move like independent ABPs, and rejoin dynamical clusters. In average, we obtain an ABP dynamics with a reduced effective Péclet number.

In the HCP phase for $\theta \leq \pi/2$, we still observe long-time active diffusion for $D_R t > 1$, with the active velocity

$v'_0 = 0.1\sqrt{k_B T/m} = v_0/20$, i.e., a 20 times smaller active Péclet number. Here, the aggregate moves as a whole. Calculations for N bound active Brownian particles yield an active diffusion coefficient proportional to $1/N$,⁵² which corresponds to an effective active velocity $v'_0 \sim 1/\sqrt{N}$. With about 650 particle in a cluster, the reduction by the factor 20 of v_0 is consistent with the picture of a cluster moving actively as a whole.

4.2 Higher packing fraction

4.2.1 Phases and phase diagrams. Fig. 8 displays snapshots of iABP structures for various vision angles and the packing fraction $\Phi = 0.0785$. We obtain similar phases as in Fig. 2 with aggregates and worms (see also Fig. S1, ESI†). In addition to Fig. 2, two more phase appear, a dispersed cluster phase (DC) comprised of small clusters (Fig. 8(d)), and a fluid-like aggregate with rather mobile groups, which we denote as aggregate phase (Fig. 8(e)).

The cluster-size distribution function of Fig. 9 shows the crossover from a fluid-like phase with an exponentially decaying N for $\theta < \pi/16$ to a bimodal distribution characteristic for a phase separated system.²⁷ The angle $\theta = \pi/16$ is close to the boundary separating the two phases. Note that we use $\sigma_0 = 1.2\sigma$ in this case to identify iABPs belonging to a particular cluster.

Based on the cluster-size distribution function, visual inspection, and the hexagonal order parameter q_6 (Fig. S3, ESI†)^{9,46,53}—specifically for separating the aggregate and HCP phase—we obtain the phase diagram in Fig. 10. Again, we find a HCP, worm-aggregate, and a dilute phase, however no worm phase. Evidently, higher densities enhance the preference of cluster and aggregate formation, because more particles appear in the vision cone. At smaller $Pe < 50$, in the aggregate phase, the iABPs form smaller cohesive clusters, which remain close to each other, but are highly dynamic by resolving and reforming while in contact with a dilute phase (Fig. 8(e)). At low Pe , this phase extends up to $\theta = \pi/2$. With increasing Pe , and for $\theta > \pi/8$, a HCP phase is present. The more persistent motion implies stronger cohesion and formation of a denser aggregate. Even larger Pe lead to melting of the HCP aggregates and a worm-aggregate phase appears as long as $Pe \gtrsim 50$ and $\pi/9 < \theta < 3\pi/2$ (Fig. 8(c)). Compared to the worm-aggregate phase at the lower density, the worms are typically shorter in length and shorter lived (Section 4.1.1). For smaller vision angle, the second new phase, the dispersed cluster phase, appears at high Péclet numbers, with small and short-lived clusters (Fig. 8(d)).

The various phases not only depend on Pe , but also on the vision range R_0 and the maneuverability Ω . Fig. S2 (ESI†) presents the dependence on R_0 and Ω for $Pe = 10$. The three phases, dilute, aggregate, and HCP, as in Fig. 10, are present for the range of considered values R_0 and Ω . With increasing vision range and maneuverability strength, the transition to the aggregate and HCP phase shifts to smaller vision angles. This is to be expected, because by a large R_0 , more iABPs are present in the vision cone, enhancing the tendency of clustering, and thus, cohesion. Similarly, at a larger Ω , orientational noise is

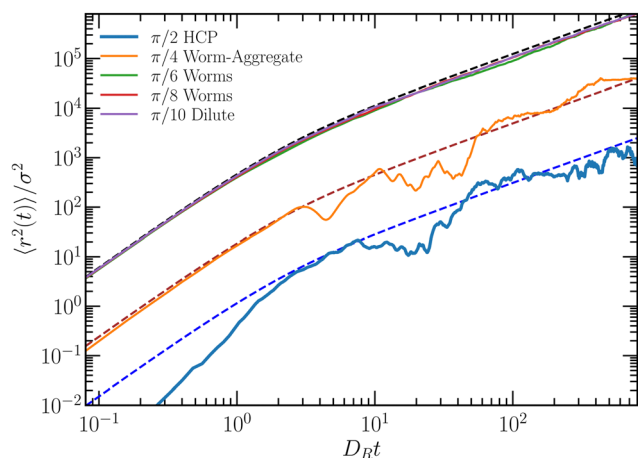


Fig. 7 Mean-square displacement of iABPs as a function of time at $Pe = 200$, $\Omega/D_R = 62.5$, vision range $R_0 = 1.5\sigma$, and the packing fraction $\Phi = 7.85 \times 10^{-3}$. The dashed lines are fits of eqn (12), without the passive diffusion term $4D_T t$.



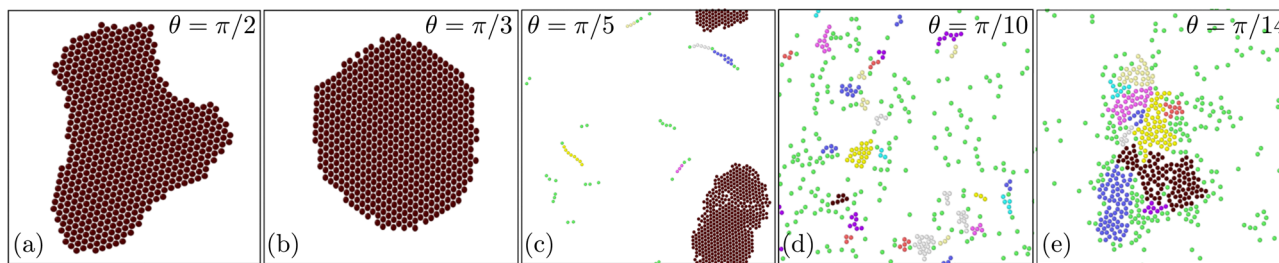


Fig. 8 Snapshot of iABP structures for various vision angles: (a) hexagonal-closed packed (HPC) structure, $\theta = \pi/2$, (b) hexagonal-closed packed (HPC) structure, $\theta = \pi/3$, (c) worm-aggregate coexistence, $\theta = \pi/5$, (d) dispersed cluster (DC) phase, $\theta = \pi/10$, for the Péclet number $Pe = 200$, and (e) aggregate phase, $\theta = \pi/12$, for $Pe = 10$. The strength of the perceptive interaction is $\Omega/D_R = 62.5$, and the packing fraction $\Phi = 0.0785$. The various colors represent different cluster. See movies M3, M4, and M5 (ESI†).

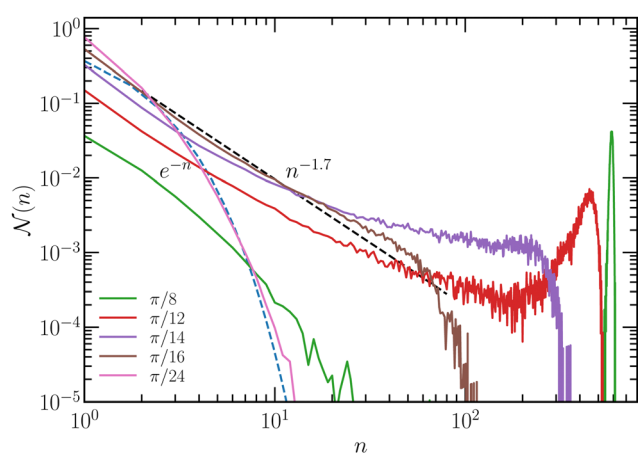


Fig. 9 Cluster-size distribution function $N(n)$ as a function of the cluster size n at $Pe = 10$, $\Omega/D_R = 62.5$, and the packing fraction $\Phi = 7.85 \times 10^{-2}$. The dashed line indicates a power-law decay. Notice that the radius to identify ABPs belonging to a cluster is $\sigma_0 = 1.2\sigma$.

less important compared the maneuverability, which also enhances cohesion.

4.2.2 Shape of aggregates. To characterize the shape of the iABP structures, we determine the kurtosis

$$K = \frac{\langle \Delta r^4 \rangle}{\langle \Delta r^2 \rangle^2}, \quad (13)$$

where

$$\Delta r^\zeta = \frac{1}{N} \sum_{i=1}^N (r_i - r_{cm})^\zeta, \quad (14)$$

with $\zeta = 2, 4$. The kurtosis of a Gaussian distribution is $K = 3$, that of a uniform distribution within a square is $K = 7/5$, and for a circle $K = 4/3$. Respective larger values indicate deviations from homogeneity and isotropy, where larger variations imply larger K .

Fig. 11 shows the kurtosis for various Pe . At very low vision angles, in the dilute phase, the ABPs are homogeneously distributed and $K \approx 1.4$ for all Pe , in agreement with the theoretical prediction $K = 7/5$. For $Pe = 1$, the K are close to the isotropic value at small θ , but increase with increasing θ ,

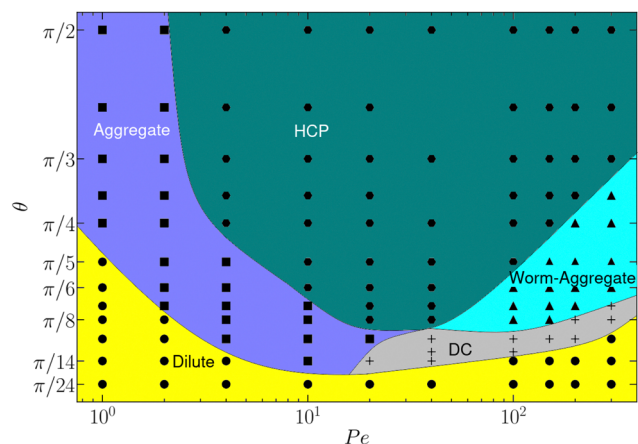


Fig. 10 Vision angle-Péclet number ($\theta - Pe$) state diagram for the packing fraction $\Phi = 7.85 \times 10^{-2}$, $\Omega/D_R = 62.5$, and $R_0 = 1.5\sigma$. The individual phases are indicated by different colors and symbols. HCP: navy, worm-aggregate: blue ▲, worm: green, dilute: yellow ●, distributed cluster (DC): grey +, aggregate: purple ■. The “phase” borders are guides for the eye rather than strict boundaries.

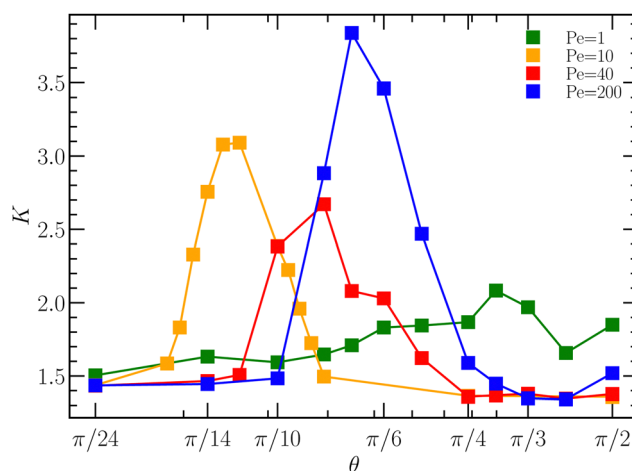


Fig. 11 Kurtosis of the probability distribution of iABPs for various Péclet numbers, $\Omega/D_R = 62.5$, vision range $R_0 = 1.5\sigma$, and the packing fraction $\Phi = 7.85 \times 10^{-2}$ (symbols). The lines are guides for the eye.



indicating formation of inhomogeneities, consistent with the formation of rather mobile clusters.

Similarly, for $Pe = 10$ and $\theta \lesssim \pi/20$ the system is isotropic and homogeneous. At $\theta \approx \pi/18$, K increases sharply and reaches the value $K \approx 3.2$ corresponding to a symmetric Gaussian distribution of iABPs (Fig. 10). The value K suggests that the shape of the aggregate is flexible and the iABPs are mobile, which agrees with the visual impression of a very dynamic, fluid-like cluster. Between $\theta = \pi/8$ and $\theta = \pi/2$, the phase transition from the aggregate phase to the HCP phase occurs, and K approaches the value $K \approx 3/4$. Here, the iABPs are densely packed and uniformly distributed in a circular area much smaller than the simulation cell (Fig. 8(b)).

The broad peak at $Pe = 40$ for $\pi/14 < \theta < \pi/4$ comprises configurations in the distributed cluster, worm-aggregate, and HCP phase. The values $7/4 \lesssim K \lesssim 2.5$ point toward large variations in density or/and shapes of clusters.

For $Pe = 200$, K increases as distributed clusters appear ($\theta \lesssim \pi/10$), reaches a maximum at $\theta \approx \pi/7$ in the worm-aggregate phase (Fig. 8(c)). In the latter case, the structures are rather non-uniform, specifically the worms, which yields the higher value $K \approx 3.8$. The K value of a dense, uniform, and symmetric cluster is reached for $\theta \approx \pi/3$ (Fig. 8(b)). The larger K value at $\pi/2$ is caused by the shape asymmetry of the cluster in the HCP phase (Fig. 8(a)). From the kurtosis it is clear that the dilute phase and closed packed hexagonal structure phases are more uniformly distributed and the value is close to the theoretical expectation. Hence, the kurtosis allows for a distinction of the dilute, aggregate (or worm-aggregate), and HCP phase and shape asymmetry within a phase.

4.2.3 Active diffusion coefficient. Fig. 12(a) provides examples of iABP mean-square displacements. From the linear regime for $tD_R > 1$, we extract the effective active diffusion coefficient D_A according to $\langle r^2(t) \rangle = 4D_A t$. The respective values D_A are presented in Fig. 12(b). For the vision angles $\theta < \pi/14$ —the dilute regime—the iABPs behave as ABPs in dilute solution, and $D_A = D_T + v_0^2/(2D_R)$. The values from our simulations are within 20–30% of the expected theoretical values, despite the additional vision interaction. With increasing θ , aggregates form and D_A decreases. Even for Péclet numbers as small as $Pe = 1$, we observe a decrease of D_A , although small compared to that at larger Pe , suggesting emergent inhomogeneities. For all larger Pe , we obtain a very similar trend with increasing θ . At $\theta = \pi/2$, the iABPs are in the HCP phase for $Pe \geq 10$. Here, the iABPs diffuse together as a cluster, with an diffusion coefficient $D_A \sim 1/N$, a relation predicted for ABPs in an aggregate (cf. Section 4.1.3).⁵²

5 Cluster growth

In the HCP phase, clusters form from an initial uniform distribution of iABPs, which then merge and grow in time. We analyze the cluster-growth process as a function of time by calculate the number $p(n, t)$ of clusters of size n at time t and

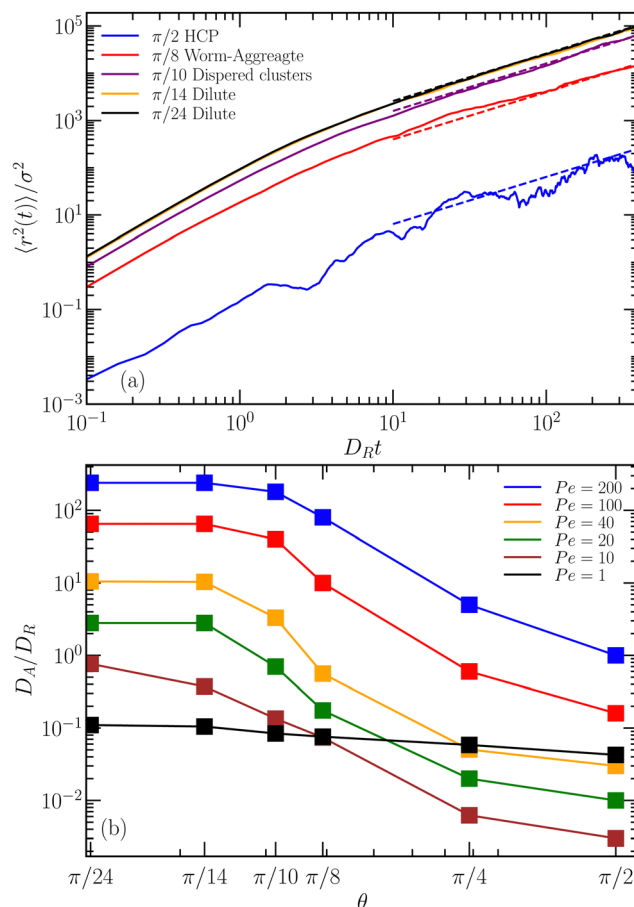


Fig. 12 (a) Mean square displacement of ABPs as a function of time for $Pe = 100$. The dashed lines are fits to a linear time dependence. (b) Effective diffusion coefficients, D_A , as a function of the vision angle θ for various Pe . The other parameters are $\Omega/D_R = 62.5$, $R_0 = 1.5\sigma$, and $\Phi = 0.0785$.

determine the time-dependent average cluster size⁴²

$$C(t) = \left(\sum_{n=1}^N np(n, t) \right) / \sum_{n=1}^N p(n, t). \quad (15)$$

As before, particles belong to a clusters if the distance between ABPs is smaller than $\sigma_0 = 1.2\sigma$. For convenience, we consider the larger packing fraction $\Phi = 0.157$, with a phase diagram very similar to that in Fig. 10 up to $Pe \approx 20$, only the boundaries of the dilute and aggregate phase are somewhat shifted (Fig. S2, ESI†). In particular, we observe a HPC phase for $1 < Pe < 20$ at $\theta = \pi/2$.

Fig. 13(a) shows the time-dependence of the average cluster size for various Pe . Evidently, cluster growth depends on Pe , and $C(t)$ exhibits two power-law regimes, $C(t) \sim t^{z_k}$ ($k = 1, 2$). The short-time regime, $1 < D_R t < 10$, starts approximately after the iABPs reach the active diffusive time regime (Fig. 12). The exponent of the power-law growth, z_1 , depends on Pe . As displayed in Fig. 13(b), it can be well described by $z_1 \sim Pe^{4/5}$. Even more, the exponent depends on the vision angle (Fig. S5, ESI†) for which we find $z_1 \sim \theta^{1/5}$, hence,

$$z_1 \sim Pe^{4/5} \theta^{1/5}. \quad (16)$$



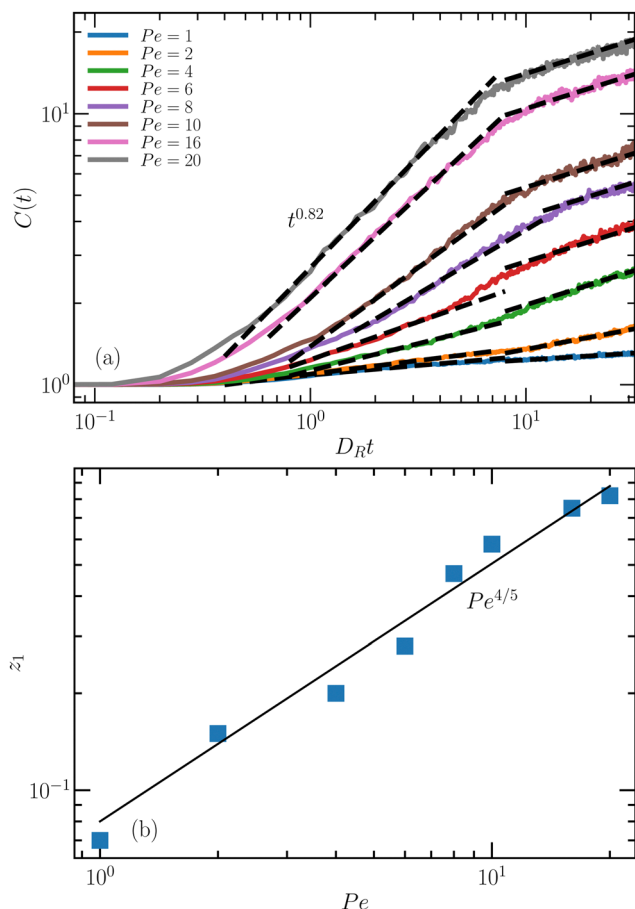


Fig. 13 (a) Average cluster size as a function of time for various Pe , the vision angle $\theta = \pi/2$, and the packing fraction $\Phi = 1.57 \times 10^{-1}$. (b) Growth exponent z_1 as a function of Pe . See movie M6 (ESI†).

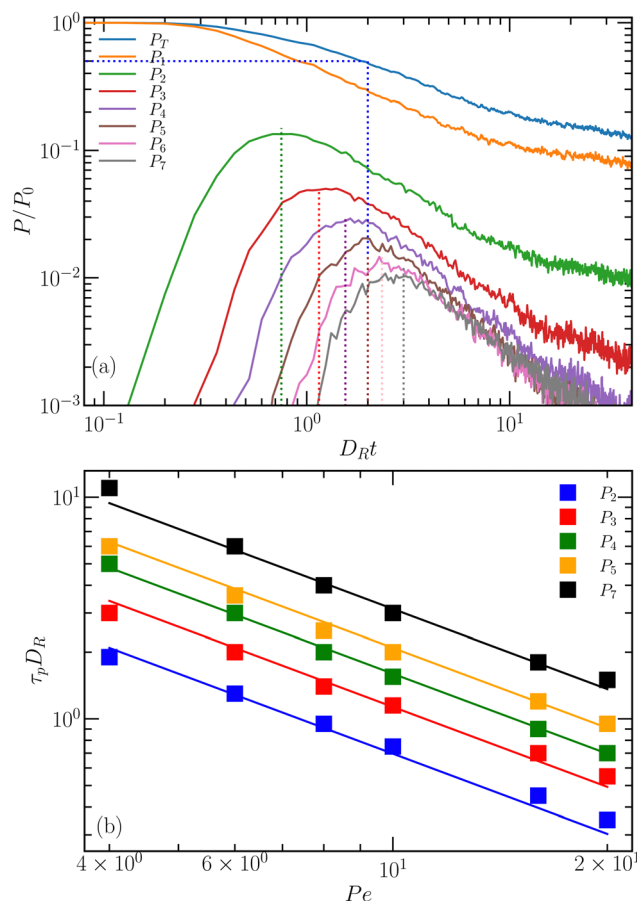


Fig. 14 (a) Temporal evolution of the cluster concentrations P_i as a function of time for the vision angle $\theta = \pi/2$ and activity $Pe = 10$. P_T is the total concentration. (b) Characteristic times of the maxima of $P_i(t)$ as a function of Pe . The fitted line corresponds to eqn (17), whereas the squares represents simulation results.

For $D_R t \gtrsim 8$, $C(t)$ crosses over to a second power-law regime, where $C(t) = Q(Pe, \theta) t^{z_2}$, with $z_2 = 1/4$ independent of Pe , but the prefactor, Q , is Pe dependent. Similarly, at constant Pe , z_2 is independent of θ , but the prefactor is θ dependent. However, this applies for $Pe \geq 4$ and $\theta \geq \pi/6$ only. It is interesting to note that the crossover from the first to the second regime occurs at fixed $D_R t \simeq 10$ —independent of Pe . Both time regimes are determined by the maneuverability of the iABPs.

The system-size dependence of $C(t)$ is analyzed by increasing the number of iABPs by a factor of two and four at the constant packing fraction $\Phi = 1.57 \times 10^{-1}$. Within the accuracy of the simulations, the various $C(t)$ curves agree very well with each other, and we could not detect a finite-size dependence (see Fig. S6 of ESI†).

To further characterize cluster formation, we consider the concentration $P_n(t) = p(n, t)/A$ (eqn (7)) of clusters containing n iABPs at time t within the area A of the simulation box. Initially the iABP concentration is $P_0 = 0.2$. The temporal evolution of the relative concentration of clusters is presented in Fig. 14(a) for various cluster sizes. The concentration P_1 of individual iABPs decrease with increasing time as particles merge. At the same time, clusters emerge, first dimers, then trimers, *etc.*, into

larger clusters, which causes an initial growth of $P_n(t)$ ($n > 1$), reaching a maximum, and a decrease with increasing time.

The characteristic time $\tau_p(n)$, where $P_n(t)$ assumes its maximum, is presented in Fig. 14(b) for various cluster sizes and Pe . The time τ_p increase with increasing n and decreases with increasing Pe , where the data sets are well described by the relation $\tau_p D_R \sim (n/Pe)^\kappa$, with $\kappa = 6/5$. In addition, τ_p depends on and vision angle θ (ESI†). Overall, the maximum time is well described by the expression

$$\tau_p(n) D_R = 5.5(n/Pe)^\kappa \theta^{-\kappa/4}. \quad (17)$$

Theoretical calculations for short-range attractive passive colloids based on the Smoluchowski equation with a constant kernel (cluster-size-independent rate constant) predict the asymptotic behavior $P(n, t) \sim 1/t^2$ for $t \rightarrow \infty$.⁴² Moreover, the time at the maximum of $P(n, t = \tau_p)$, $\tau_p \sim n$, increases linearly with n . This is distinct from our simulations, with $P(n, t) \sim 1/t$ over a certain time regime, at least for $n > 2$, and the super-linear increase of τ_p with n (eqn (17)). Hence, the clustering dynamics with activity differs strongly from that of passive short-range attractive colloids.



Our simulation results for the cluster growth can be interpreted as follows. First, at short times and small cluster sizes, the rate of cluster formation is strongly increased by visual perception and self-propulsion compared to passive aggregating particles, as directed motion is obviously much faster than random-walk-like diffusion. The dominance of active ballistic motion in the time regime $1 < D_R t < 10$ can be inferred from the Pe dependence of τ_p in eqn (17); for $\kappa \simeq 1$, $\tau_p(n)D_R \sim (n/Pe) \sim (nD_T/\sigma v_0)$, so that $\tau_p(n)v_0/\sigma \sim n$ (note that $D_T/(\sigma^2 D_R) = 1/8 = \text{const.}$ in our model). Thus, the relevant time scale for the peak times for cluster of size n is *not* the diffusion coefficient $1/D_R$, but the time σ/v_0 by active motion. Second, the peak times $\tau_p(n)$ decrease with increasing vision angle (eqn (17)), because particles can find and join existing (small) clusters the easier the more particles are within the vision cone. Third, this behavior changes at longer times, $D_R t > 10$, as particles at the cluster boundary are pointing toward the cluster center, thereby stabilizing clusters, and also cluster distances increase, so that their separation becomes larger than the vision range. Fourth, it seems likely that in this long-time regime, cluster collisions are diffusion limited, similarly as for passive colloidal systems, however with an active diffusion coefficient. Our simulations result in Fig. 12(b) show that this long-time translational diffusion coefficient D_A scales as $1/n$ with the cluster size n . Finally, the scaling behavior of cluster growth can be obtained from a description by an effective Smoluchowski equation. For any kernel K , which is a homogeneous function of the form $K(qi, qj) = q^2 K(i, j)$, the asymptotic behavior can be derived from a scaling ansatz,^{54,55} for $\lambda < 1$, this implies that the average cluster size grows with a power law t^z , with $z = 1/(1 - \lambda)$. This kernel is the product of cluster diffusion and the merging rate upon cluster collision, where the diffusion coefficient is proportional to $1/n$. More difficult to estimate is the size dependence of the collision and merging process; this can either increase with n (because larger clusters have a larger scattering cross section) or decrease with n (because particle reorientation at the collision interface, which initiates merging, might occur less frequently for larger clusters). For a growth process with diffusion and size-independent cluster collisions and mergers, $\lambda = -1$ and thus $z = 1/2$, which clearly overestimates the long-time average cluster growth compared to the numerical results in Fig. 13(a). On the other hand, the simulation result $z = 1/4$ requires $\lambda = -3$, which corresponds to a merging process which scales as $1/n^2$, i.e., which becomes less efficient for larger n . Thus, it will be important to study and unravel the collision and merging process in more detail in the future, specifically for long times.

6 Summary and conclusions

We have studied structure formation in systems of intelligent active Brownian particles, adopting the cognitive flocking model of ref. 39. We have systematically varied the maneuverability strength, the vision angle and vision cutoff radius, and the ABP activity. We find distinct phases, such as a dilute fluid,

aggregates, worms, worm-aggregate coexistence, hexagonally closed packed structures (HCP), and a diffuse clusters phase, depending upon the above parameters. We established phase diagrams for various packing fractions, illustrating the emergent phases.

Larger vision angles, θ , lead to a larger number of sensed particles and a stronger response. Correspondingly, the system is in a dilute, fluid-like phase at lower θ , and at large angles dense, hexagonally close-packed structures appear. In-between, dependent on the maneuverability strength, additional phases emerge, which have not been found in previous studies, specifically the coexistence of worms and aggregates.

The analysis of the iABP dynamics shows, in the dilute and worm phase, mean-square displacements identical with those of an individual ABP for the considered packing fractions $\Phi \leq 0.16$. The long-time active diffusion coefficient, D_A , decreases with increasing vision angle, and in the HCP phase, $D_A \sim 1/N$, where N is the number of particles in the cluster. Here, the iABP move together in a diffusive manner.

Starting from a homogeneous and isotropic system for the (large) vision angle $\theta = \pi/2$, the iABPs begin to nucleate and to form clusters, which merge in the course of time. Our analysis of the temporal evolution of the average cluster size, $C(t) \sim t^{z_k}$, reveals two power-law regimes with characteristic short-, z_1 , and long-time, z_2 , exponents. The exponent $z_1 \sim Pe^{4/5} \theta^{1/5}$ strongly depends on activity and the vision angle, whereas $z_2 = 1/4$ is independent of Pe. The analysis of the temporal evolution of the cluster concentration, P_n , yields the power-law dependence $\tau_p(n)D_R = 5.5(n/Pe)^\kappa \theta^{-\kappa/4}$, with $\kappa = 6/5$ for the characteristic time, where P_n assumes a maximum. The exponent κ is larger than that obtain in calculations of short-range attractive passive colloids, where $\tau_p \sim n$, or $\kappa = 1$.⁴² Hence, the implemented perception rule slows down clustering and cohesion at large clusters. Our considerations show that active processes can lead to an aggregation process, which is distinct from that of passive systems.

Moreover, aggregation depends on the underlying active process. The considerations in ref. 56 for ballistic and diffusive active motion of clusters yield the time dependencies t^1 and $t^{1/2}$, respectively, for cluster growth in two dimensions at long times. Compared to these, the exponent $z_2 = 1/4$ suggests a much slower cluster growth for the considered vision-based active system.

Inertia effects can play a significant role in the structure formation of active systems.^{57,58} This is also reflected in our simulations with “slightly” underdamped equations of motion. Despite a large friction coefficient and a crossover in the mean-square displacement from the short-time passive ballistic motion to the over-damped diffusive motion at $\langle r^2 \rangle / \sigma^2 \approx 10^{-3}$, a fraction of a colloid diameter, the phase boundary are somewhat shifted, compared to a fully overdamped dynamics.

We have considered a minimal model of iABPs, with vision-based input and limited maneuverability, which serves as a basis for various possible future extensions to more specific or advanced cognitive processes. In particular, multiple input channels complemented by a complex decision process and



response can be designed, for which we expect other collective dynamical features and means to control the emerging structures and collective dynamics.

Conflicts of interest

There is no conflict of interest.

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