

Engineering of the Musculoskeletal System and Rehabilitation

2.2 Numerical methods

Hip, Knee

Alexandre Terrier

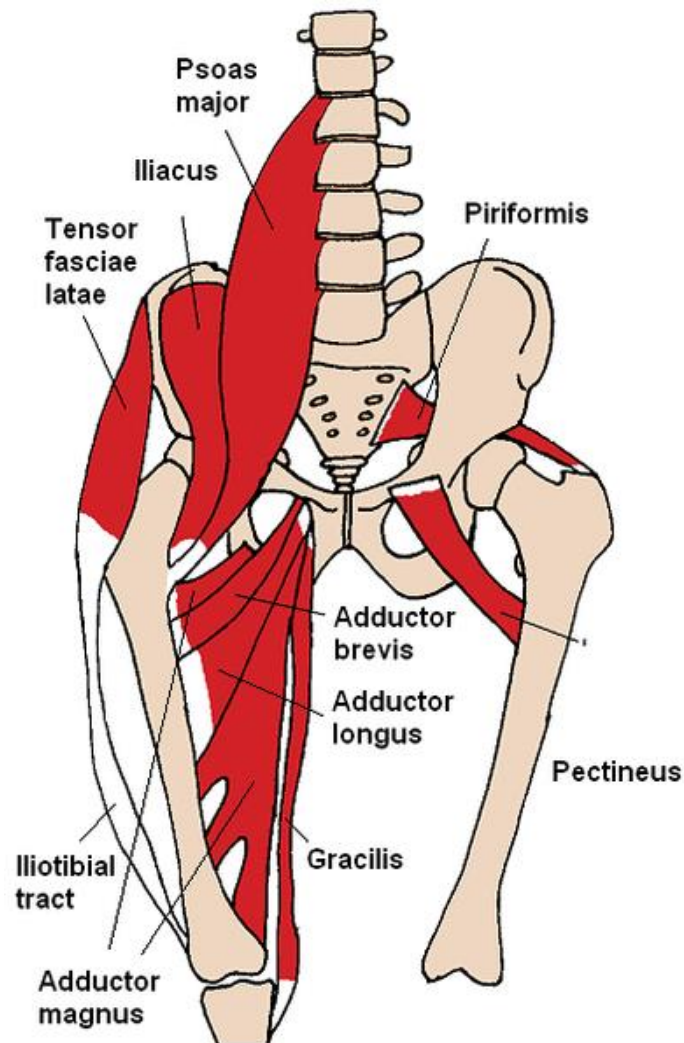
(EPFL-LBO)

Hip anatomy: joint

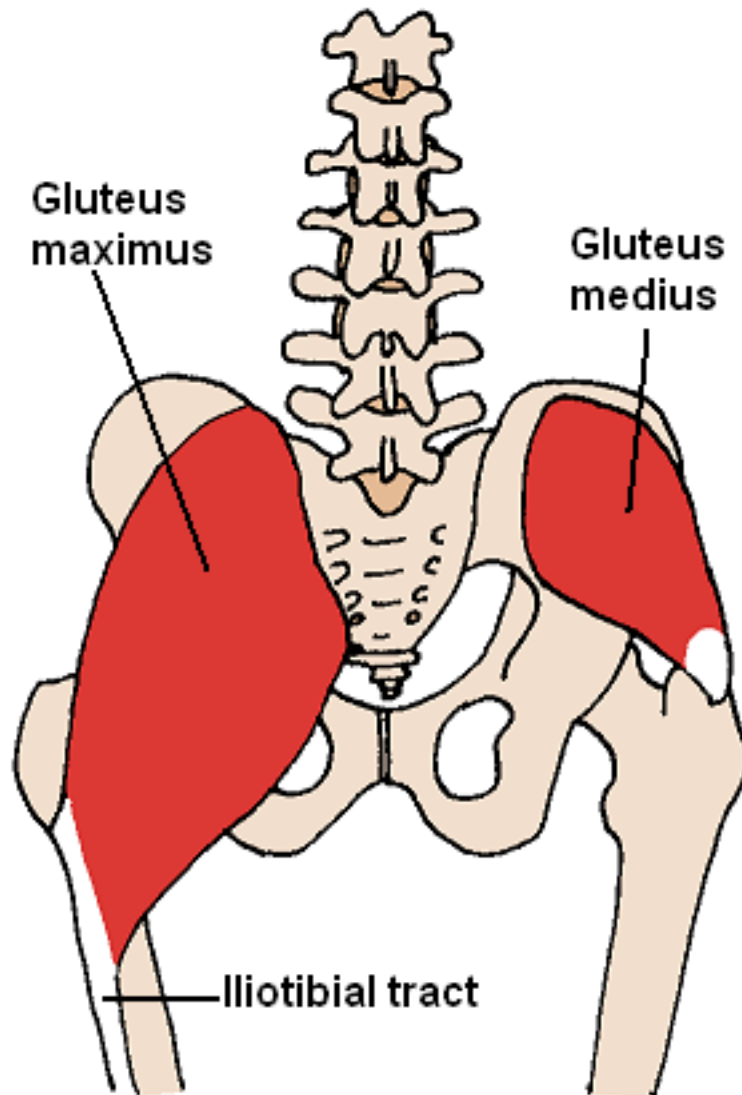
- Ball and socket joint
- Femoral head
- Acetabulum
- Cartilage
- Bone (structure)
- Muscles



Hip anatomy: muscles



Hip anatomy: muscles



Total Hip Arthroplasty (THA)



Total Hip Arthroplasty

- Osteoarthritis, fractures, tumors
- Resurfacing (femoral head) vs. total
- Uncemented vs. cemented
- Shapes of stems (straight, anatomical, custom)
- Materials: polyethylene, ceramics, metal
- Failure rate (Swedish register)
- Failure causes: loosening, infection, fracture, dislocation, technical error

Swedish register

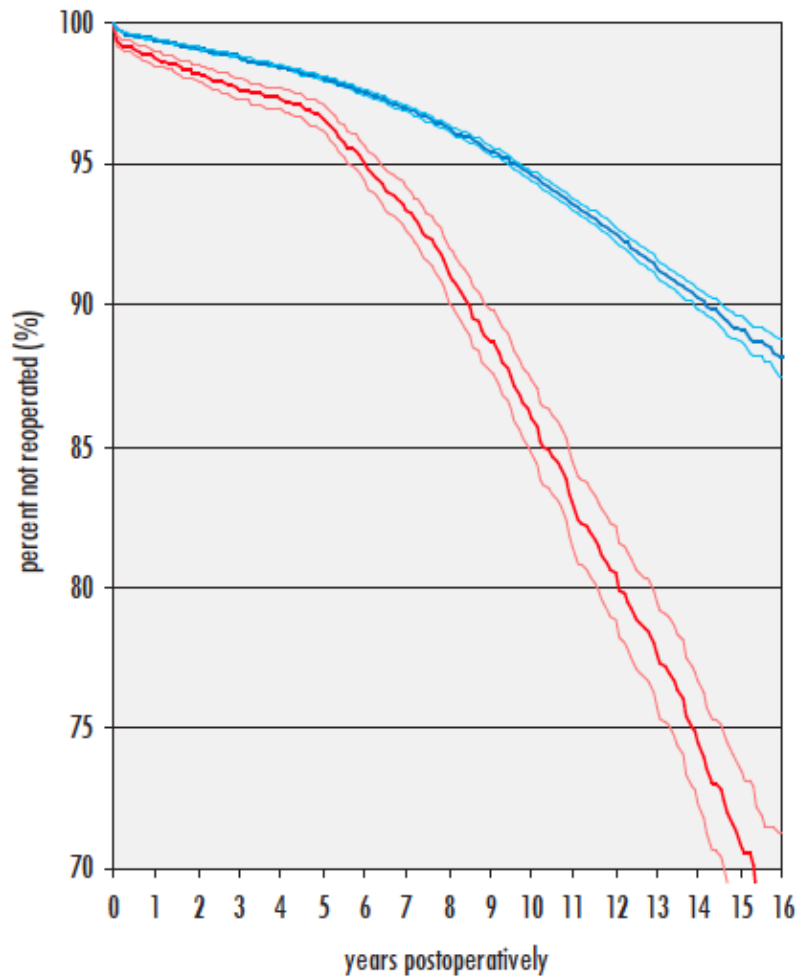
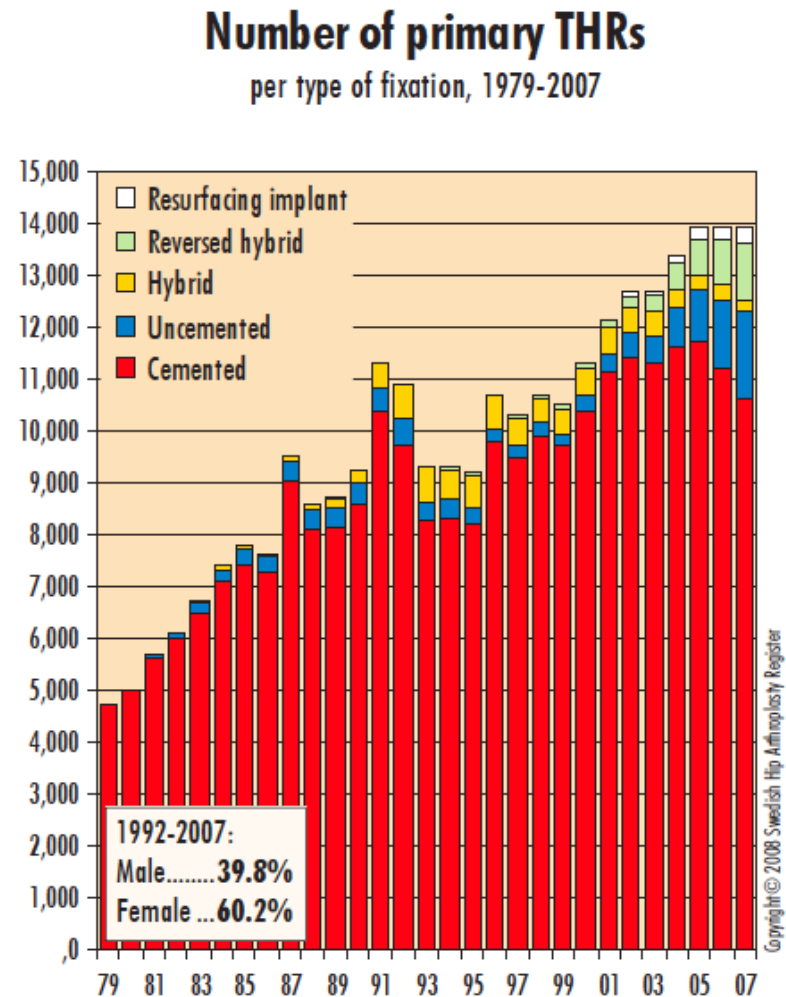
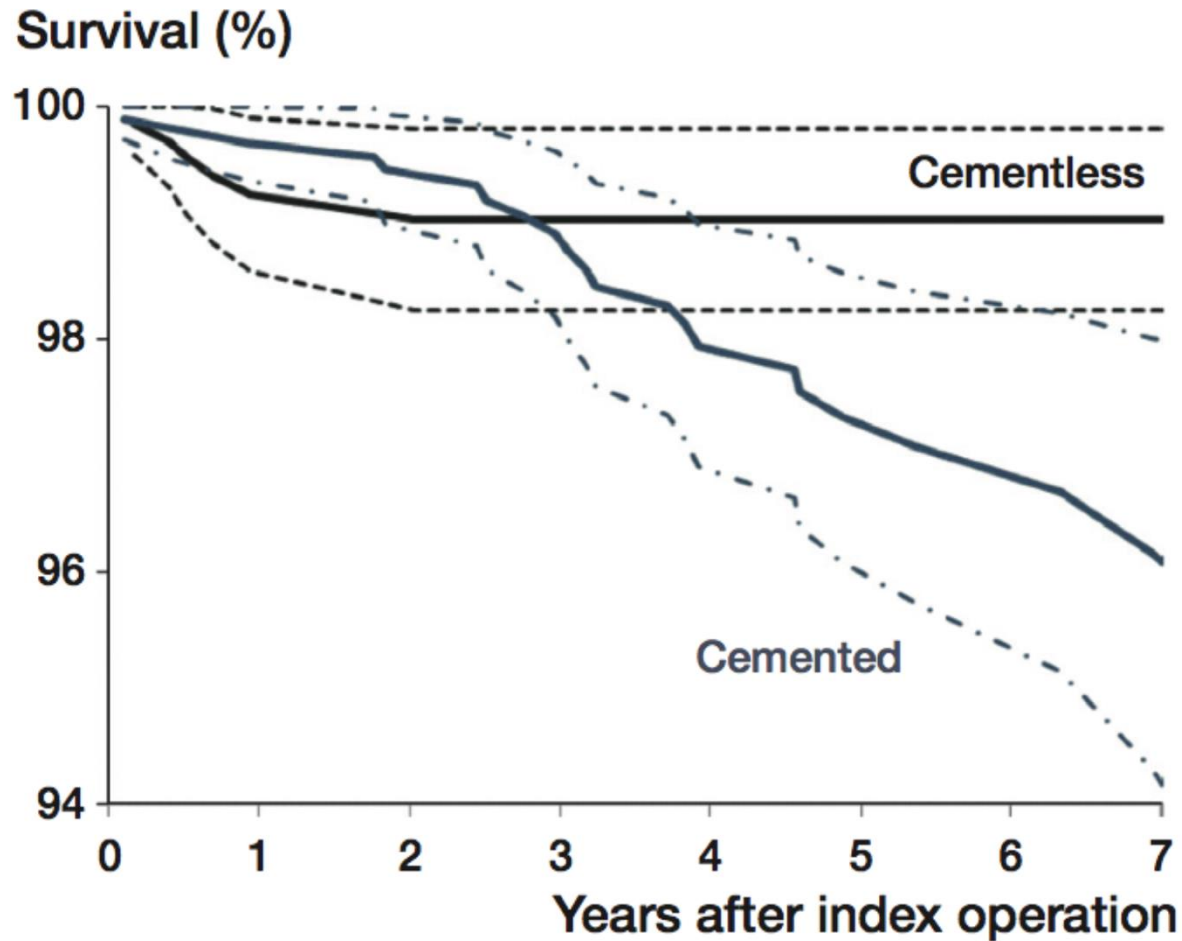


Figure 2a. Implant survival with end-point revision – all causes excluding infection for all-cemented (blue) implants and uncemented (red) implants inserted between 1992 and 2007.



Cementless advantage



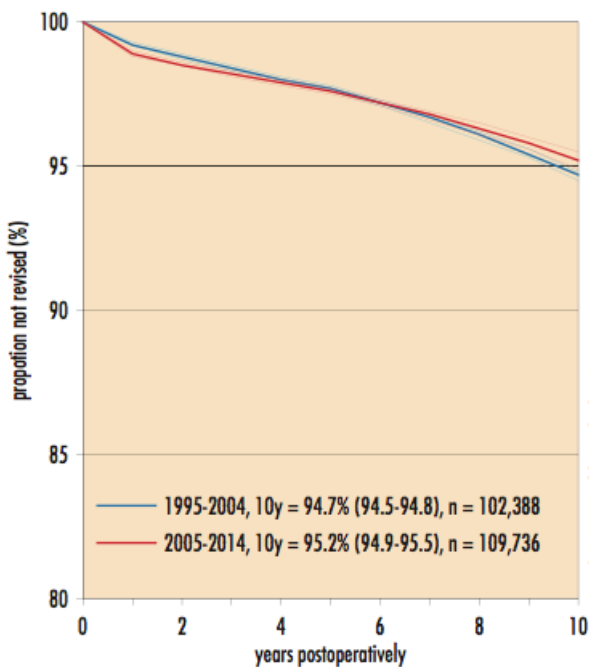
Total Hip Arthroplasty

The Swedish Hip Arthroplasty Register

Annual Report 2014

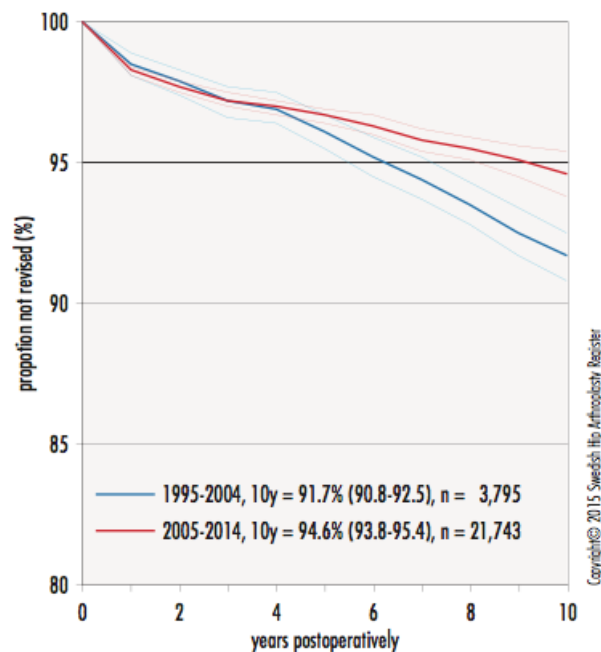
All cemented implants

All diagnoses and all reasons



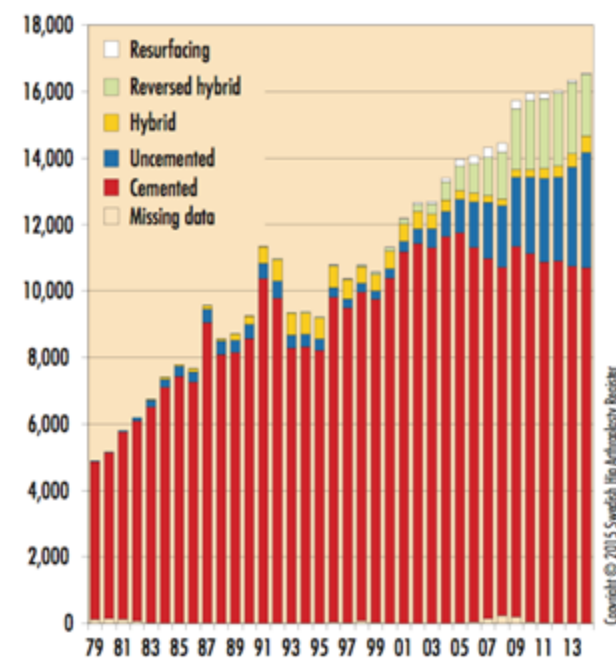
All uncemented implants

All diagnoses and all reasons



Number of primary THR

per type of fixation, 1979-2014

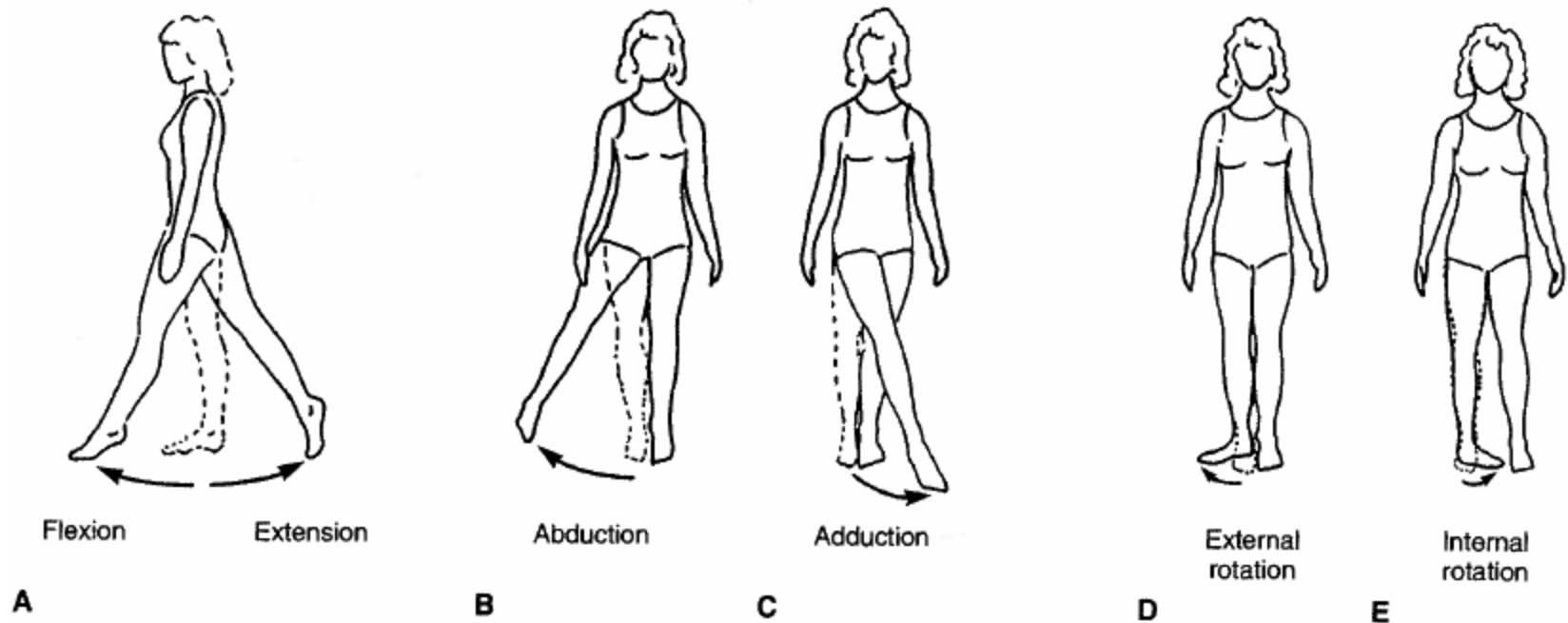


Biomechanics

- Kinematics
 - motion analysis (Camera, Magnetic, Fluoroscopy)
- Biomechanics
 - Force analysis
 - Stress/strain analysis
 - Interface
 - Mechano-biology (cellular response)

Kinematics

- Ball and socket joint (3 rotations)
 - Flexion/extension ($120^{\circ}/30^{\circ}$)
 - Abduction/adduction ($40^{\circ}/20^{\circ}$)
 - Internal/external rotation ($40^{\circ}/50^{\circ}$)



Kinematics

- Activities of Daily Living (ADL)
 - Walking
 - Sitting/standing
 - Stairs climbing/descending



Kinematics

- Kinematics problem associated to THA
 - Impingements
 - Dislocation

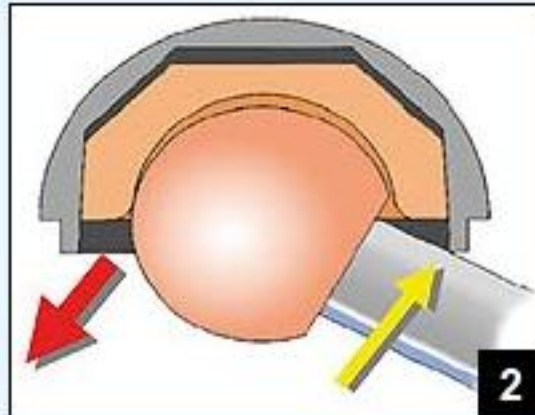


Figure 2: Diagram demonstrating femoral neck impingement on an elevated metal rim resulting in microseparation of the femoral head from the acetabular component.

Biomechanics

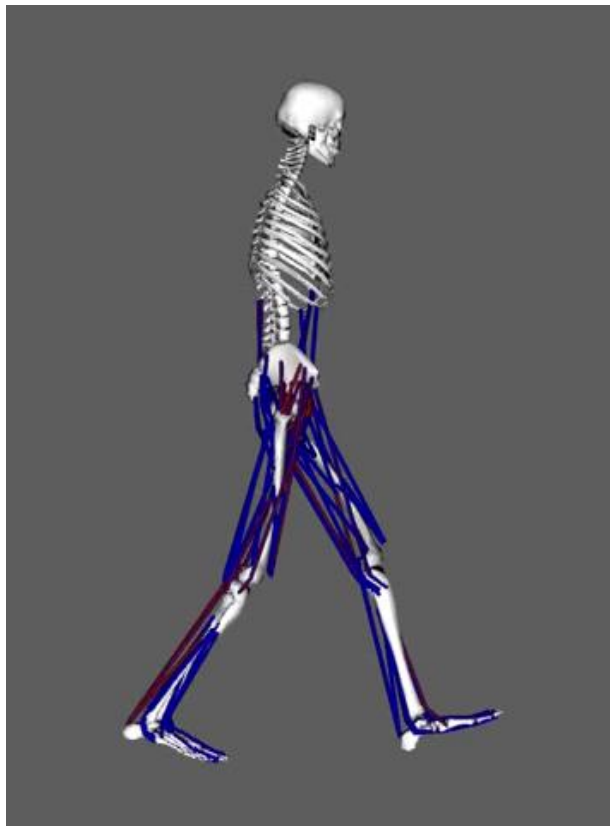
- Force analysis
 - Indeterminate mechanical system
 - Joint (instrumented prosthesis)
 - Muscles (musculoskeletal models)
 - Body weight (inertia)
 - Ground reaction (force captor plate)

NCSRR
NATIONAL CENTER
FOR SIMULATION IN
REHABILITATION
RESEARCH



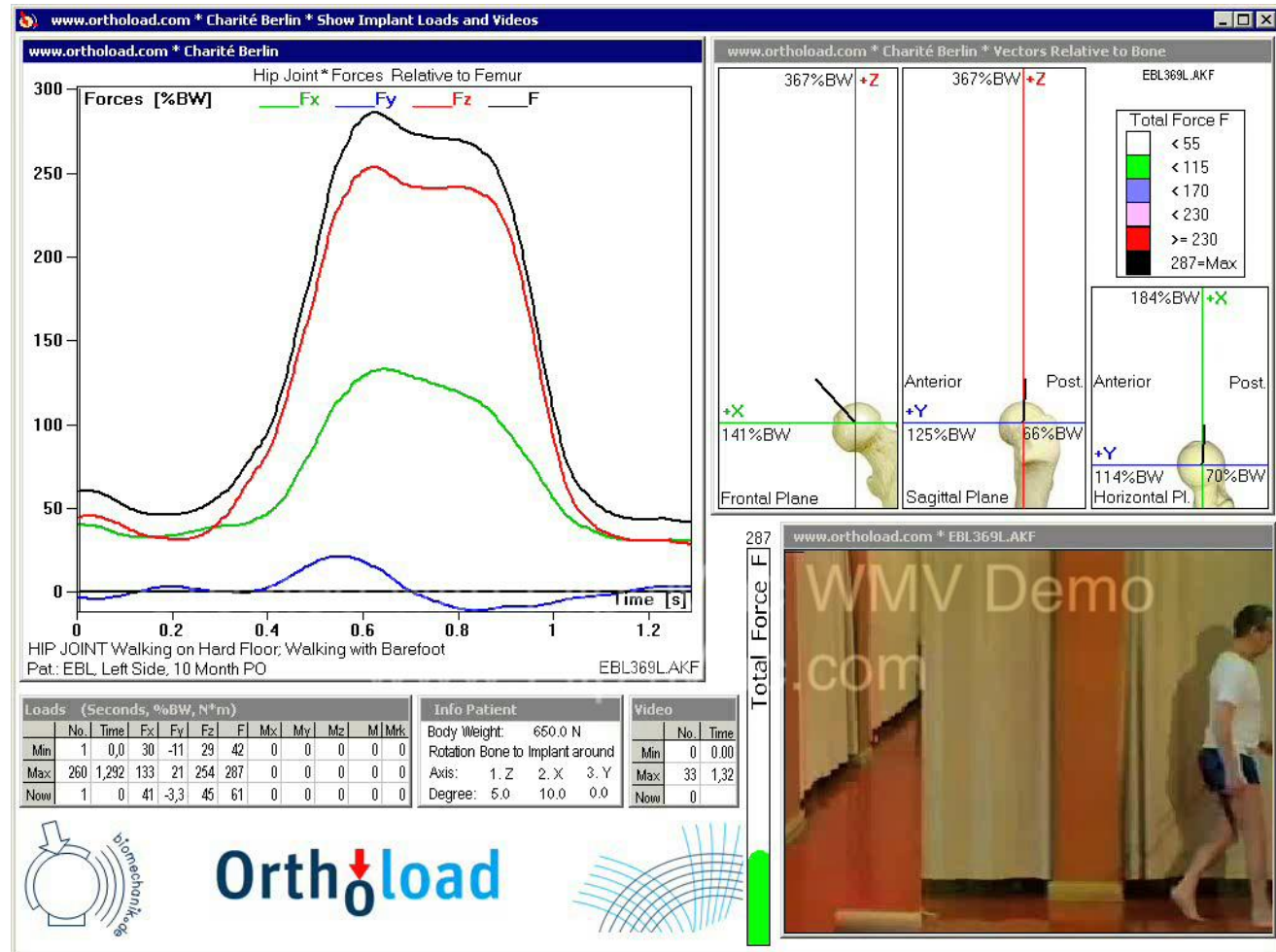
OpenSim Community

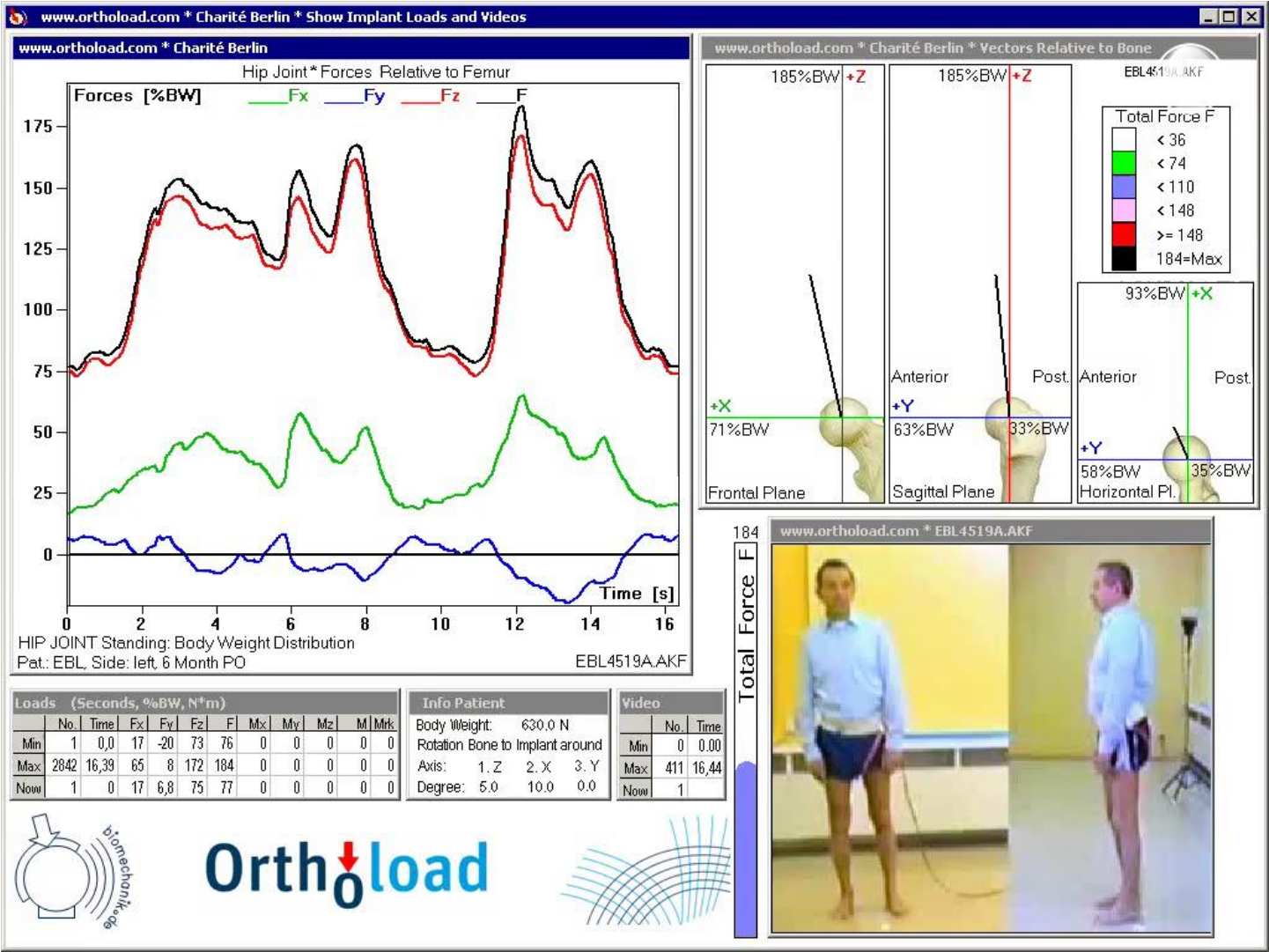
- SEE THE WORK
- JOIN THE COMMUNITY
- FIND SUPPORT, EVENTS, & RESOURCES



Hip force: instrumented prosthesis

<http://www.orthoload.com>





Numerical analyses

- Forces (muscles, joint)
- Stress/strain (vs. material/physiological limits)
- Micromotion (interface)
 - Slipping (tangential)
 - Debonding (perpendicular)
- Mechano-biology (remodeling/stress shielding)
- Parametric study
- Patient-specific analyses
- Prosthesis design improvement
- Patient-specific treatment

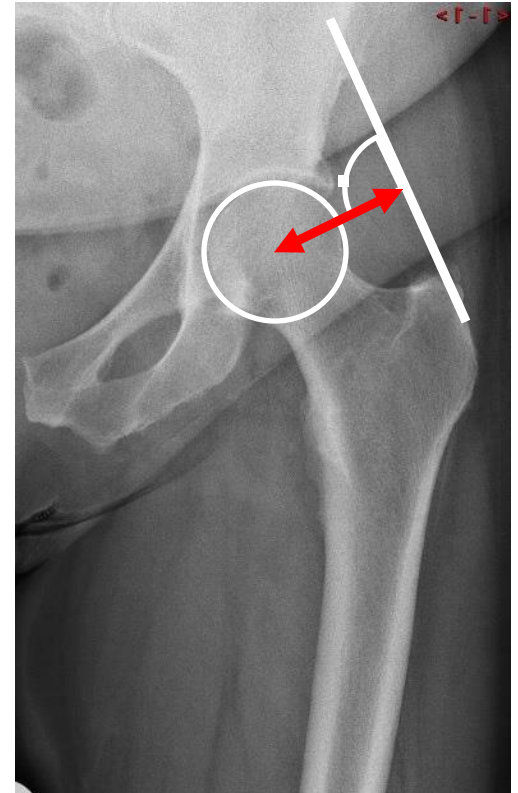
THA: cup medialization

Cup medialization:

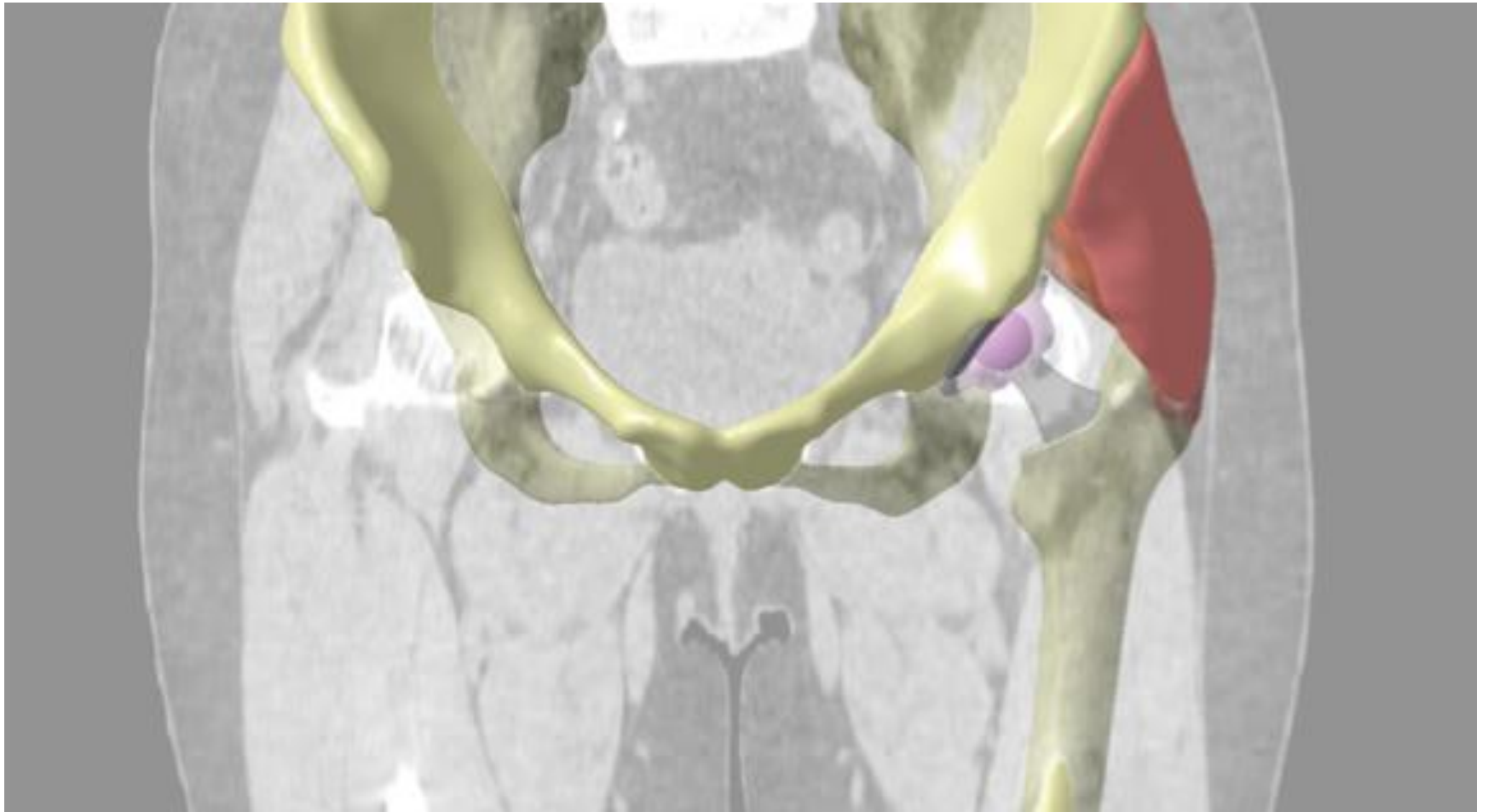
- femoral offset $\uparrow$
- acetabular offset $\downarrow$
- global offset constant

→ Improved lever arms

→ Loss of bone stock

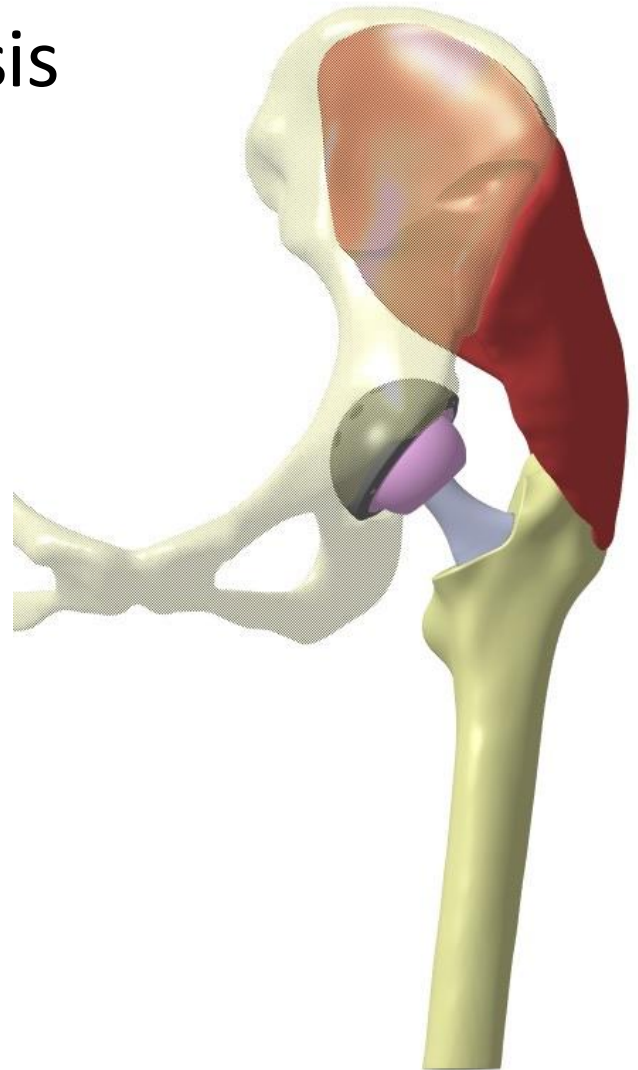


Hip



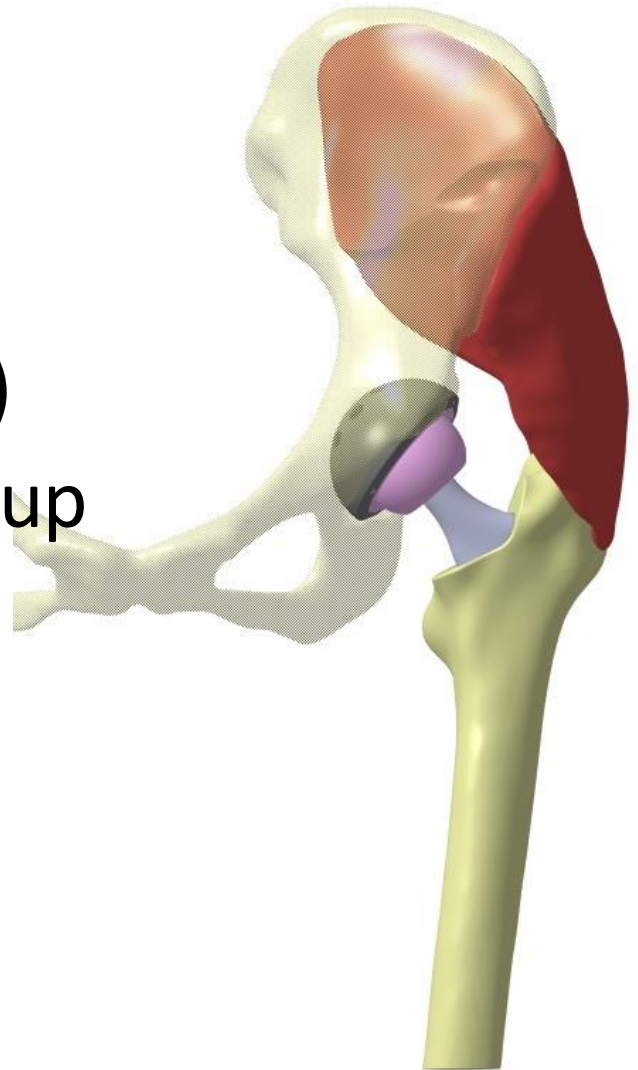
THA: cup medialization

- Limitation of Xray 2D analysis
- Muscle volume
- Muscle fibers
- Gait

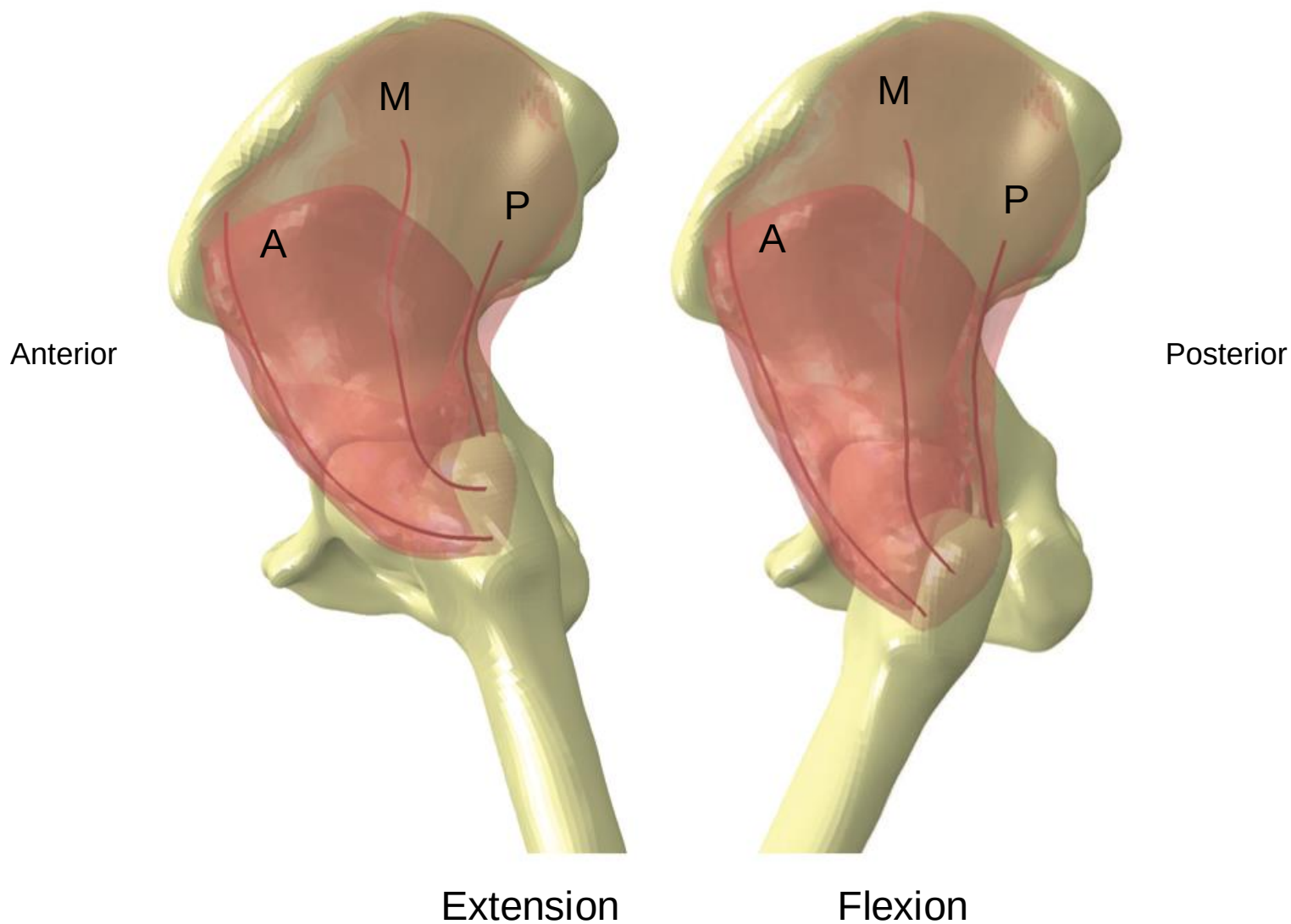


THA: cup medialization

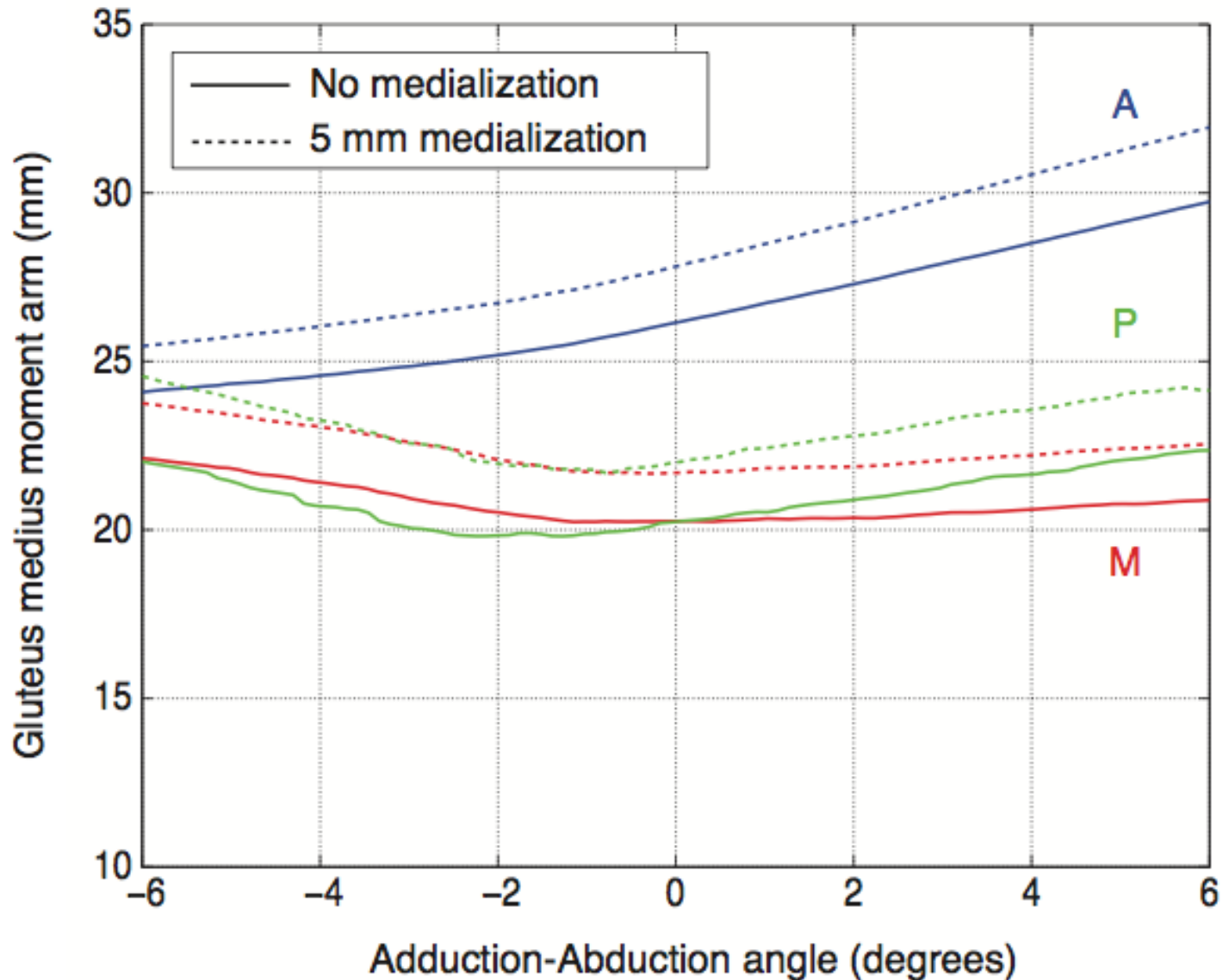
- Numerical model
- 15 patients CT
- Gluteus medius
- 3 fibers (Ant., Middle, Post.)
- Anatomical vs. medialized cup
- Gait
 - Abduction-adduction
 - Flexion-extension



THA: cup medialization

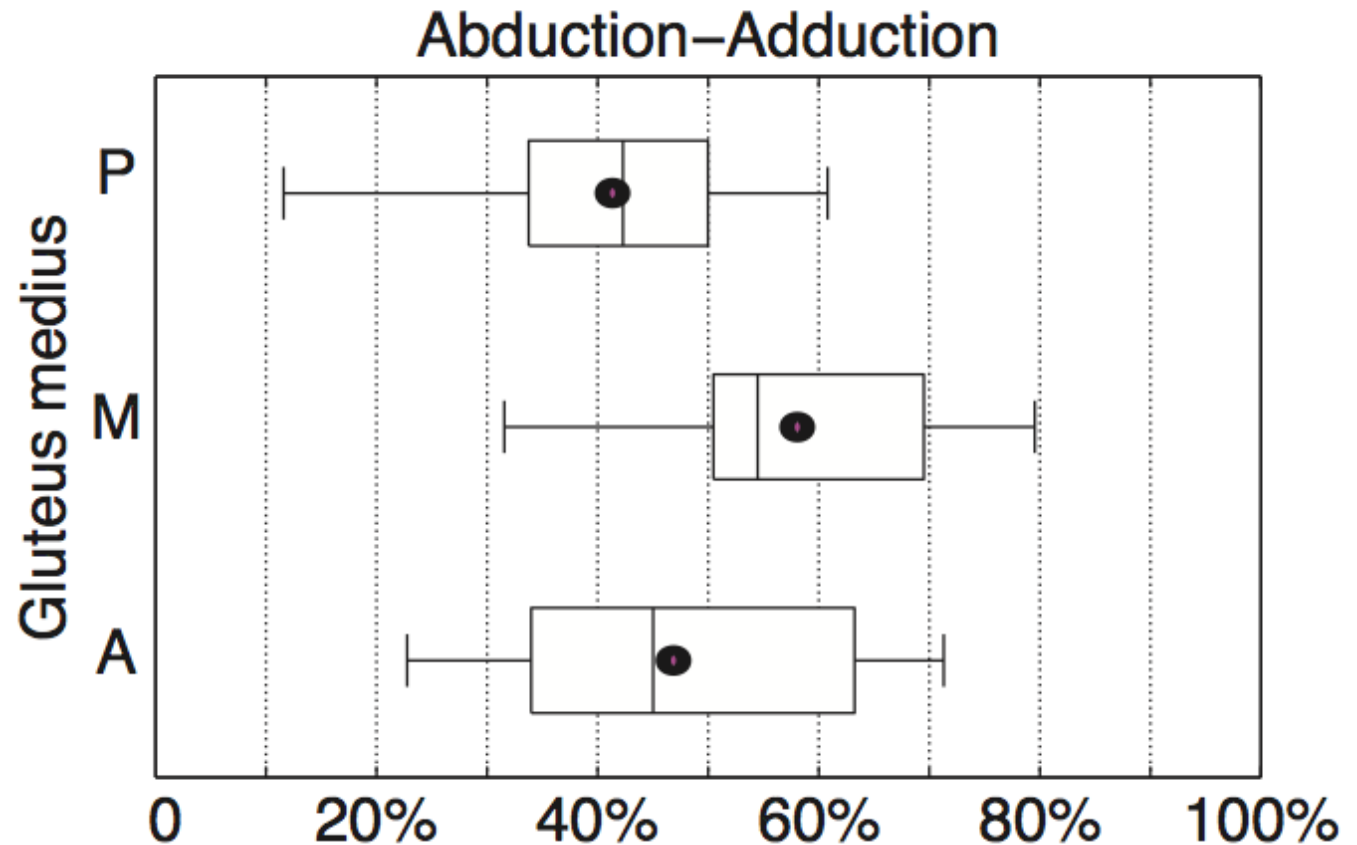


THA: cup medialization



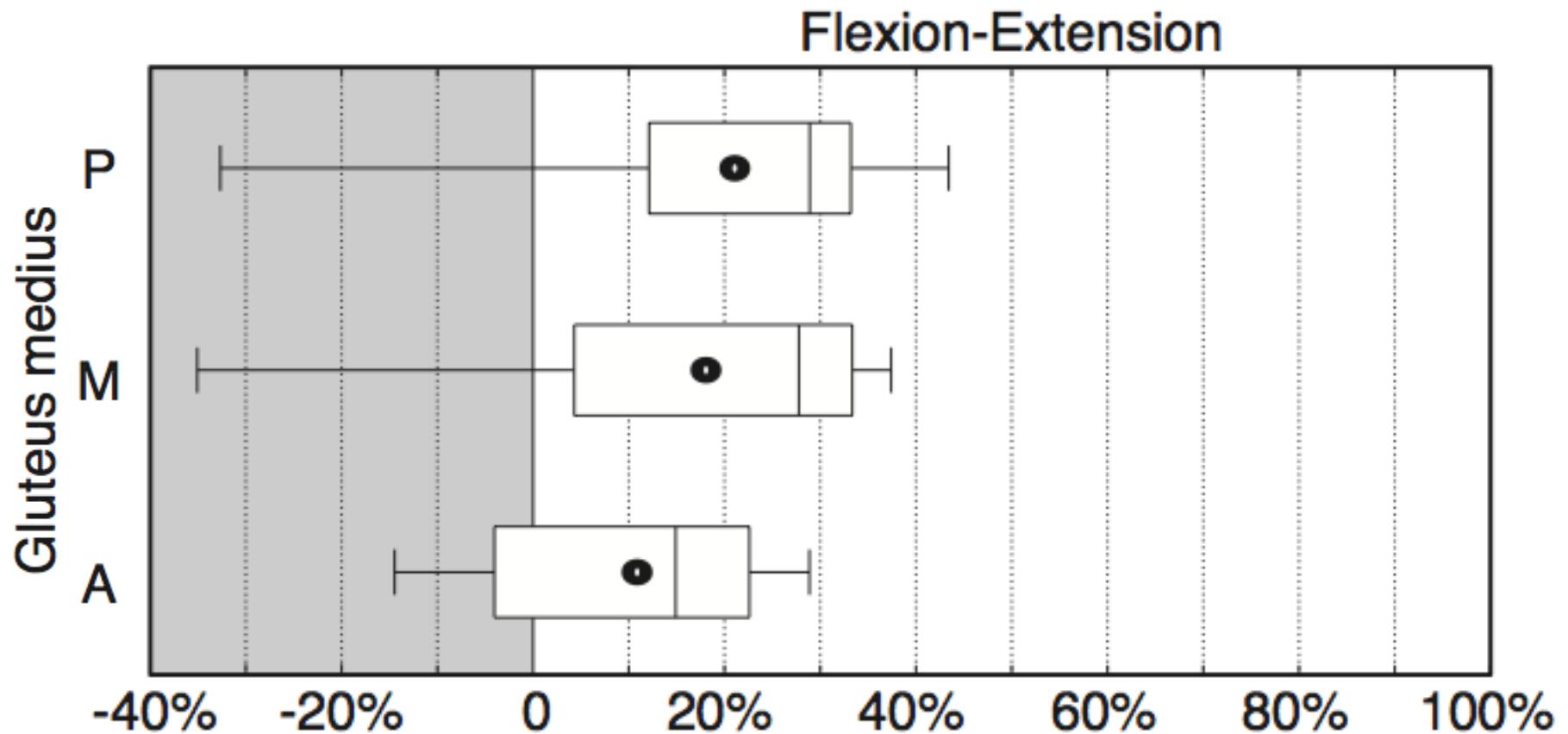
THA: cup medialization

Relative moment arm increase

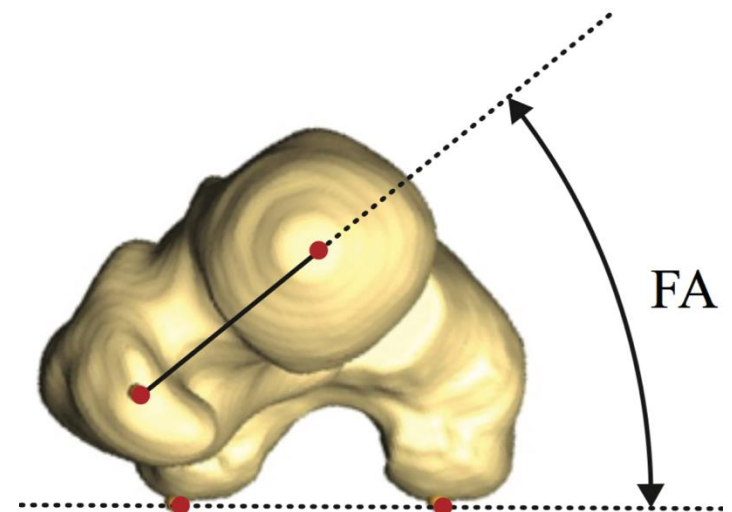
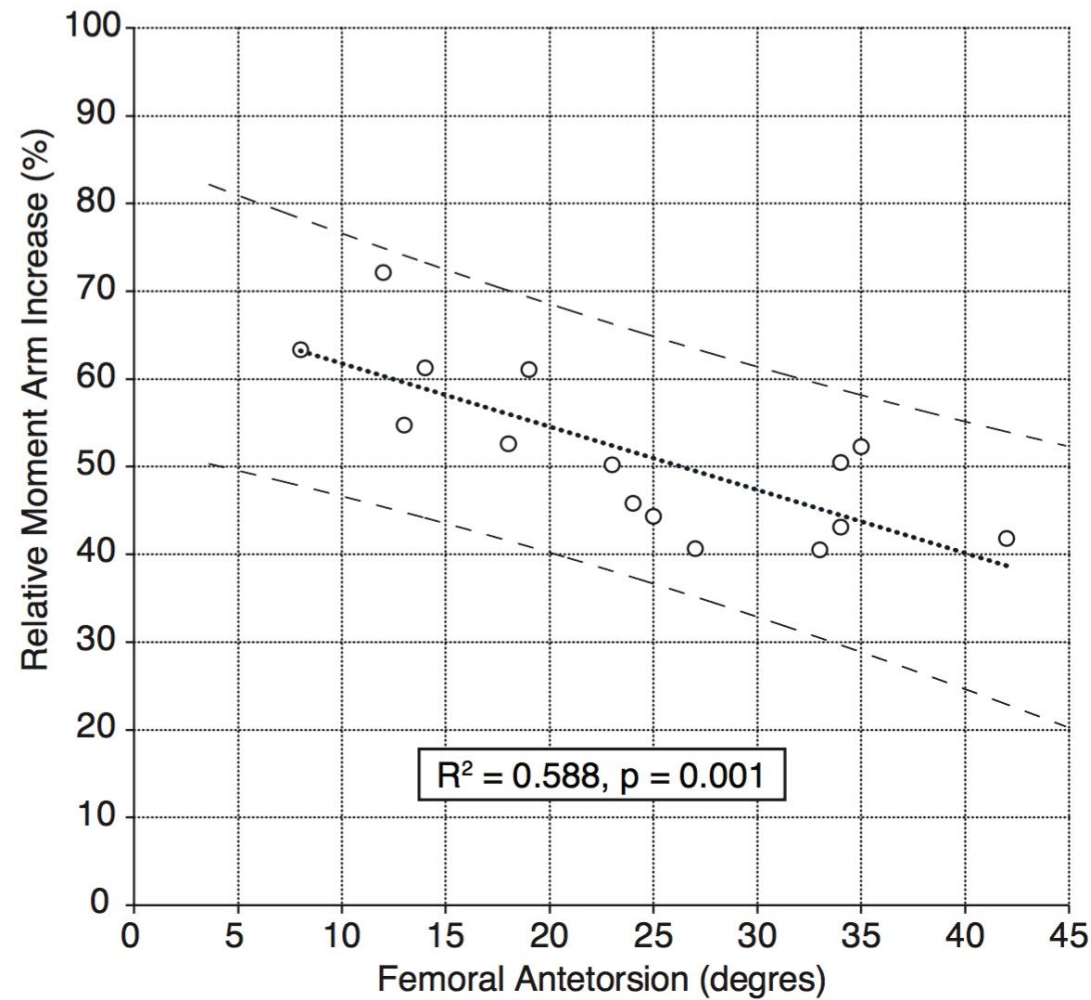


THA: cup medialization

Relative moment arm increase



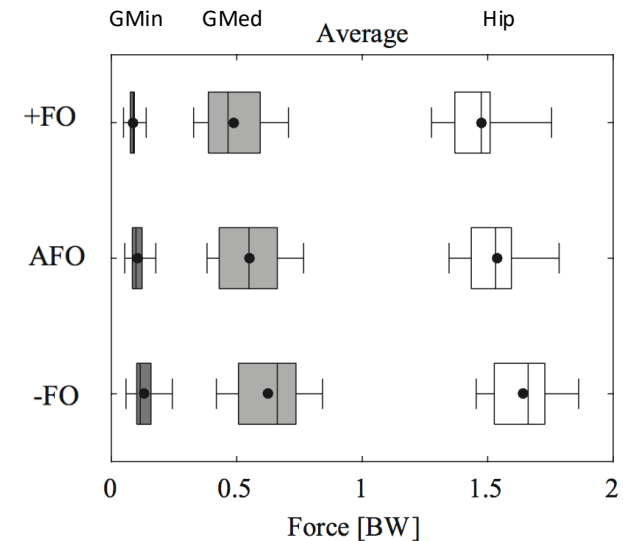
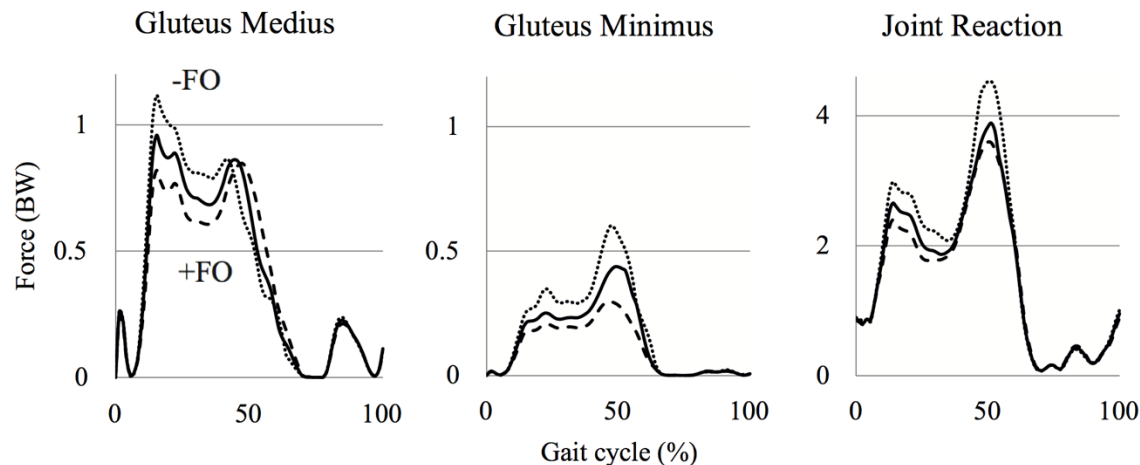
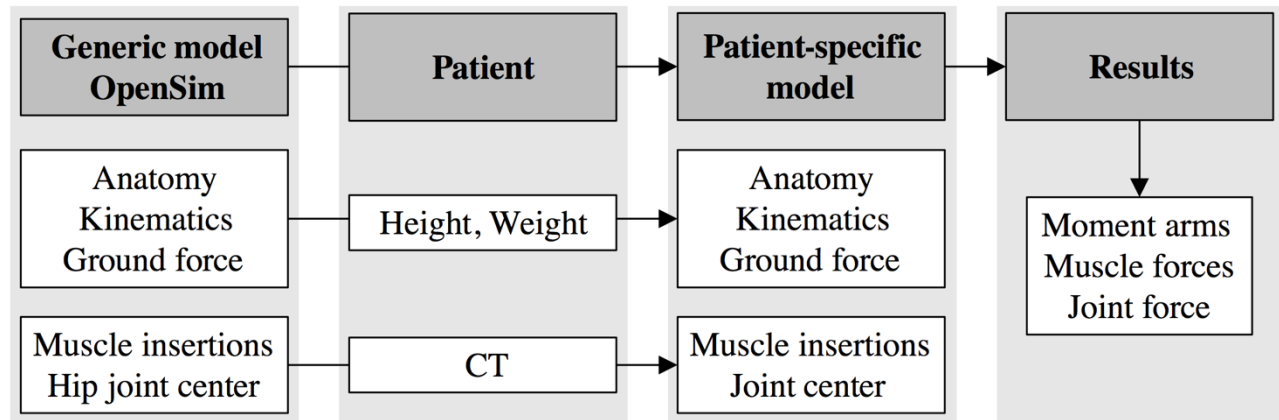
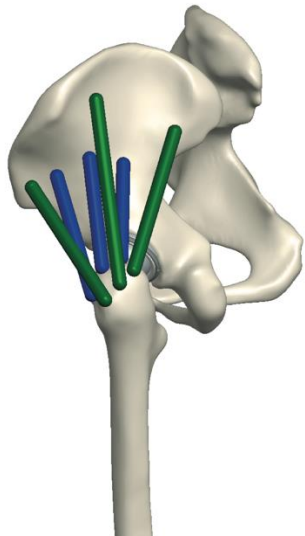
Correlation with anatomy



THA: cup medialization

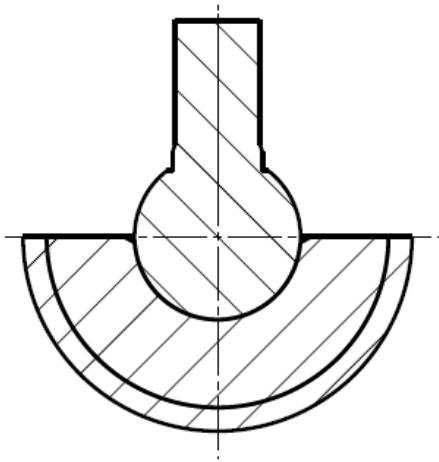
- Advantage of cup medialization quantified
- Statistical analysis on 15 patients
- Variable increase of moment arm
- Dependence of anatomical parameters
- Dependence on surgical technique?
- Surgical technique adapted to the patient
- Effect on forces

Effect of Femoral Offset on Forces

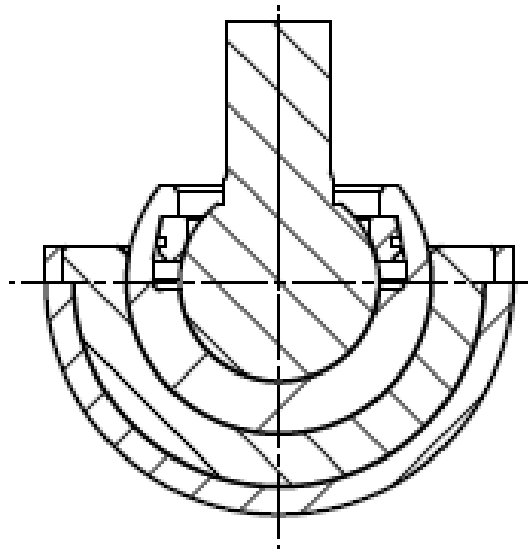


THA: Dual mobility

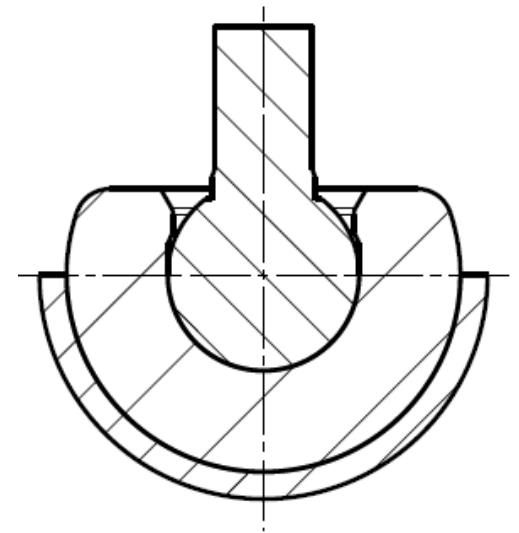
Conventional



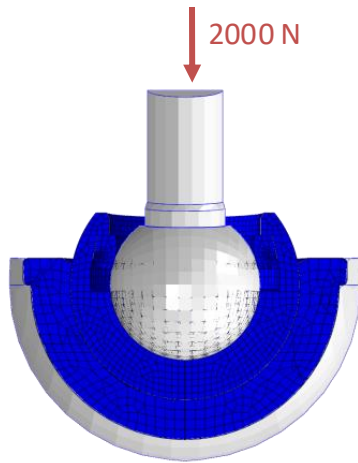
Constraint



Dual mobility

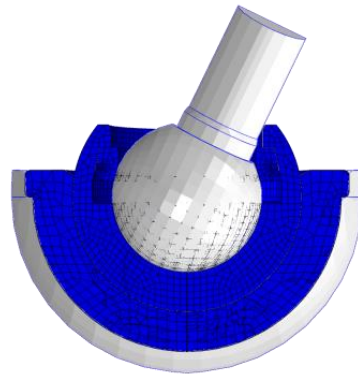


THA: Dual mobility

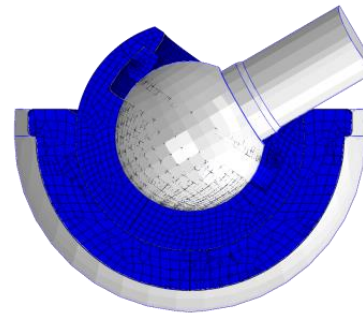


Embedded cupule

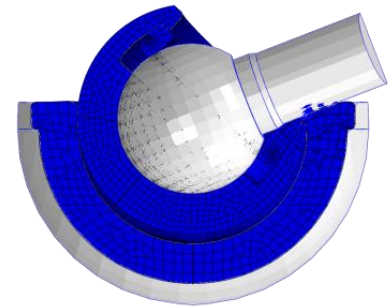
Start



2nd Mobility

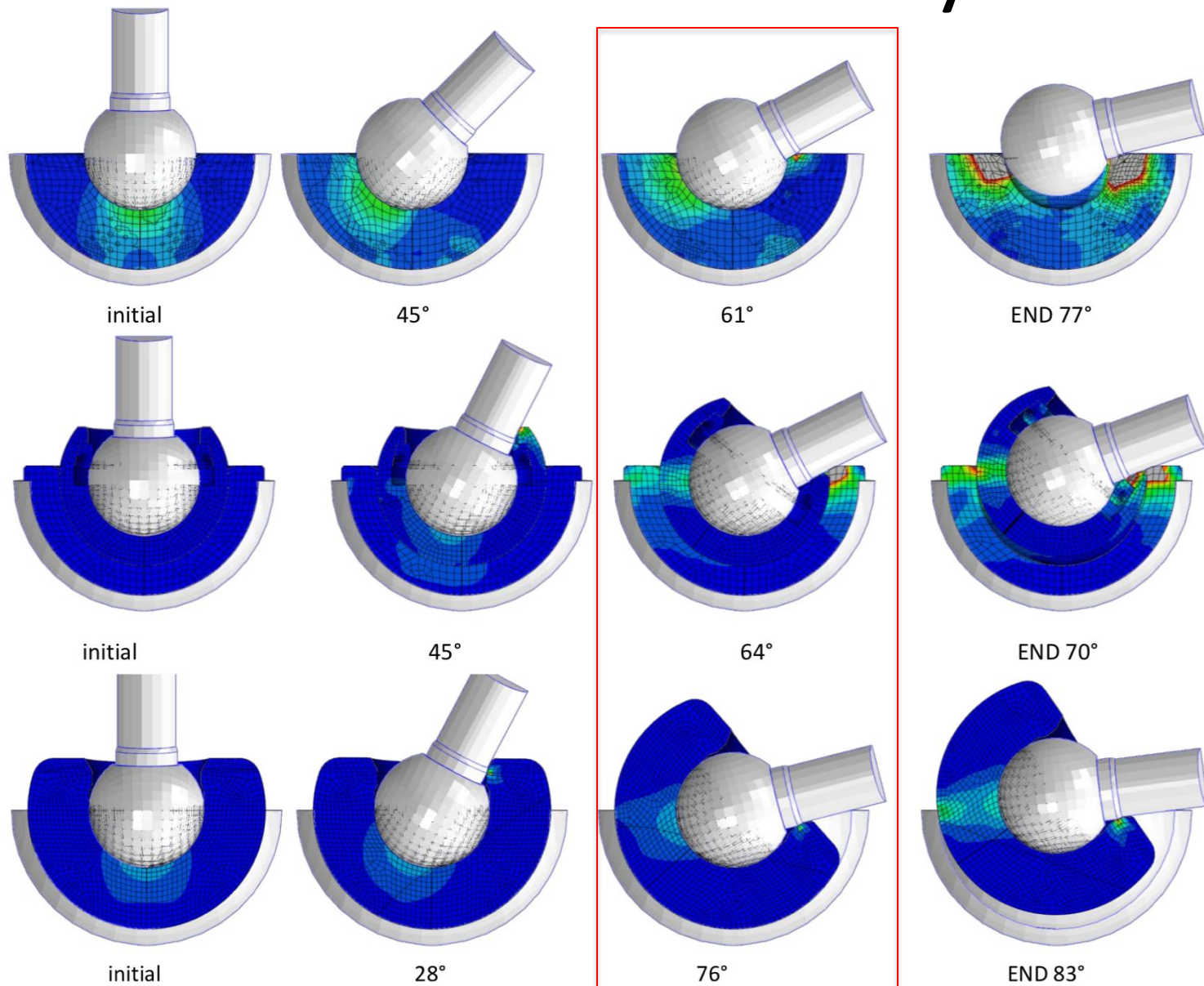


Impingement



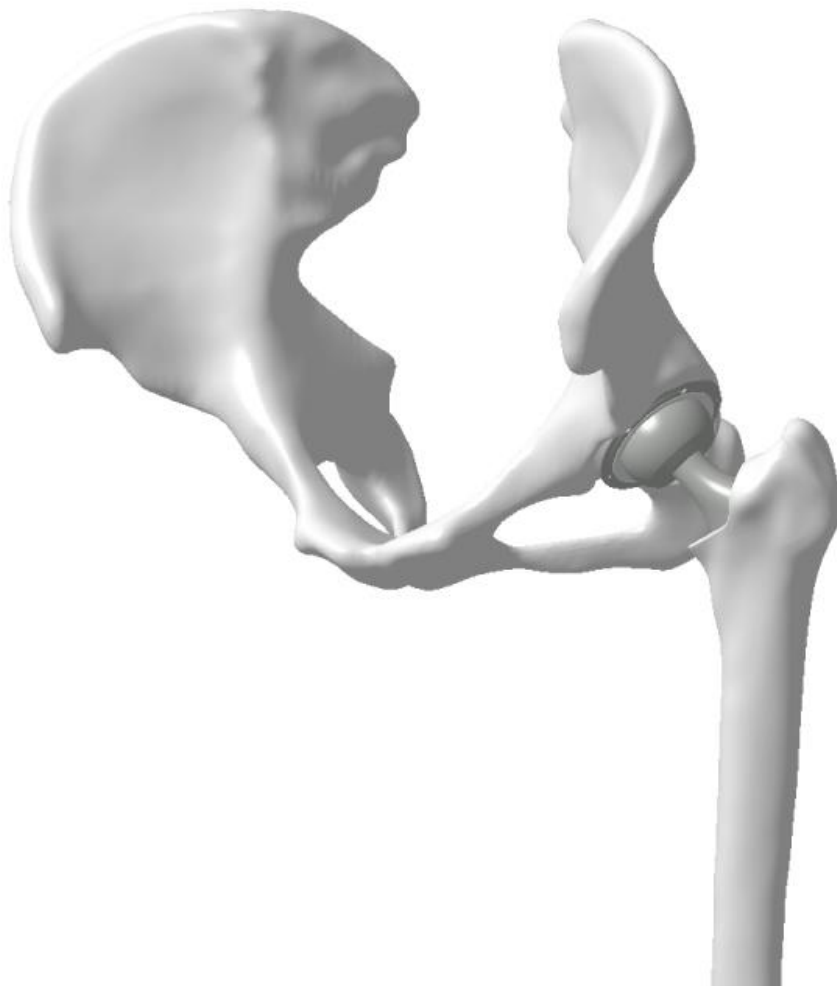
Subluxation

THA: Dual mobility

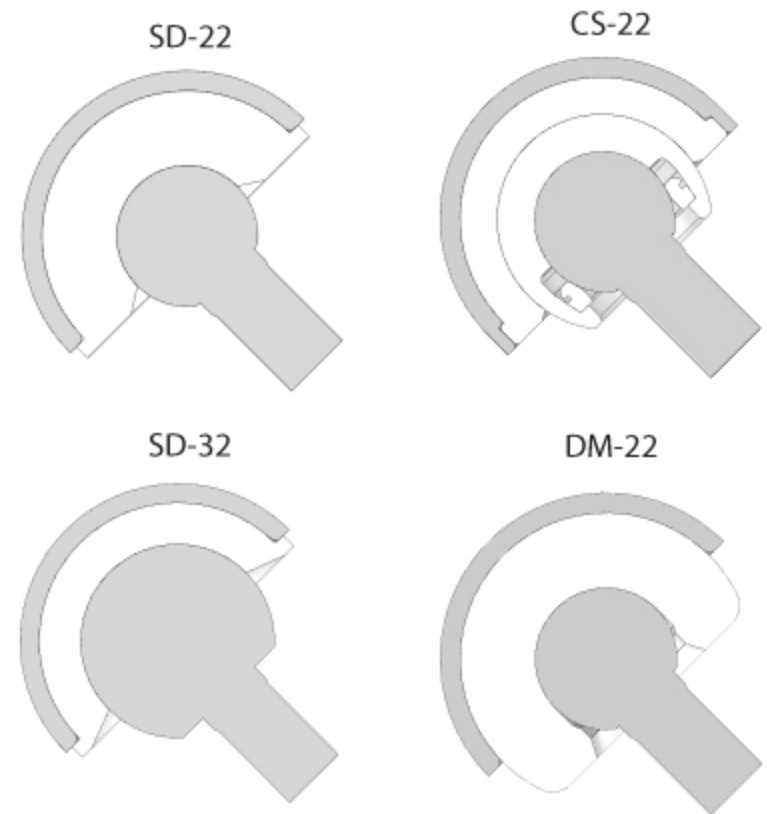


THA: Dual mobility

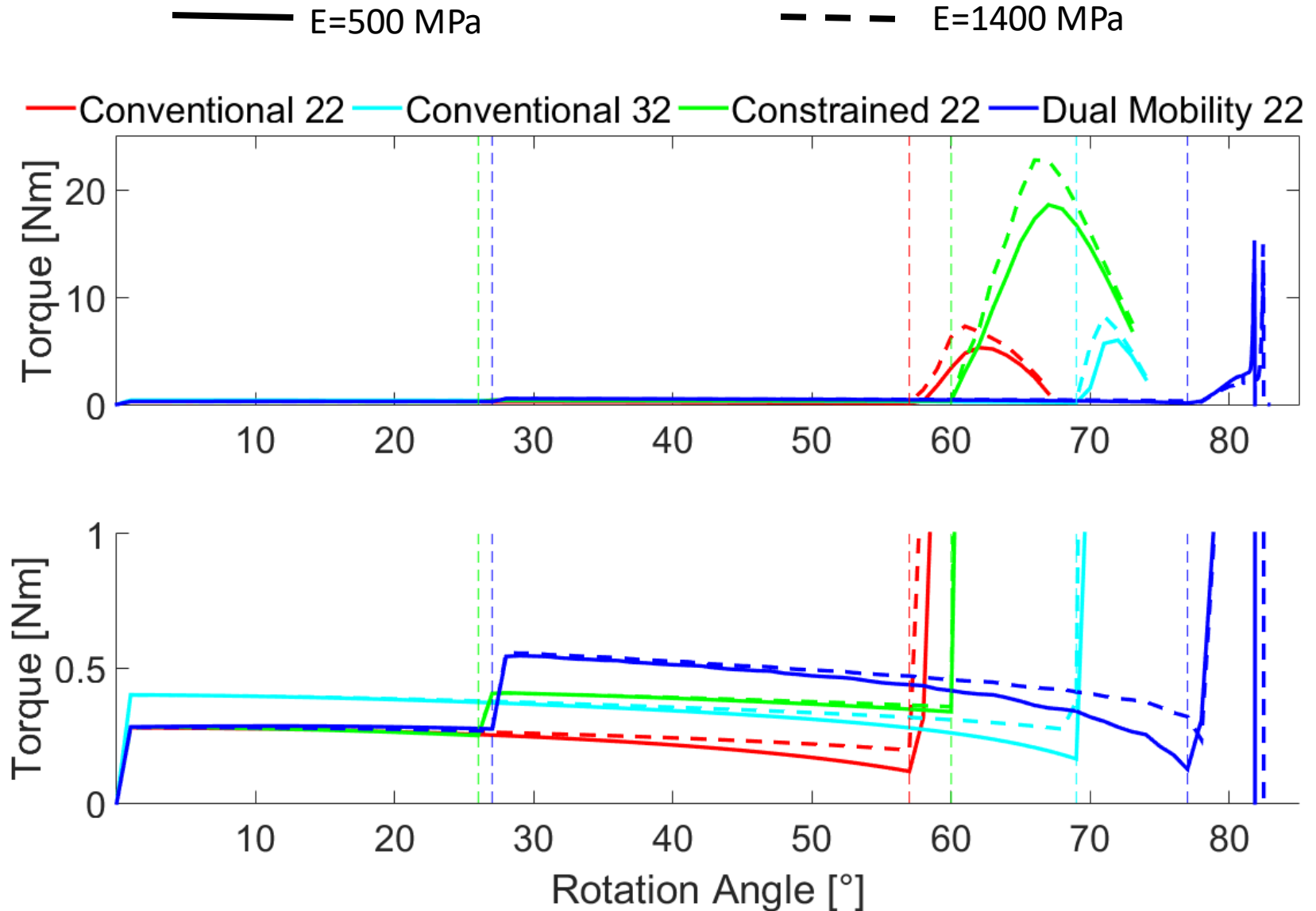
Reconstruction from patient CT



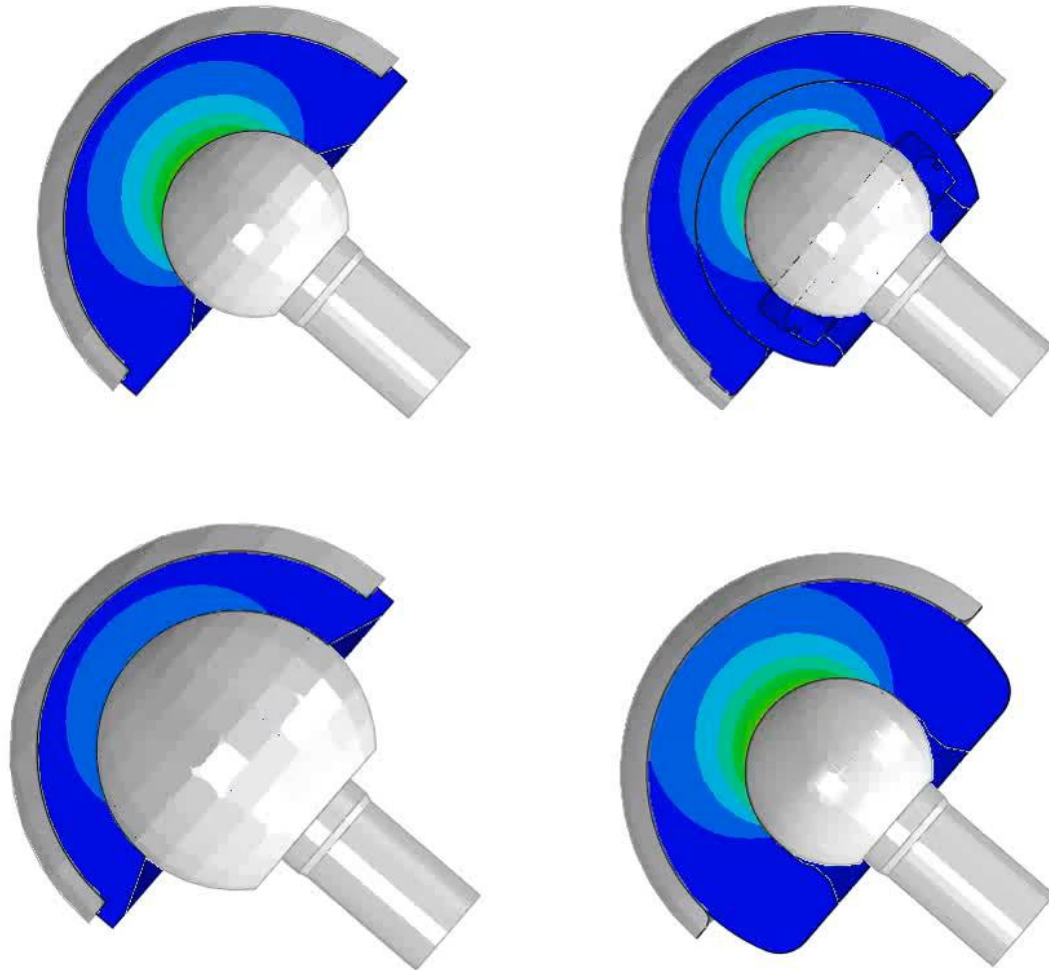
4 types of implants



THA: Dual mobility



THA: Dual mobility



THA: Dual mobility

Polyethylene yield stress

SD-22
(100%)



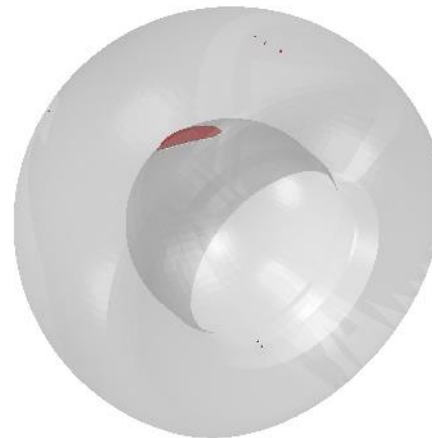
CS-22
(160%)



SD-32
(130%)



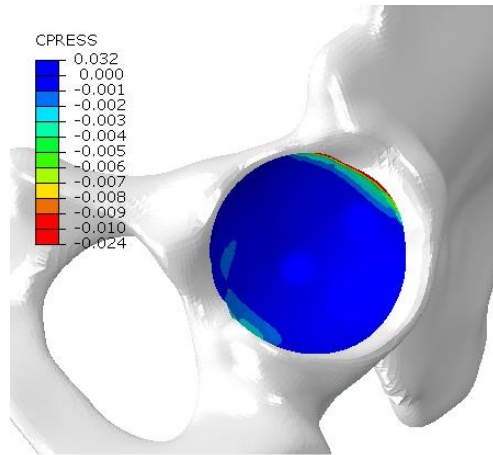
DM-22
(8%)



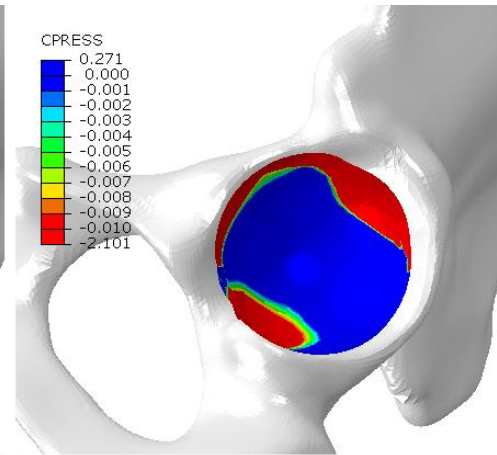
THA: Dual mobility

Bone-implant tension

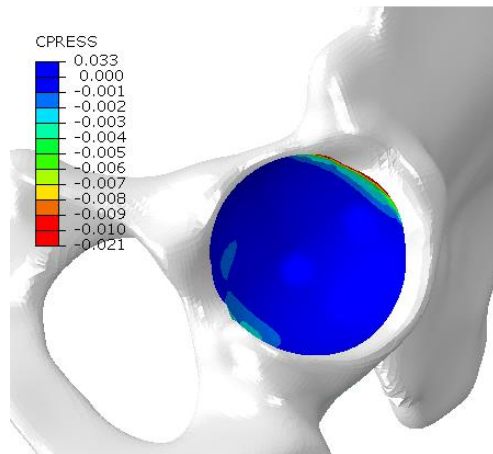
SD-22



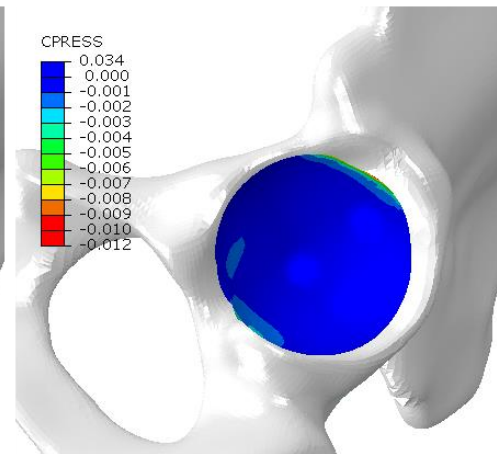
CS-22



SD-32



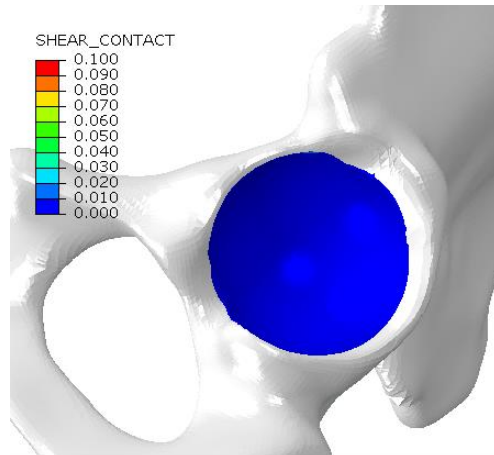
DM-22



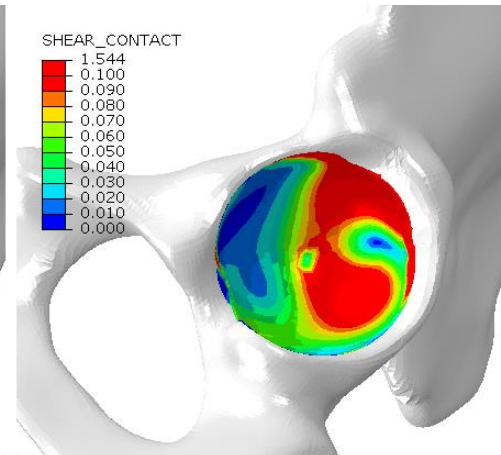
THA: Dual mobility

Bone-implant shear

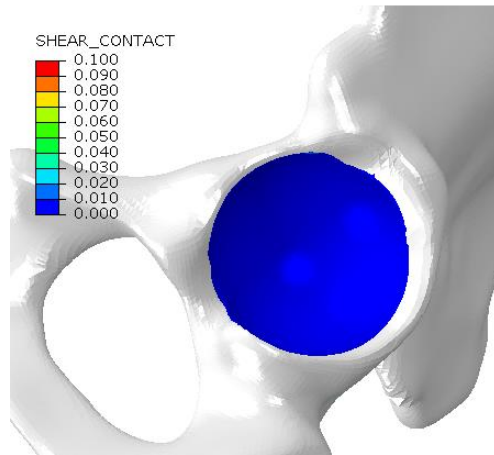
SD-22



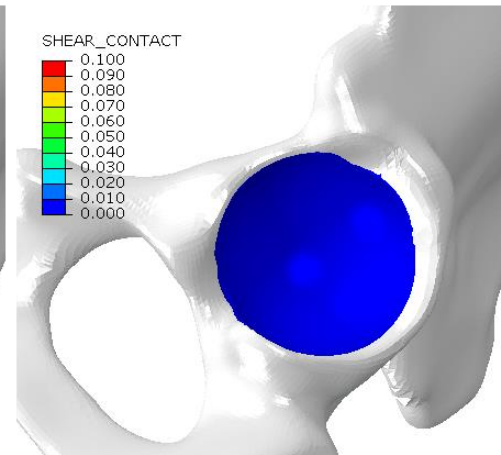
CS-22



SD-32



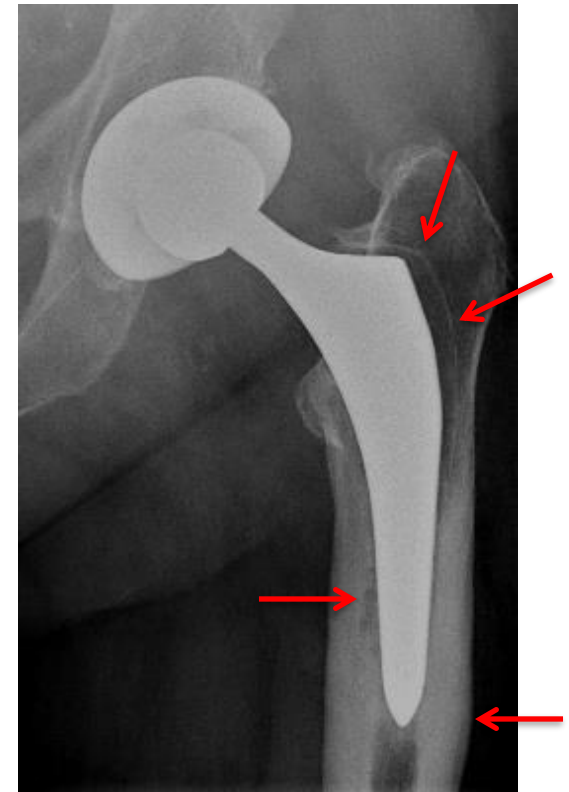
DM-22



Primary stability

Clinical Background

- Aseptic loosening is the main cause of revision of cementless THA
- Poor primary stability and excessive micromotions at the bone-implant interface promotes aseptic loosening¹



¹ Engh et al. CORR 1992;285:13-29.

Reason for Revision

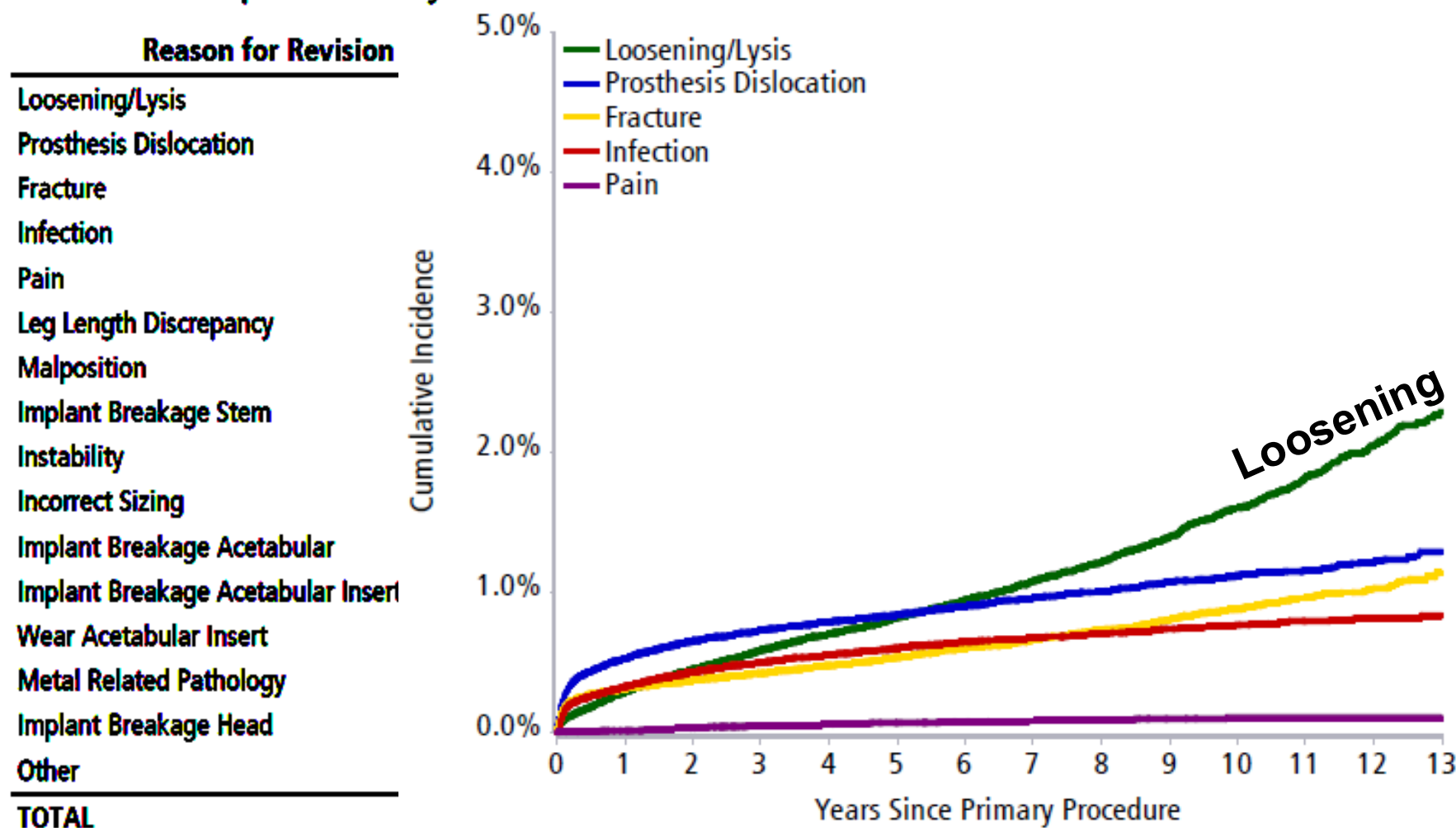
Table HT10: Primary Total Conventional Hip Replacement by Reason for Revision

Reason for Revision	Number	Percent
Loosening/Lysis	2550	28.4
Prosthesis Dislocation	2251	25.0
Fracture	1576	17.5
Infection	1534	17.1
Pain	168	1.9
Leg Length Discrepancy	122	1.4
Malposition	108	1.2
Implant Breakage Stem	82	0.9
Instability	77	0.9
Incorrect Sizing	73	0.8
Implant Breakage Acetabular	72	0.8
Implant Breakage Acetabular Insert	69	0.8
Wear Acetabular Insert	58	0.6
Metal Related Pathology	49	0.5
Implant Breakage Head	26	0.3
Other	179	2.0
TOTAL	8994	100.0

Australian Joint Registry – Annual Report 2014

Reason for Revision

Table HT10: Primary Total Conventional Hip Replacement by Reason for Revision



Australian Joint Registry – Annual Report 2014

Micromotion, Gap, subsidence

- Micromotion > 150 μm : connective tissue
 - Micromotion > 40 μm : bone ingrowth
 - Gap > 500 μm : delayed & reduced bone quality
 - Subsidence > 5 mm : delayed/no bone ingrowth
-
- Pilliar, R.M., J.M. Lee, and C. Maniopoulos, Observations on the effect of movement on bone ingrowth into porous-surfaced implants. Clin Orthop Relat Res, 1986(208): p. 108-13.
 - Jasty, M., C. Bragdon, D. Burke, D. O'Connor, J. Lowenstein, and W.H. Harris, In vivo skeletal responses to porous-surfaced implants subjected to small induced motions. J Bone Joint Surg Am, 1997. 79(5): p. 707-14.
 - Soballe, K., E.S. Hansen, H. Brockstedt-Rasmussen, and C. Bunger, Hydroxyapatite coating converts fibrous tissue to bone around loaded implants. J Bone Joint Surg Br, 1993. 75(2): p. 270-8.
 - Mavrogenis, A.F., R. Dimitriou, J. Parvizi, and G.C. Babis, Biology of implant osseointegration. J Musculoskelet Neuronal Interact, 2009. 9(2): p. 61-71.
 - Engh, C.A., P. Massin, and K.E. Suthers, Roentgenographic assessment of the biologic fixation of porous-surfaced femoral components. Clin Orthop Relat Res, 1990(257): p. 107-28.
 - Goodman S, Aspenberg P. Effects of mechanical stimulation on the differentiation of hard tissues. Biomaterials. 1993;14:563-9

In vitro



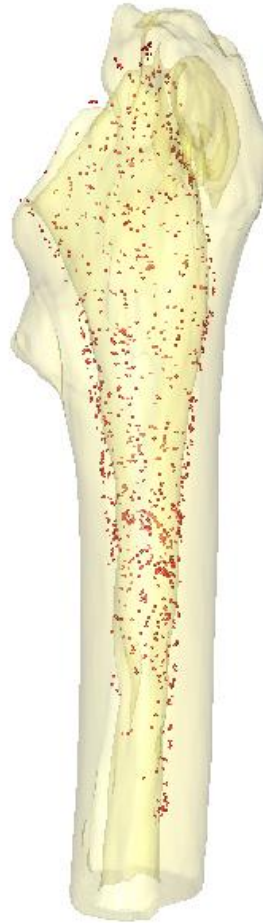
Bone & Stem markers

Bone

~ 1000 markers

Stainless steel beads

Ø 600 µm

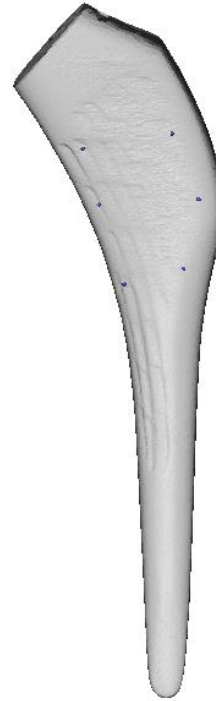


Stem

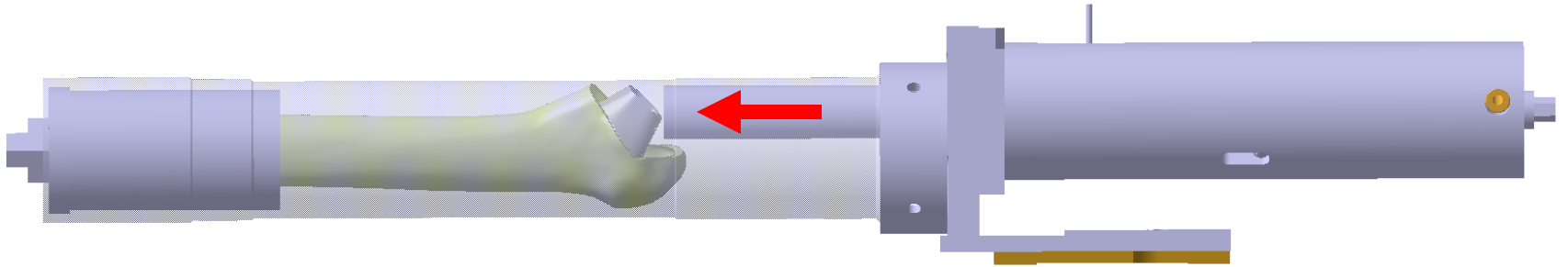
6 markers

Tantalum beads

Ø 800 µm

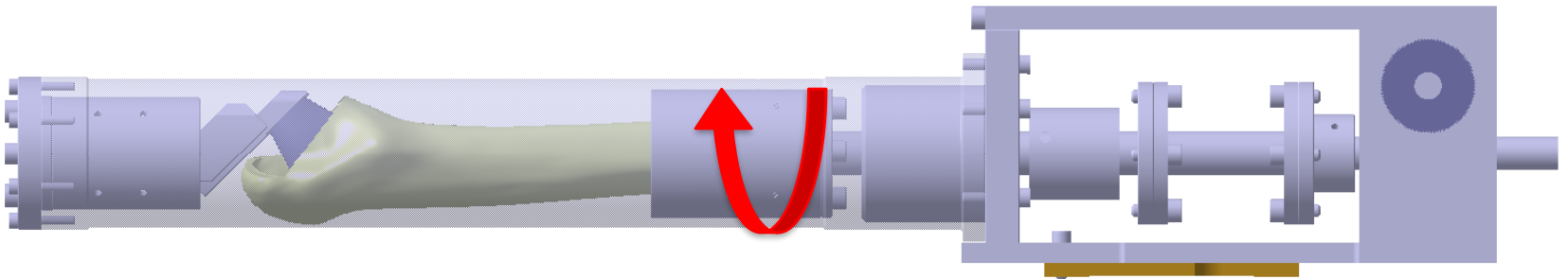


Compression device



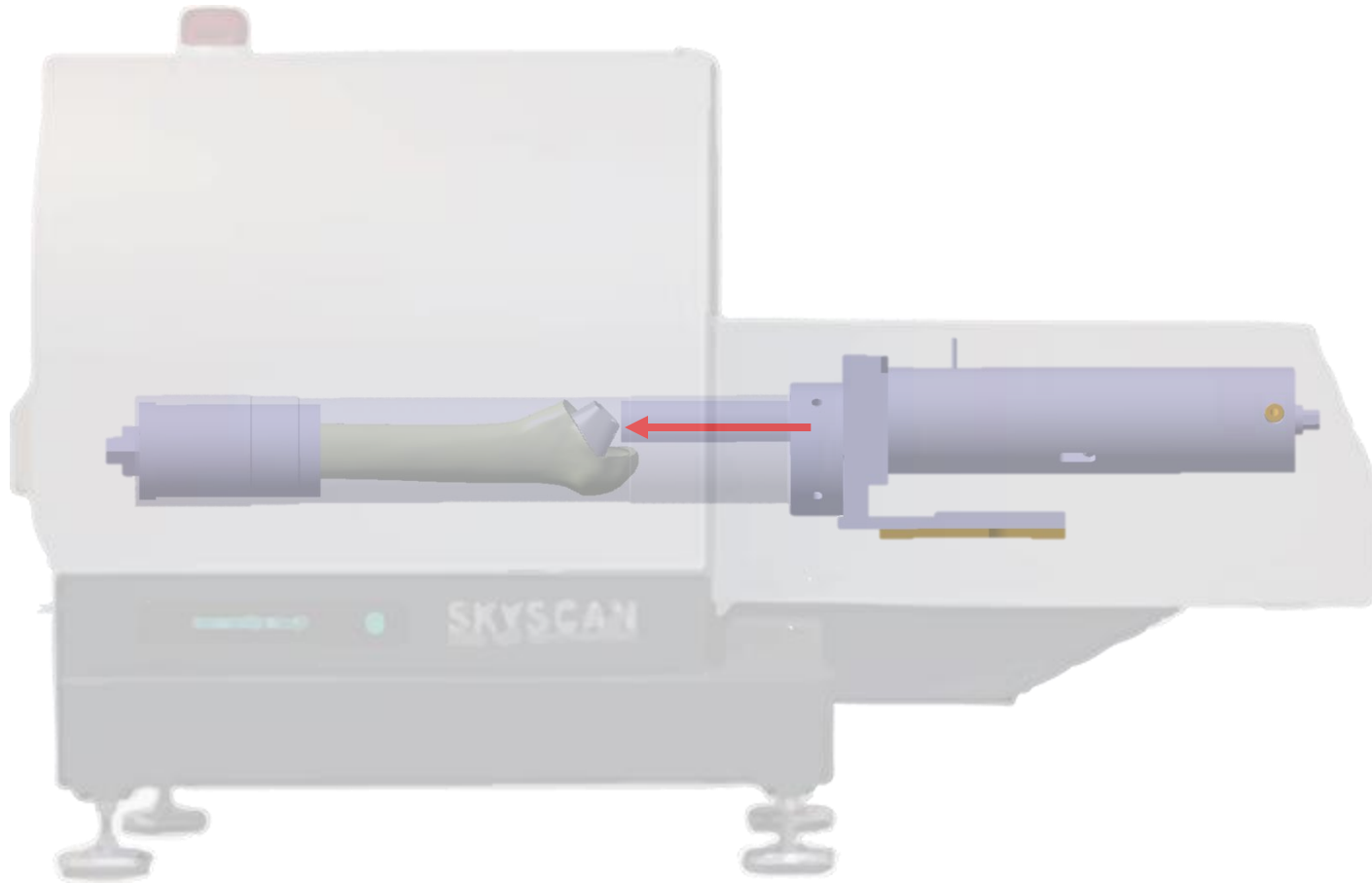
Compression 1800 N

Torsion device



Torsion 14 Nm

Micro-CT



Malfroy Camine V. et al., 2014, ORS 2014 Annual Meeting

4 μ CTs



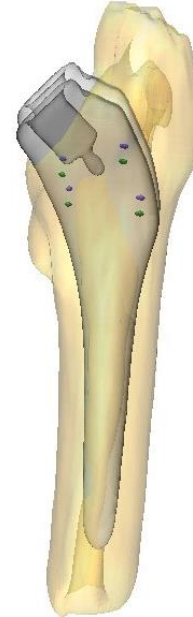
μ CT 1:
no load



μ CT 2:
no load



μ CT 3:
load



μ CT 4:
no load

Error

μ CT 2 – μ CT 1

Micromotion

μ CT 4 – μ CT 3

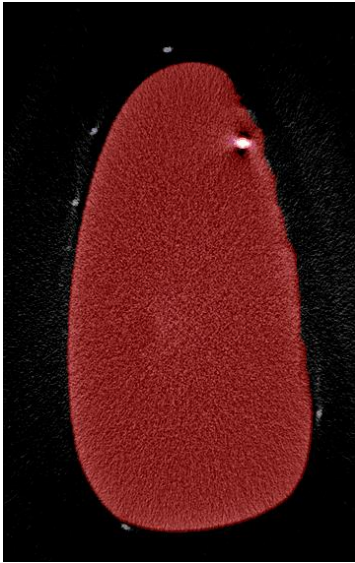
Gap

μ CT 4

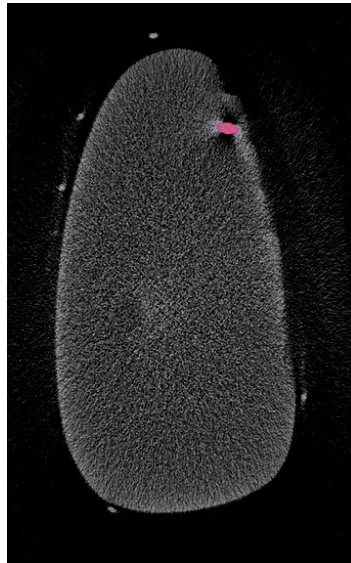
Subsidence

μ CT 4 – μ CT 2

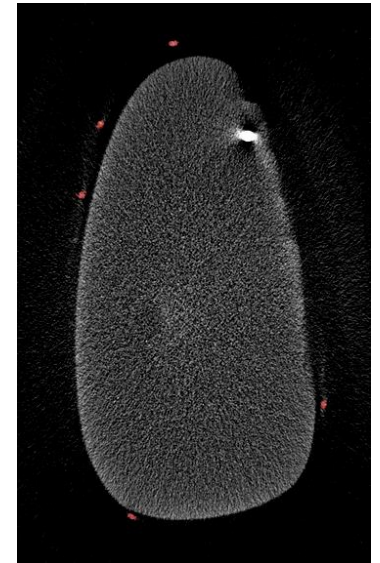
Segmentation



Stem

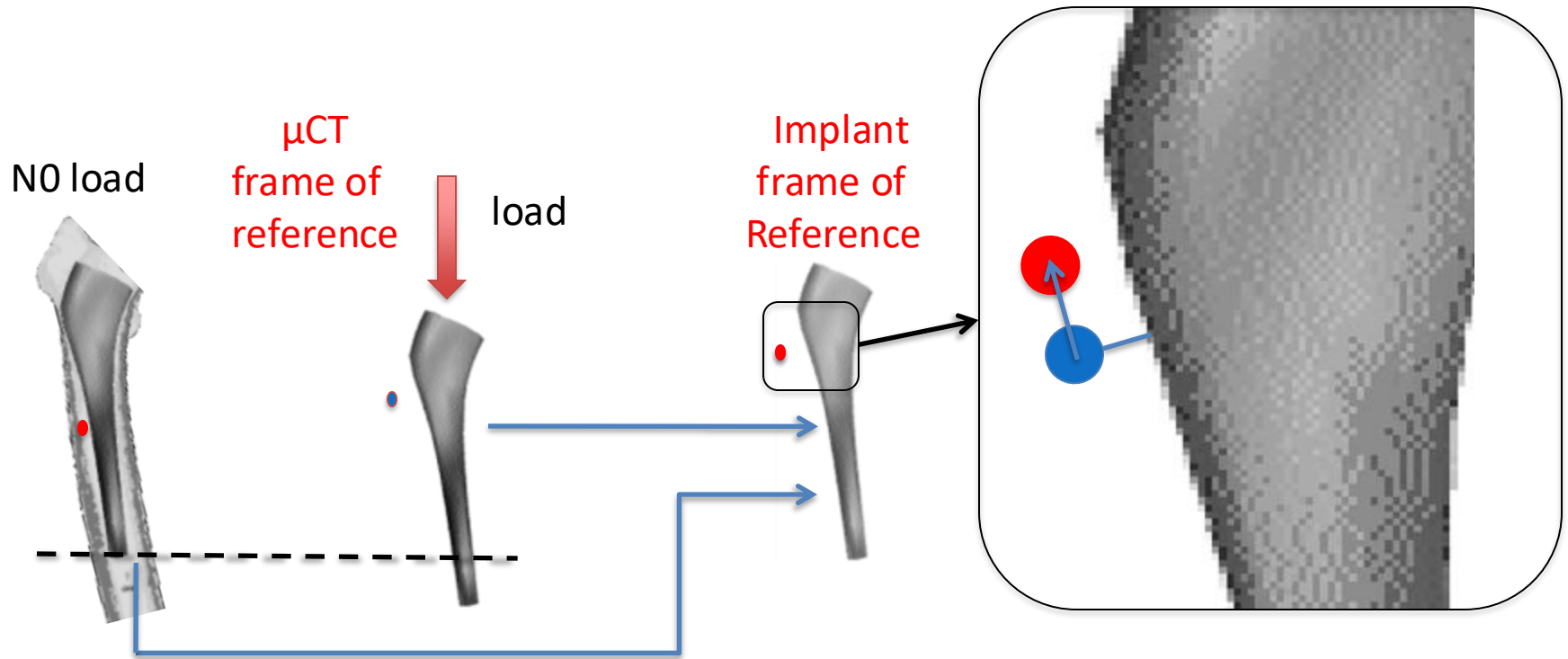


Stem markers

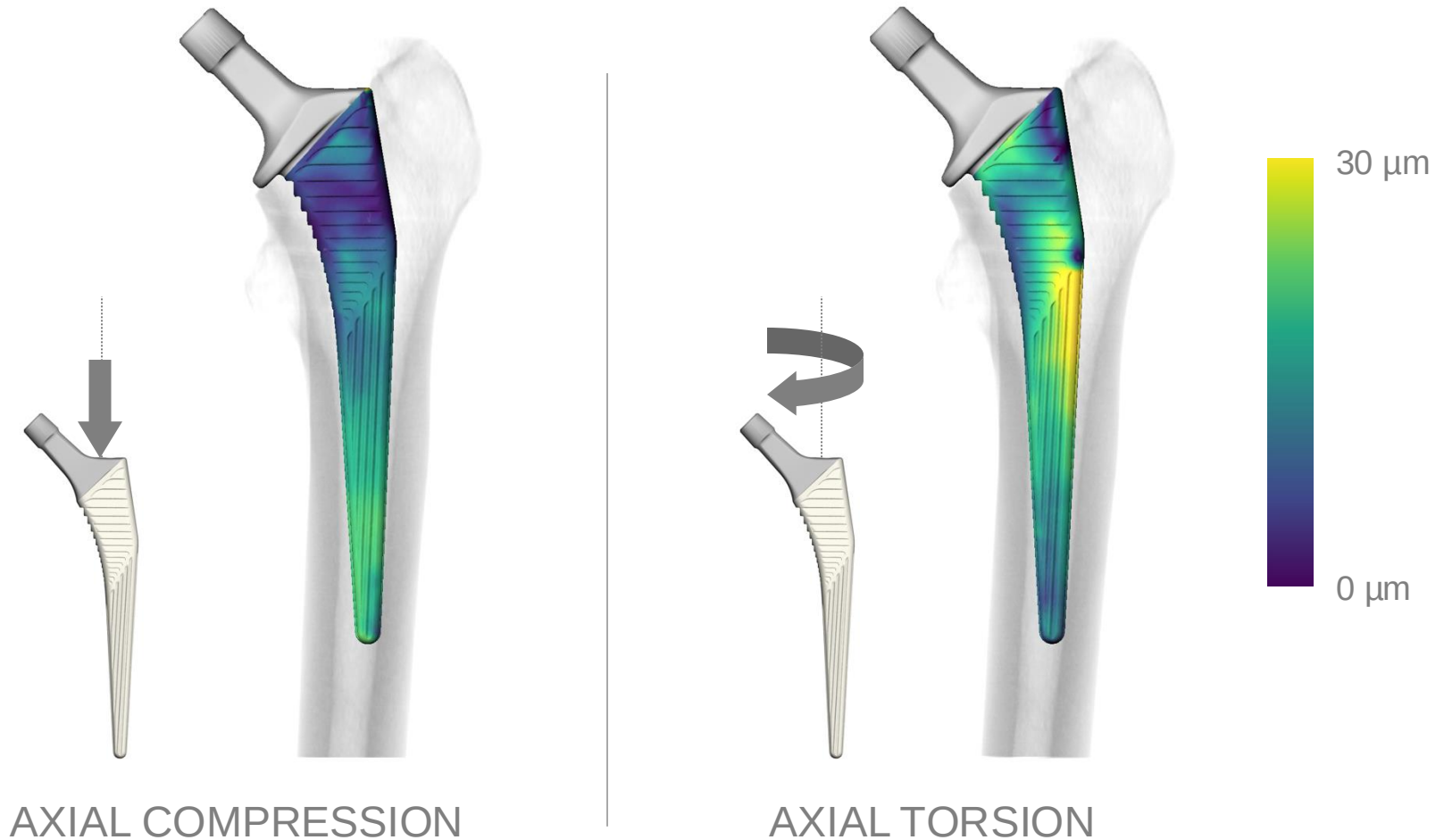


Bone markers

Micromotions



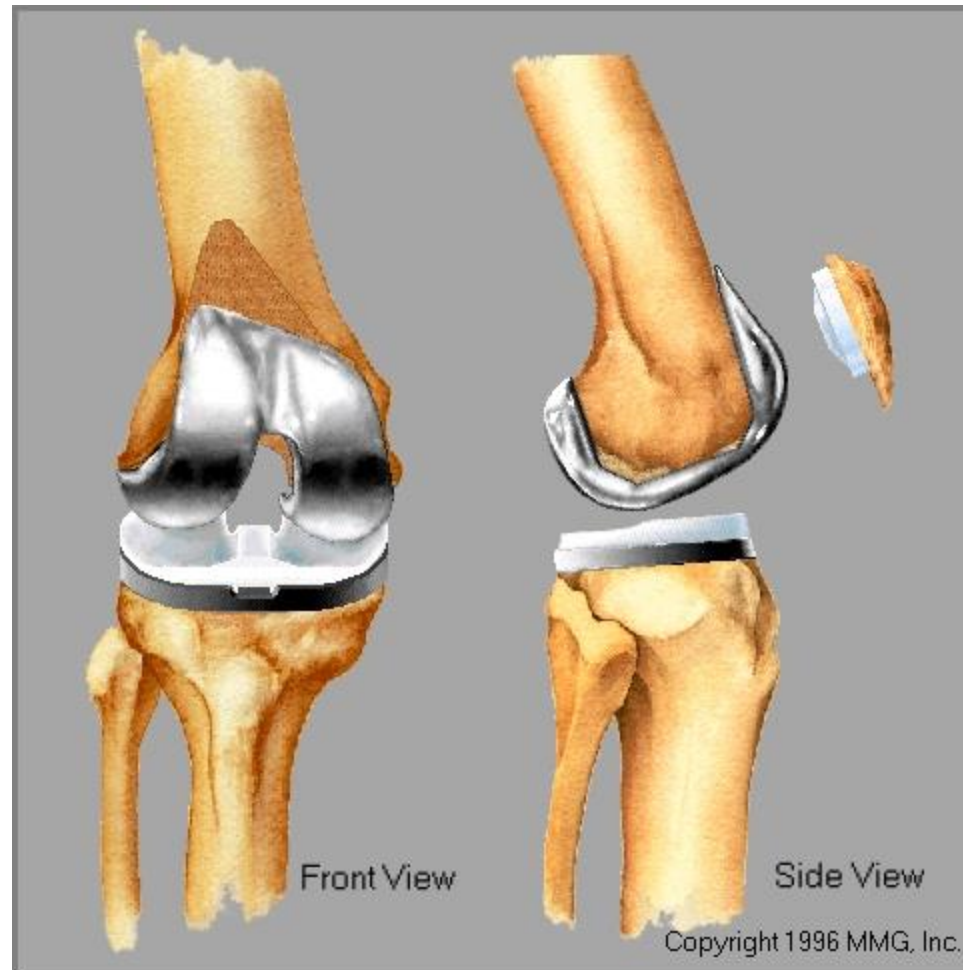
Micromotion



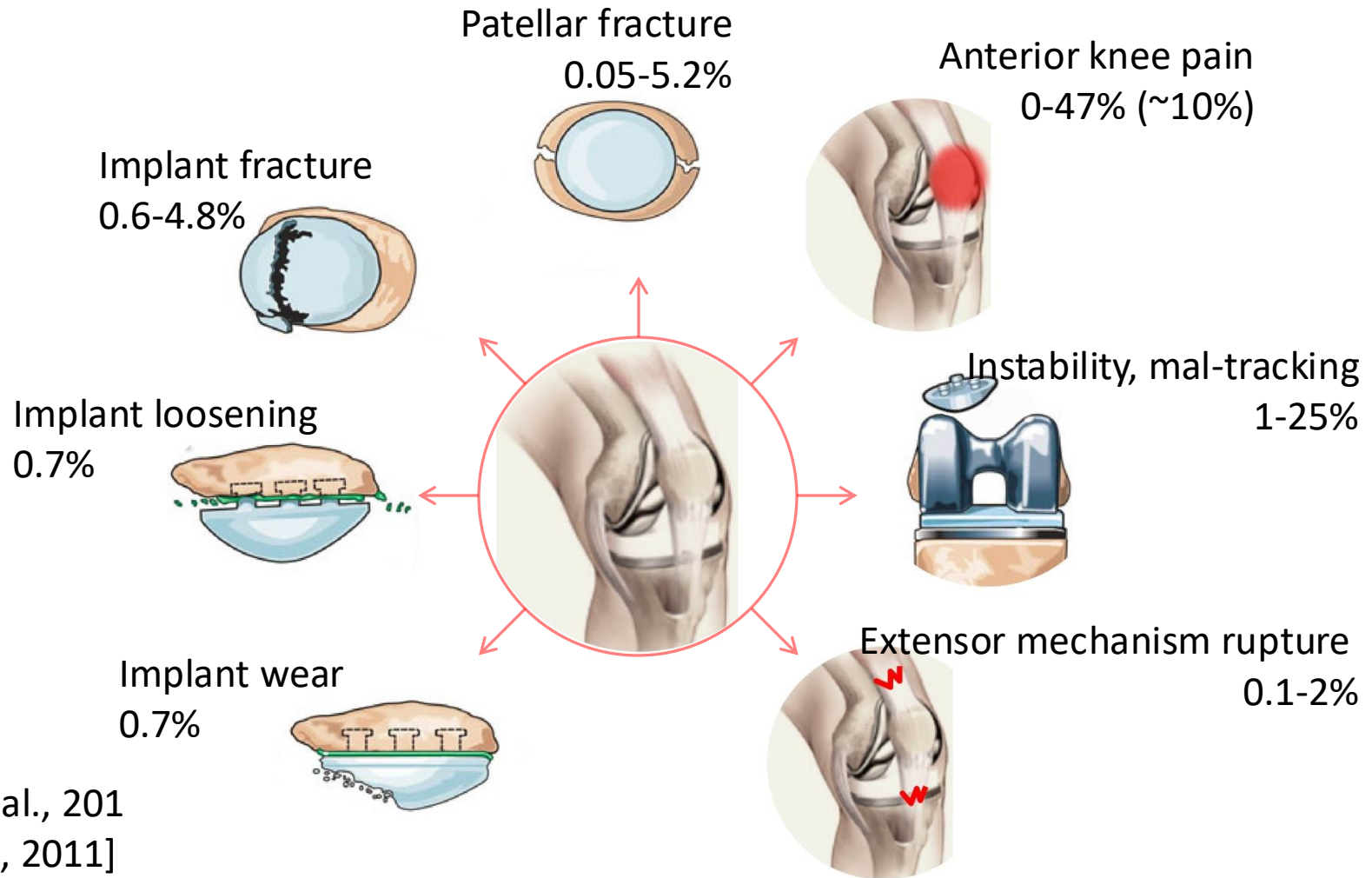
Comparisons of design philosophies



Total Knee Arthroplasty (TKA)



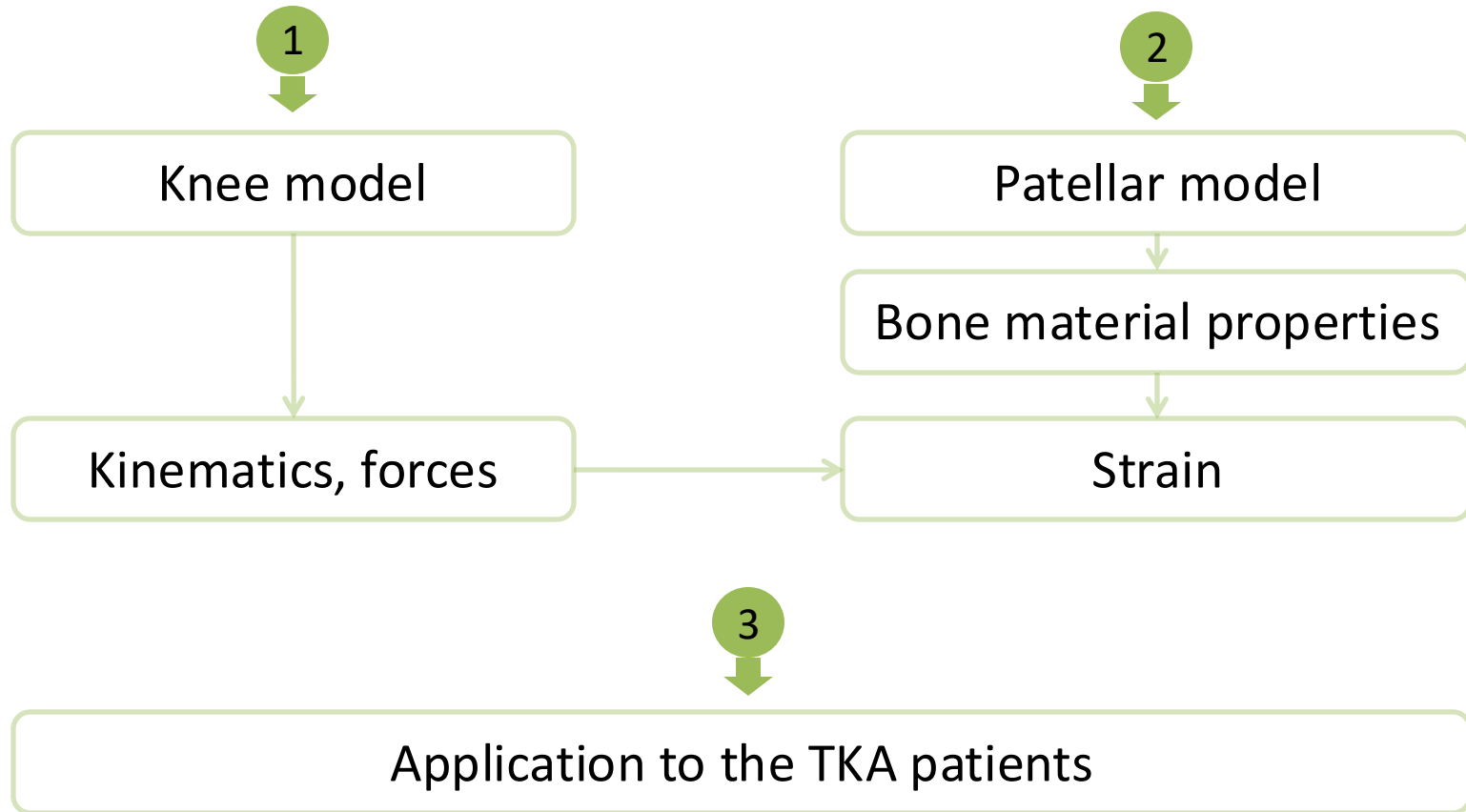
TKA: patella problem



[Bozic et al., 201
[He et al., 2011]
[Schindler, 2012]
[Sundberg et al., 2014]
[Kurtz et al., 2007, 2011]

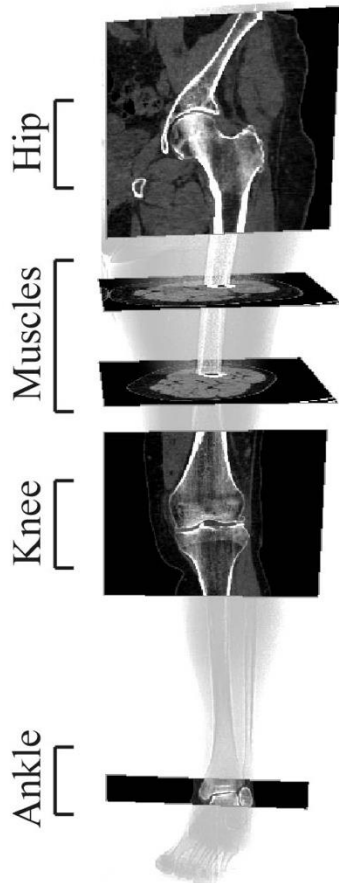
~ 1.1 million TKA per year in USA and Europe!
↑ number of young and active patients

Patient-specific TKA model for patella

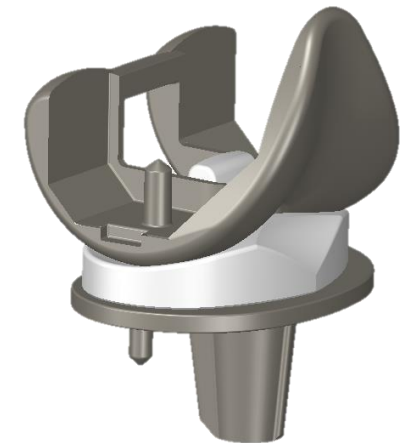
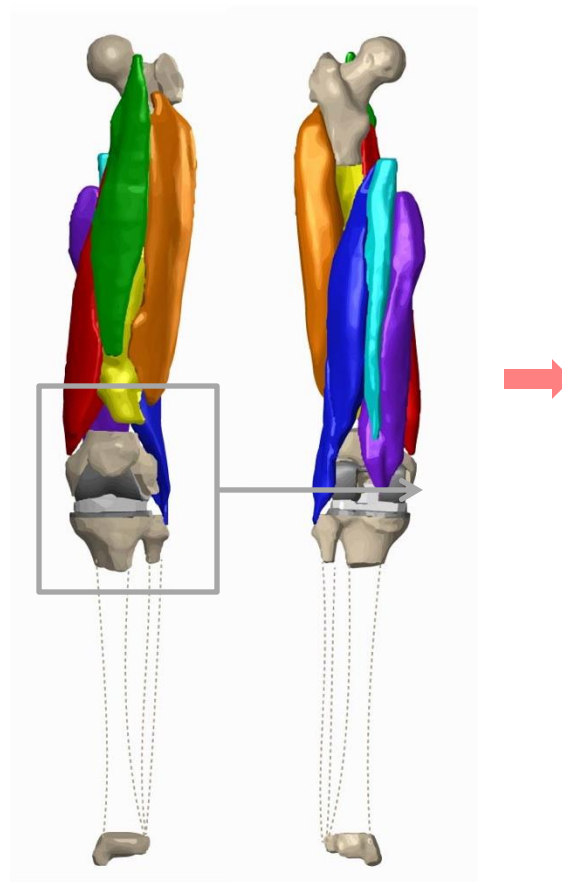


KNEE MODEL: GEOMETRY

CT protocol



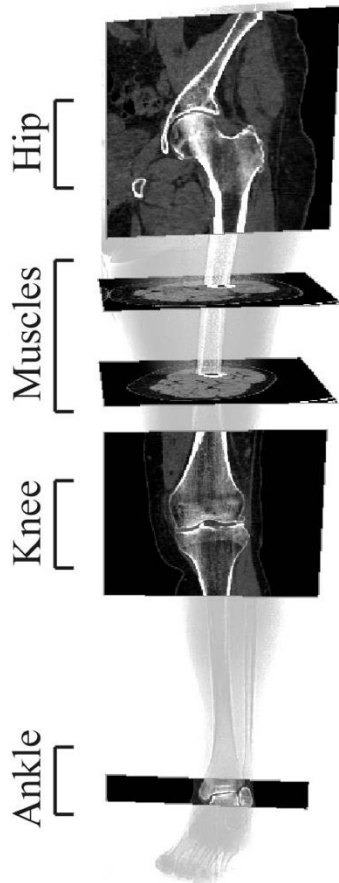
Geometry reconstruction
Implant positioning



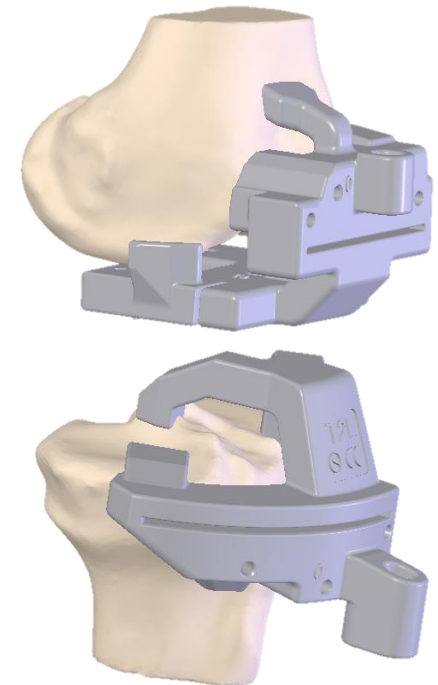
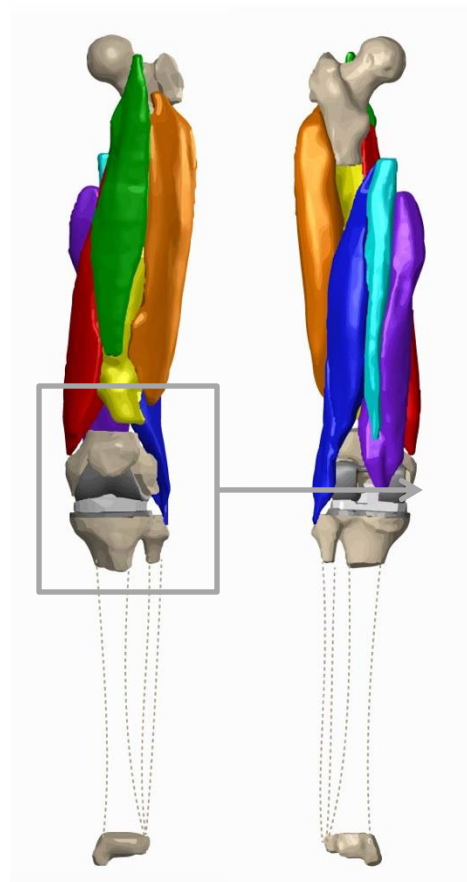
- Ultra-congruent
- Mobile-bearing
- Resurfaced patella

KNEE MODEL: GEOMETRY

CT protocol



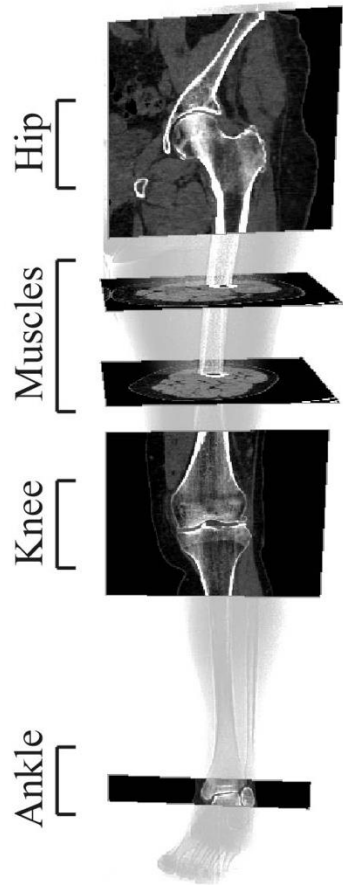
Geometry reconstruction
Implant positioning



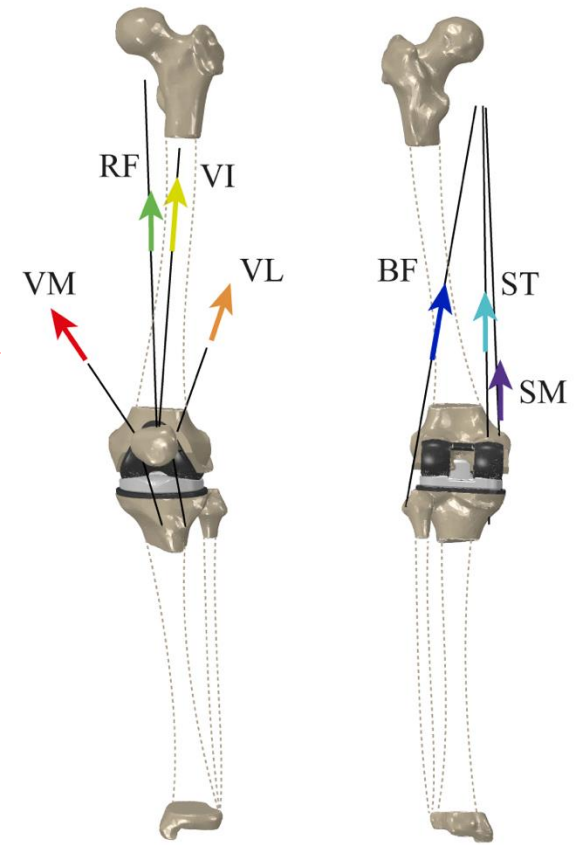
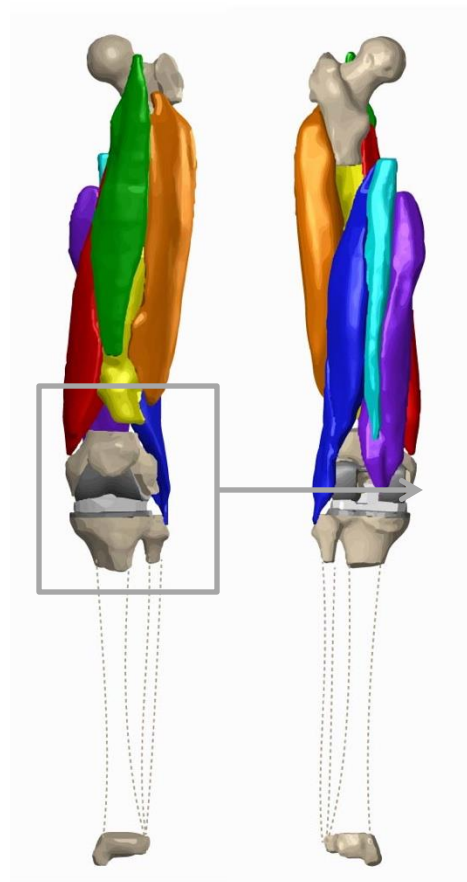
- patient-specific cutting tools

KNEE MODEL: GEOMETRY

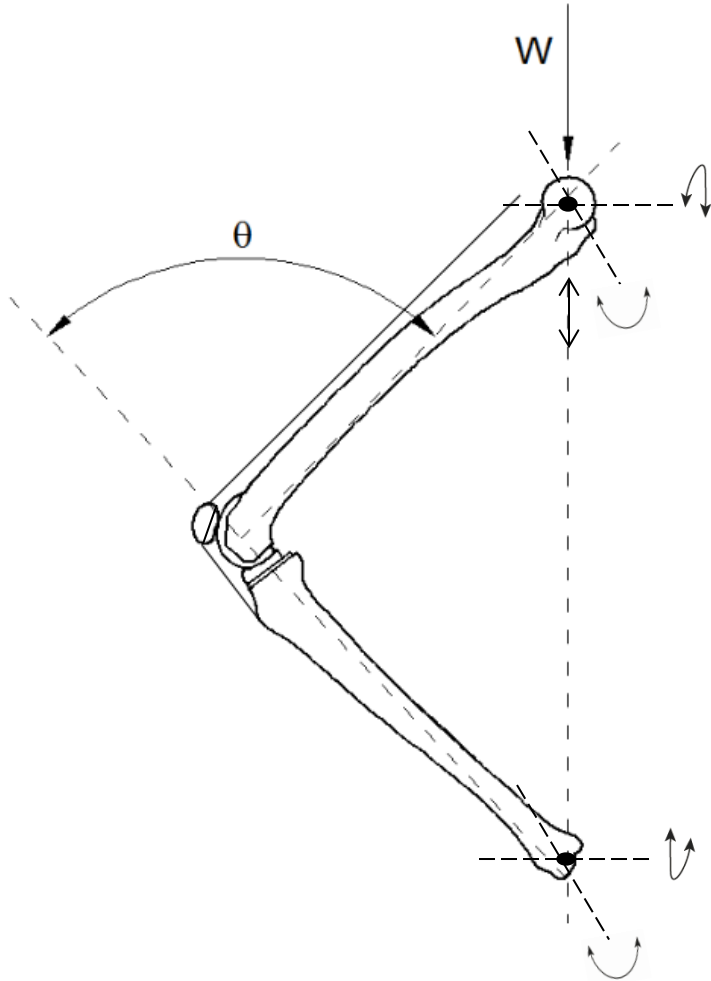
CT protocol



Geometry reconstruction
Implant positioning

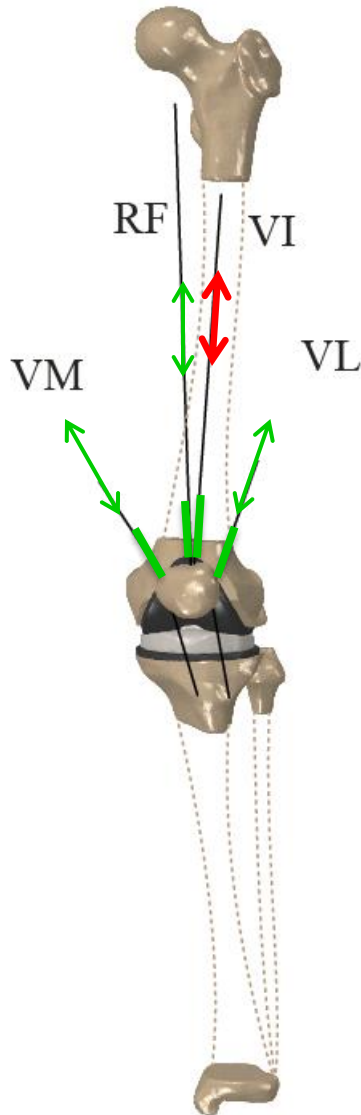


KNEE MODEL: BOUNDARY CONDITIONS



- Ankle: 2 DoF
Flexion/extension
Adduction/abduction
- Hip: 3 DoF
Superior/inferior translation
Flexion/extension
Adduction/abduction
- Patella: 6 DoF
- Contacts:
Patellofemoral
Tibiofemoral

KNEE MODEL: EXTENSOR MECHANISM



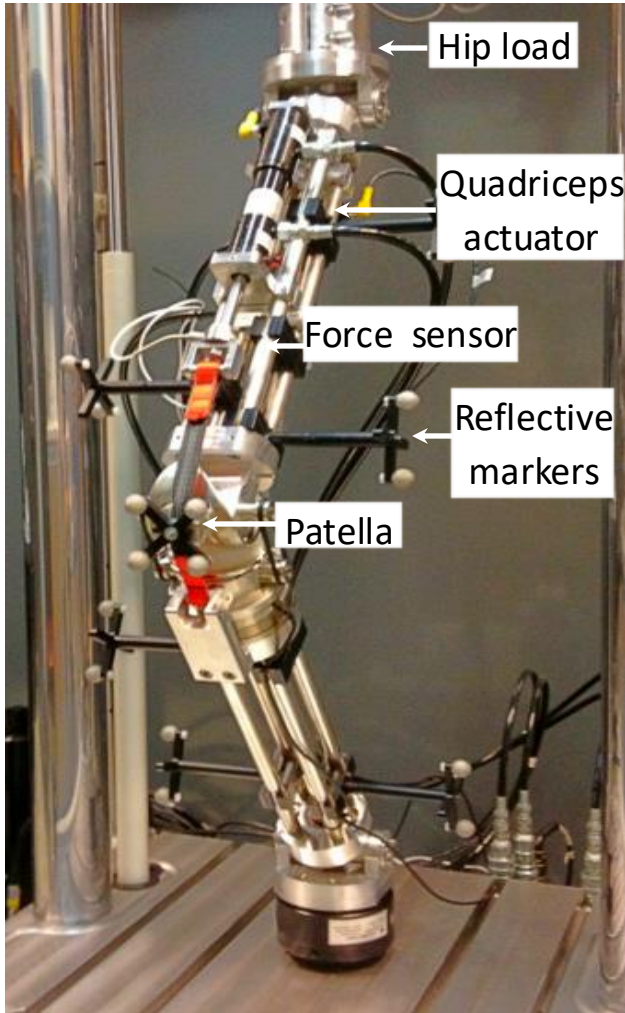
- Muscle: passive (tendon) + active (UEL)
- Control: muscle elongation + feedback algorithm¹
- Force in muscles distributed according muscle ratios
- Constant ratios as product of PSCA (patient) and EMG (literature)²
- Patellar tendon: non-linear spring³

¹[Terrier et al., 2007]

²[Dionisio et al., 2008; Yavuz et al., 2015]

³[Staubli et al., 1996]

KNEE MODEL: VALIDATION



- Static squat: 10 to 60° (each 5°)
- Body load 300 N
- Self-learning algorithm ¹

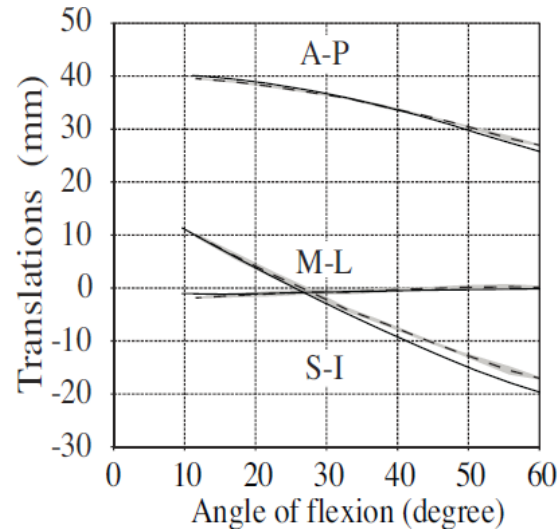
Measurements:

- Quadriceps force
- Patellar kinematics

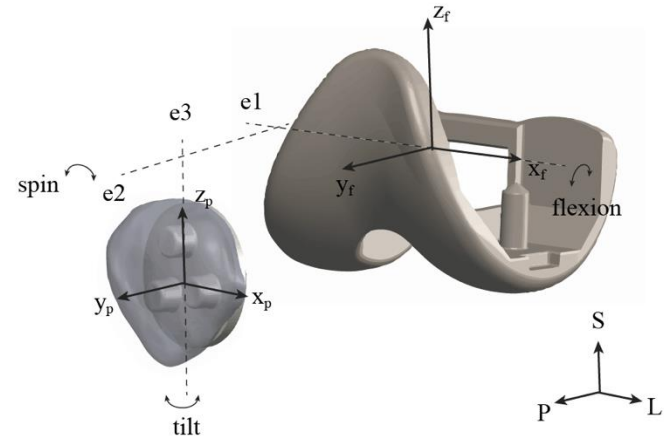
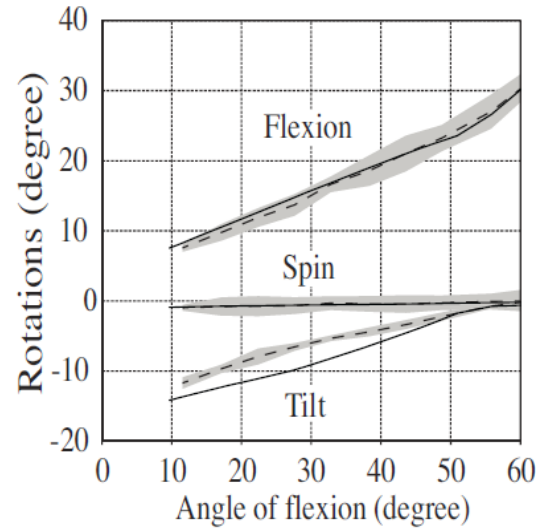
¹ [Arami et al.,2008]

KNEE MODEL: VALIDATION

Average error: 0.6 mm



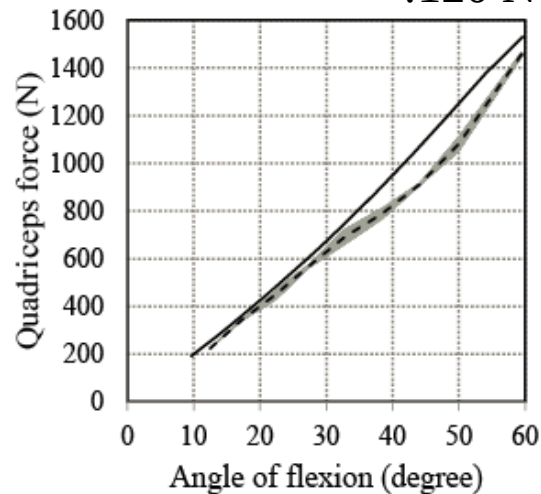
:1.1 degree



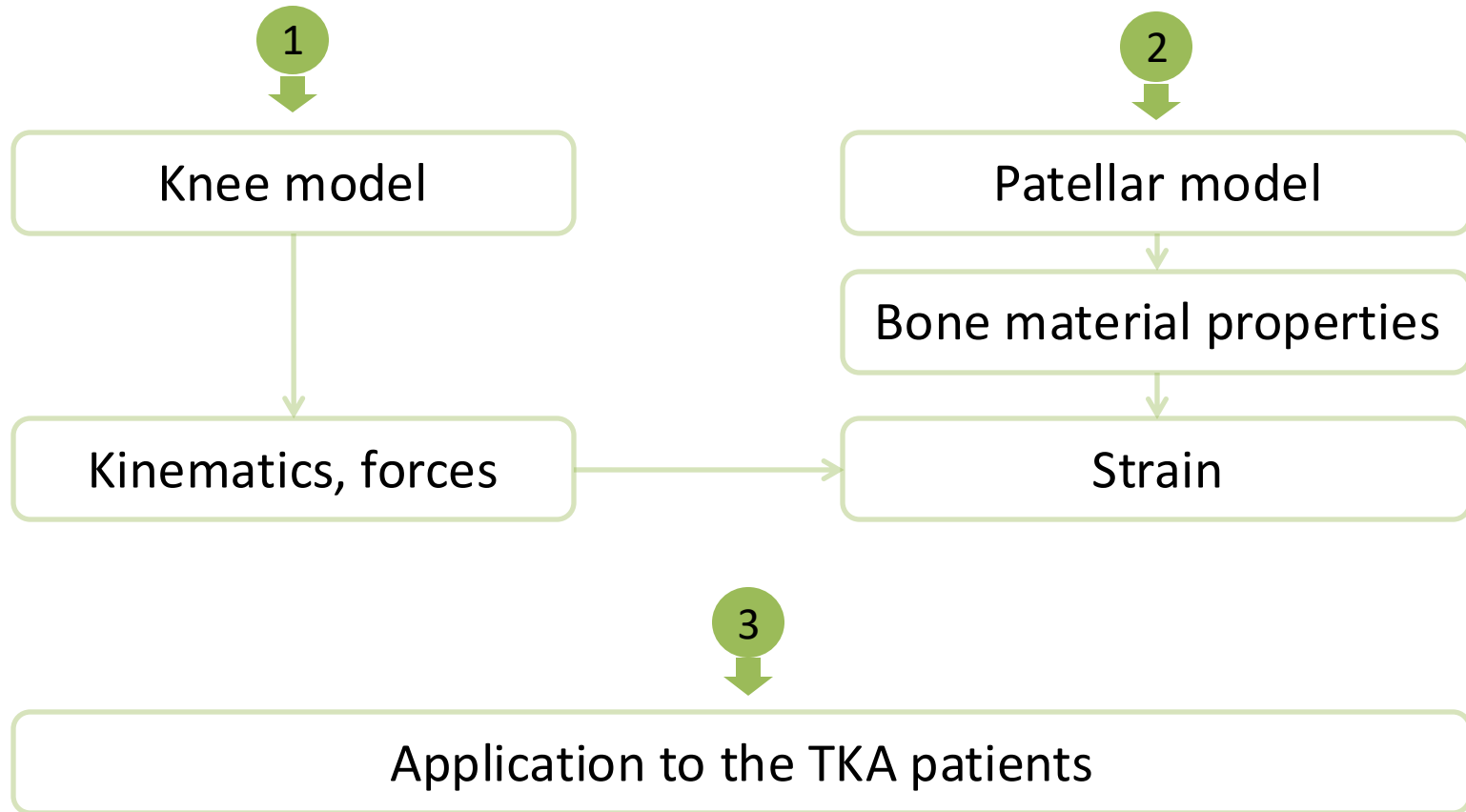
Three-cylinder open-chain system

[Grood and Suntay, 1983]

:120 N



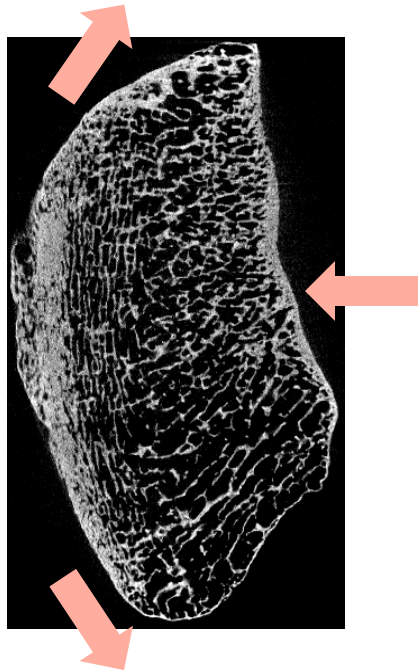
Patient-specific TKA model for patella



Patellar bone model

Anisotropic linear elastic material $\varepsilon = \mathcal{C} \sigma$

Morphology – elasticity relationship
(Zysset – Curnier)¹



$$\mathcal{C} = \begin{bmatrix} \frac{1}{E_1} & -\frac{\nu_{21}}{E_2} & -\frac{\nu_{31}}{E_3} & 0 & 0 & 0 \\ -\frac{\nu_{12}}{E_1} & \frac{1}{E_2} & -\frac{\nu_{32}}{E_3} & 0 & 0 & 0 \\ -\frac{\nu_{13}}{E_1} & -\frac{\nu_{23}}{E_2} & \frac{1}{E_3} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2G_{23}} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{2G_{13}} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{2G_{12}} \end{bmatrix}$$

$$E_i = E_0 \rho^k m_i^{2l}$$

$$\frac{E_i}{\nu_{ij}} = \frac{E_0}{\nu_0} \rho^k m_i^l m_j^l$$

$$G_{ij} = G_0 \rho^k m_i^l m_j^l \quad \forall i \neq j = 1, 2, 3$$

M : fabric tensor²

ρ : BV/TV

E_0, ν_0, G_0, k, l : constants to identify

anisotropic model

$$M = \begin{bmatrix} m_1 & 0 & 0 \\ 0 & m_2 & 0 \\ 0 & 0 & m_3 \end{bmatrix}$$

$$m_1 \leq m_2 \leq m_3, \text{tr}(M) = 3$$

isotropic model

$$M = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

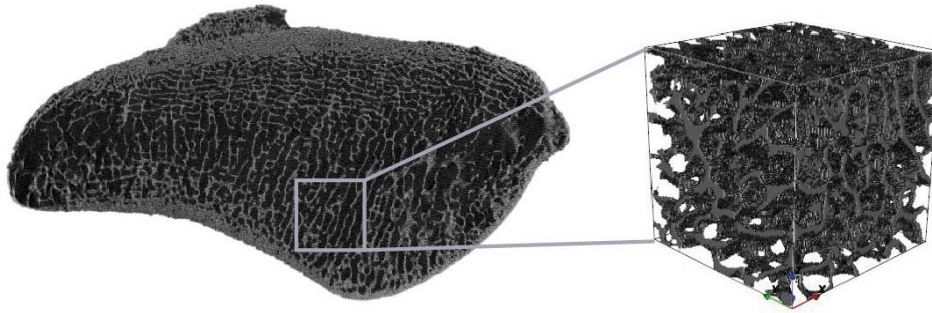
¹ [Zysset , Curnier, 1995]

² [Cowin, 1995]

IDENTIFICATION

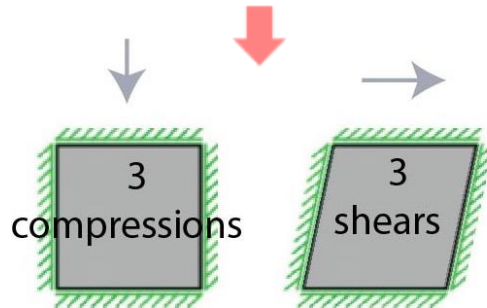
μ CT: 20 patellae

200 cubes (5.3 mm)



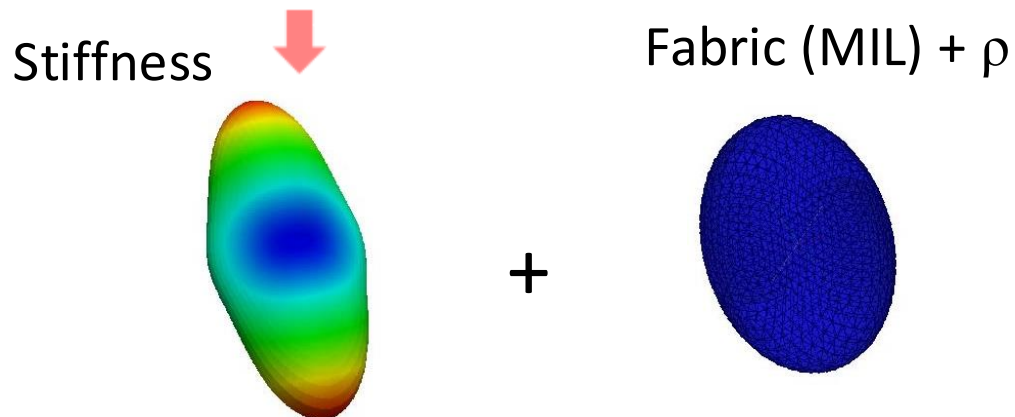
- Each voxel to hex element
($E=12$ GPa, $\nu=0.3$)¹

¹[Wolfram, 2010, 2012]



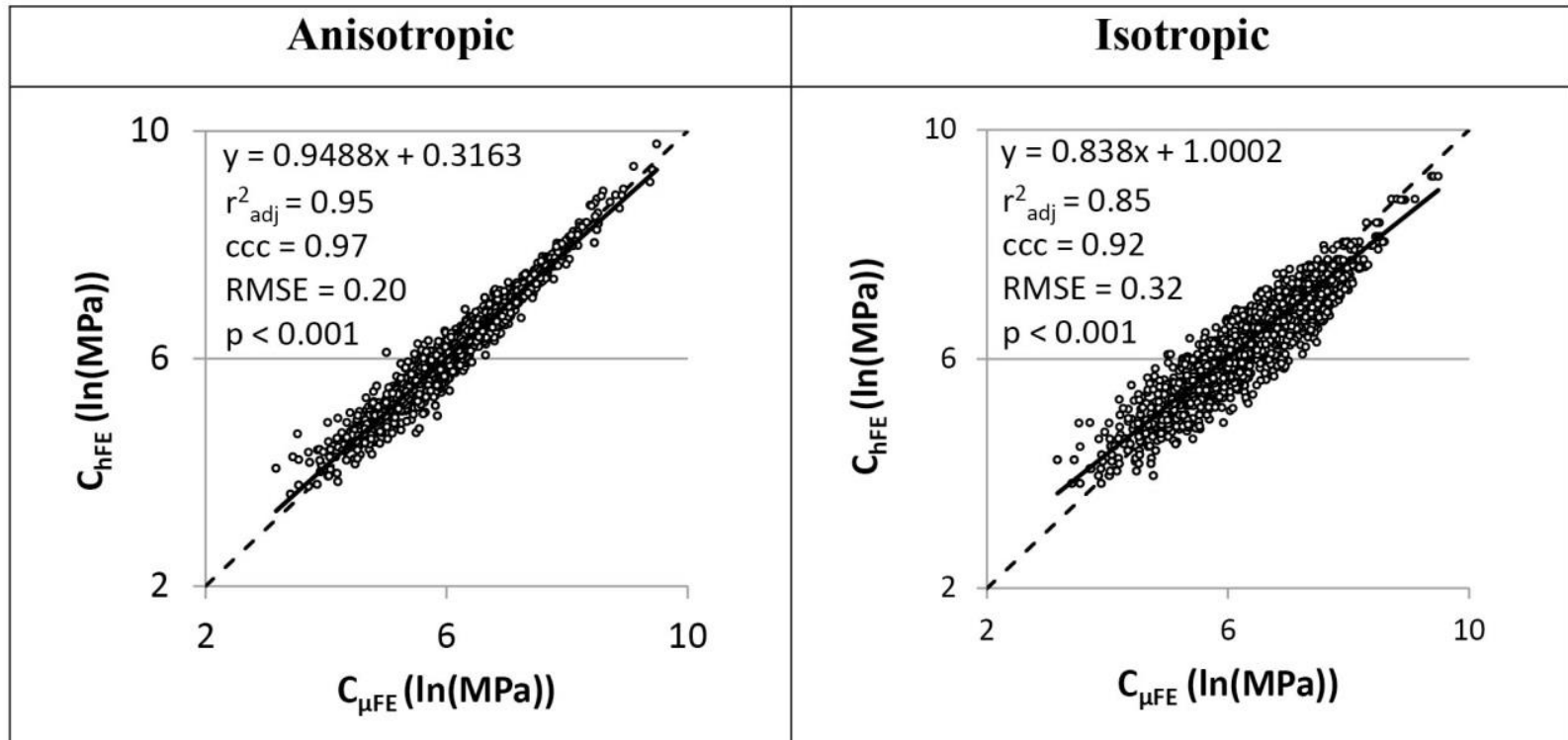
- KUBC²

²[Pahr and Zysset, 2008]



Constants: E_0 , ν_0 , G_0 , k , l

IDENTIFICATION



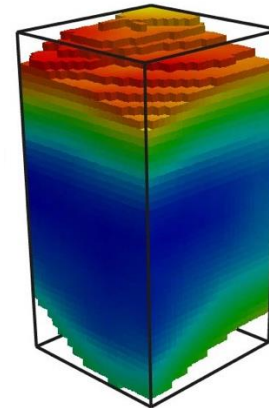
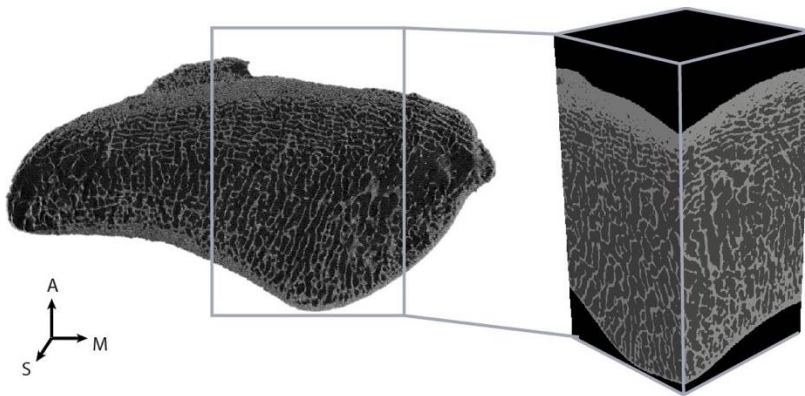
Law	E_0 (MPa)	ν_0	G_0 (MPa)	k	l
Anisotropic	12723.05	0.24	4224.62	2.1	1.02
Isotropic	11035.98	0.26	4395.05	2.13	-

VALIDATION

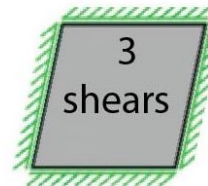
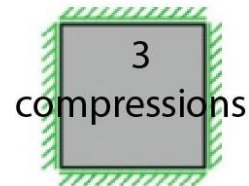
μ CT: 18 sections

μ FE

hFE



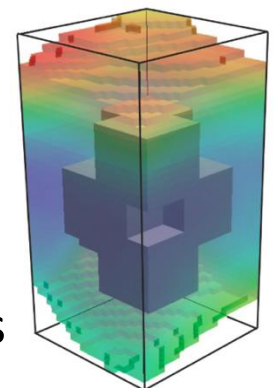
- hFE: anisotropic and isotropic



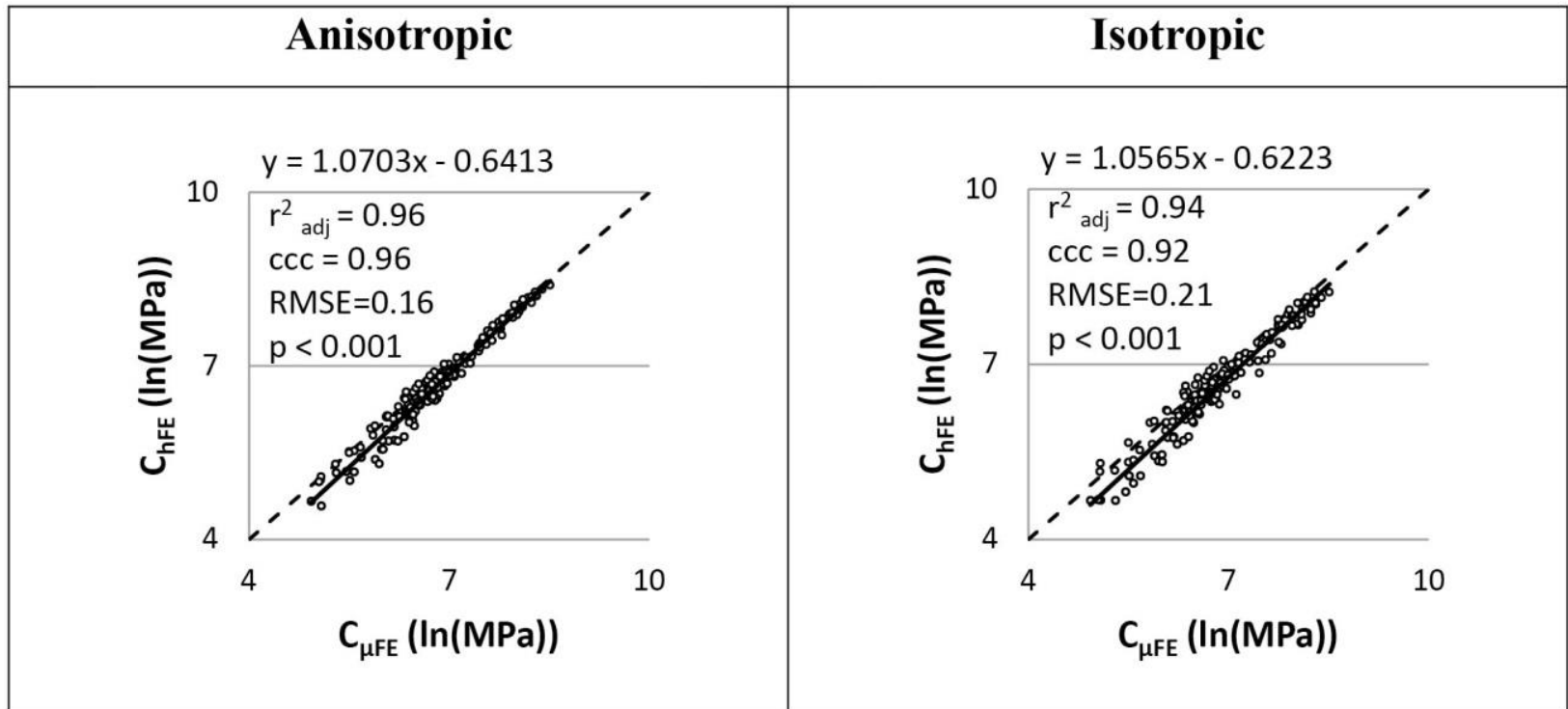
- KUBC

Global comparison:
Stiffness

Local comparison:
Strain/stress invariants

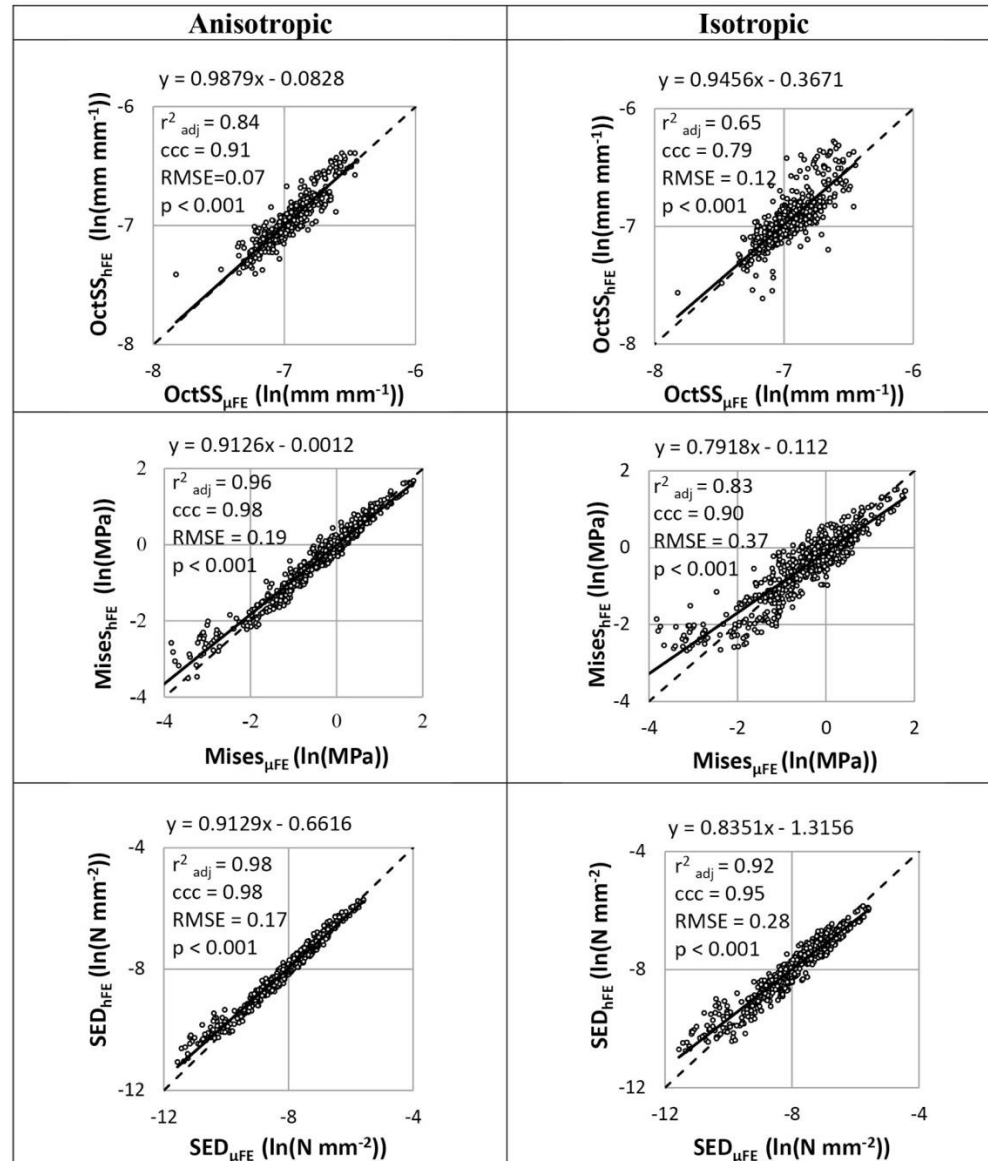


VALIDATION:GLOBAL STIFFNESS

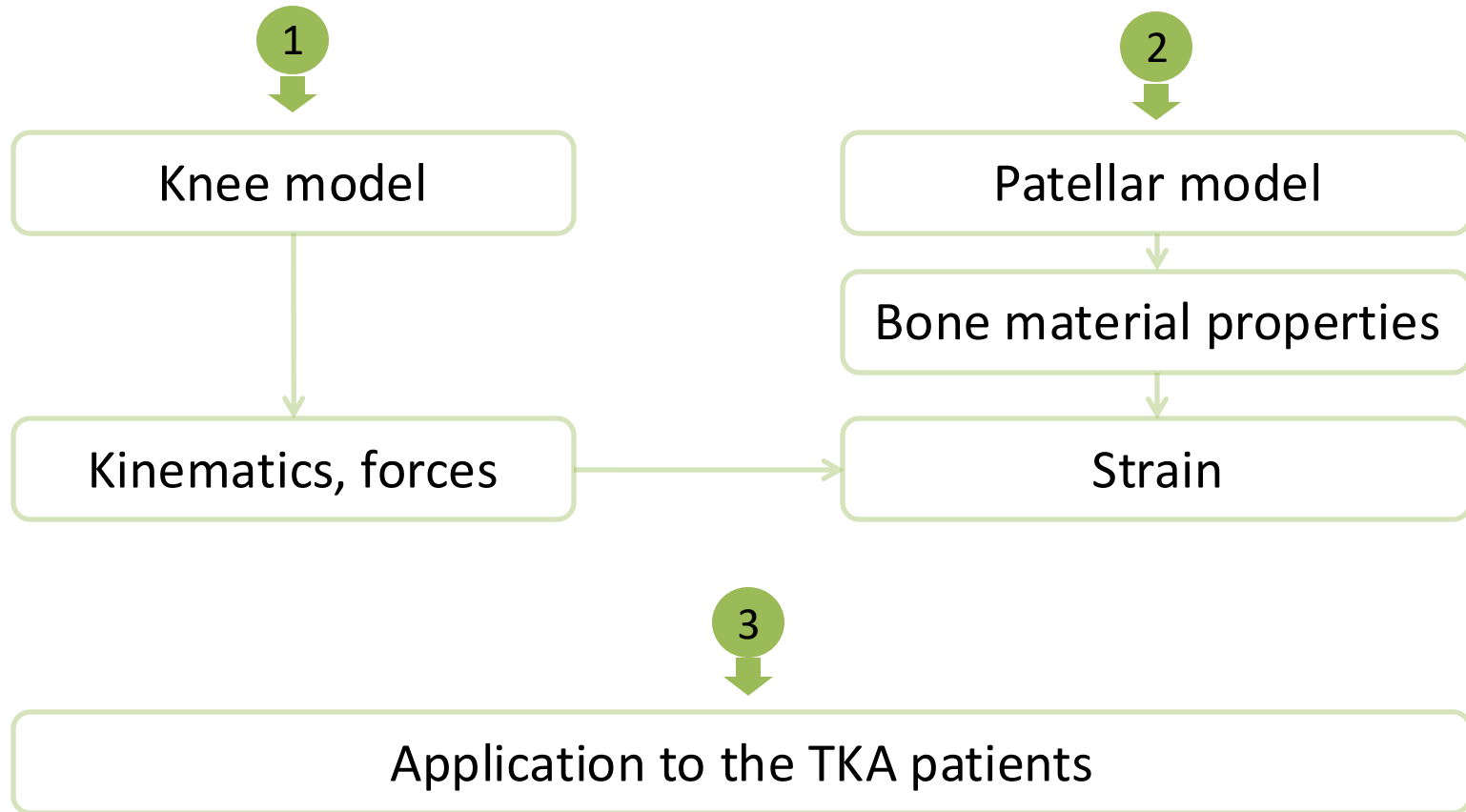


VALIDATION:LOCAL STRESS AND STRAIN

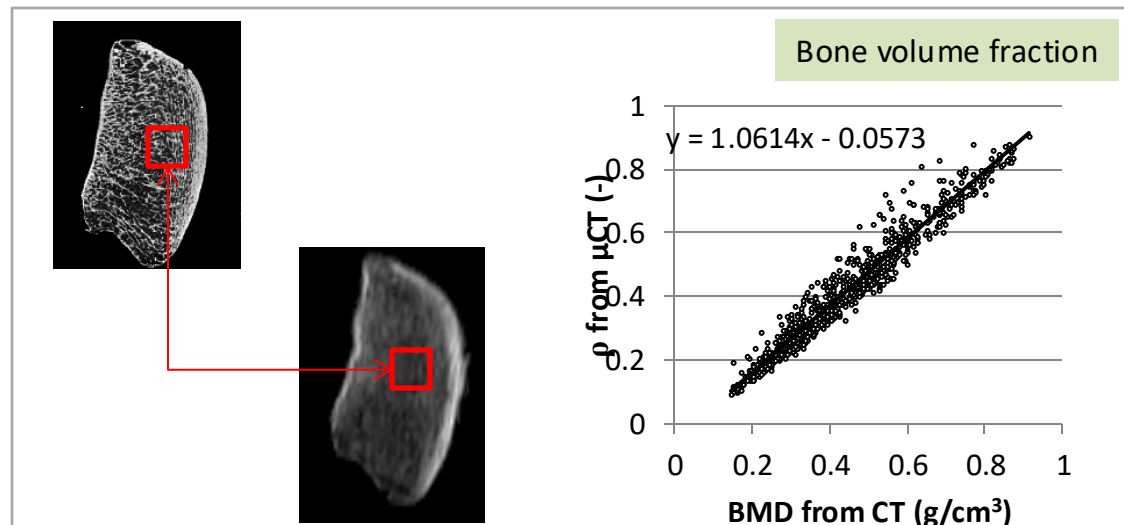
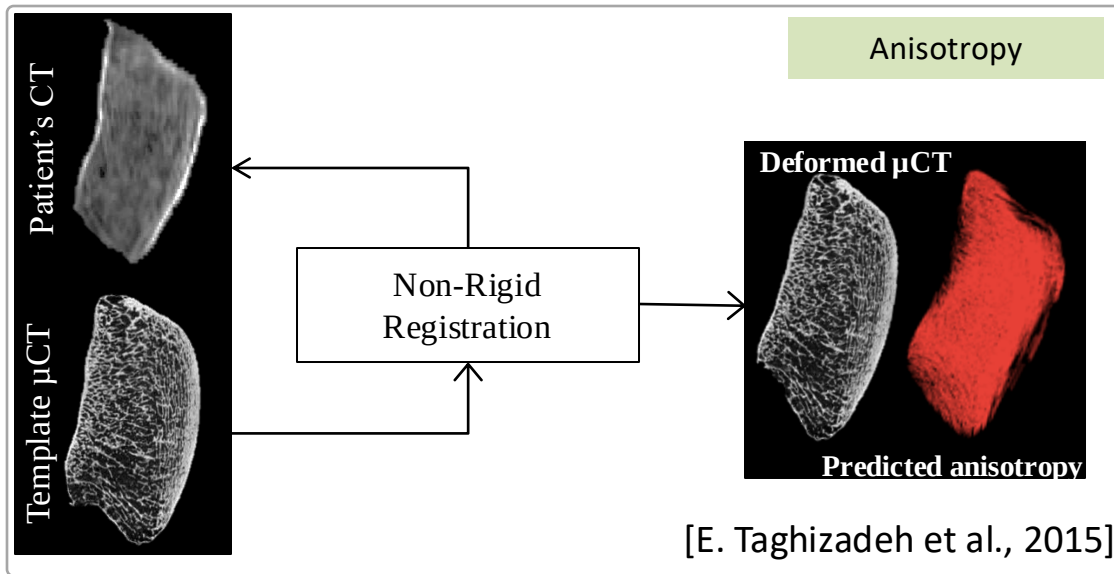
Octahedral shear strain



Patient-specific TKA model for patella

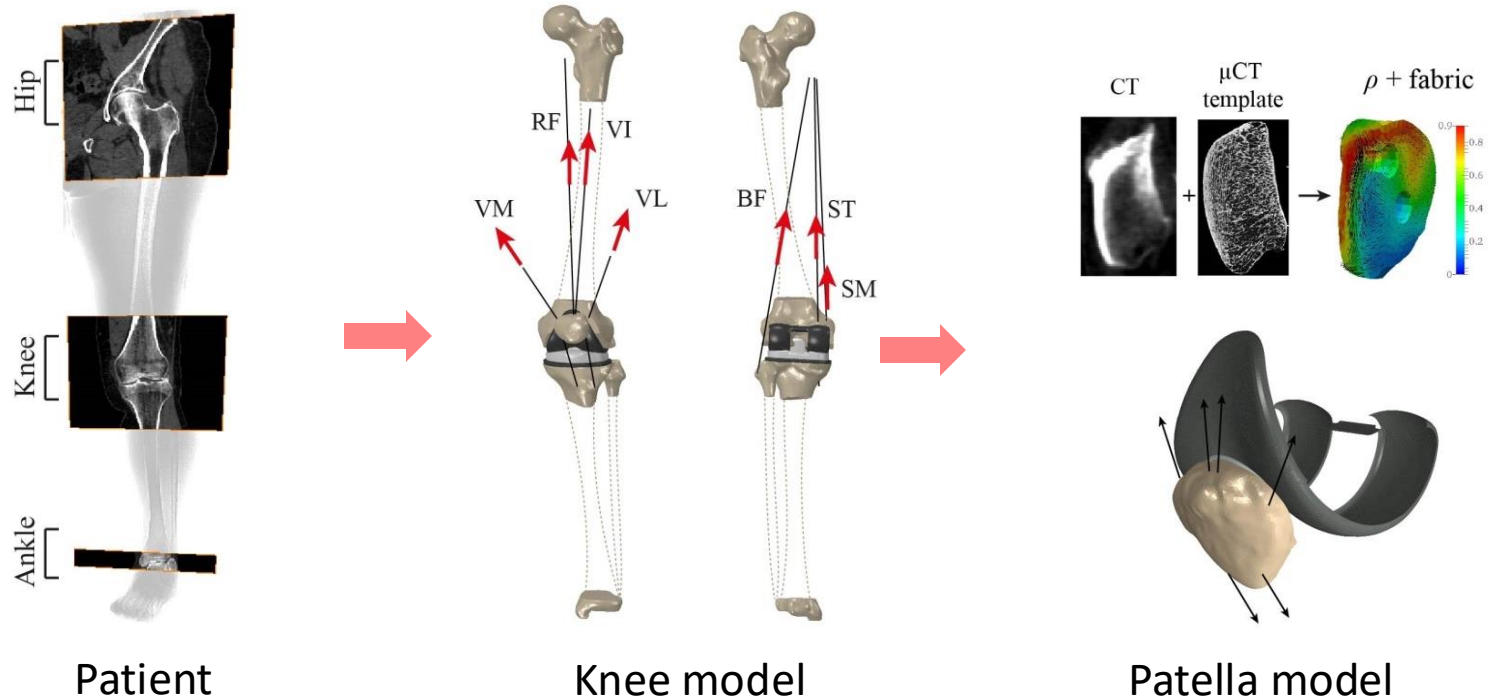


MATERIAL PROPERTIES FROM CT

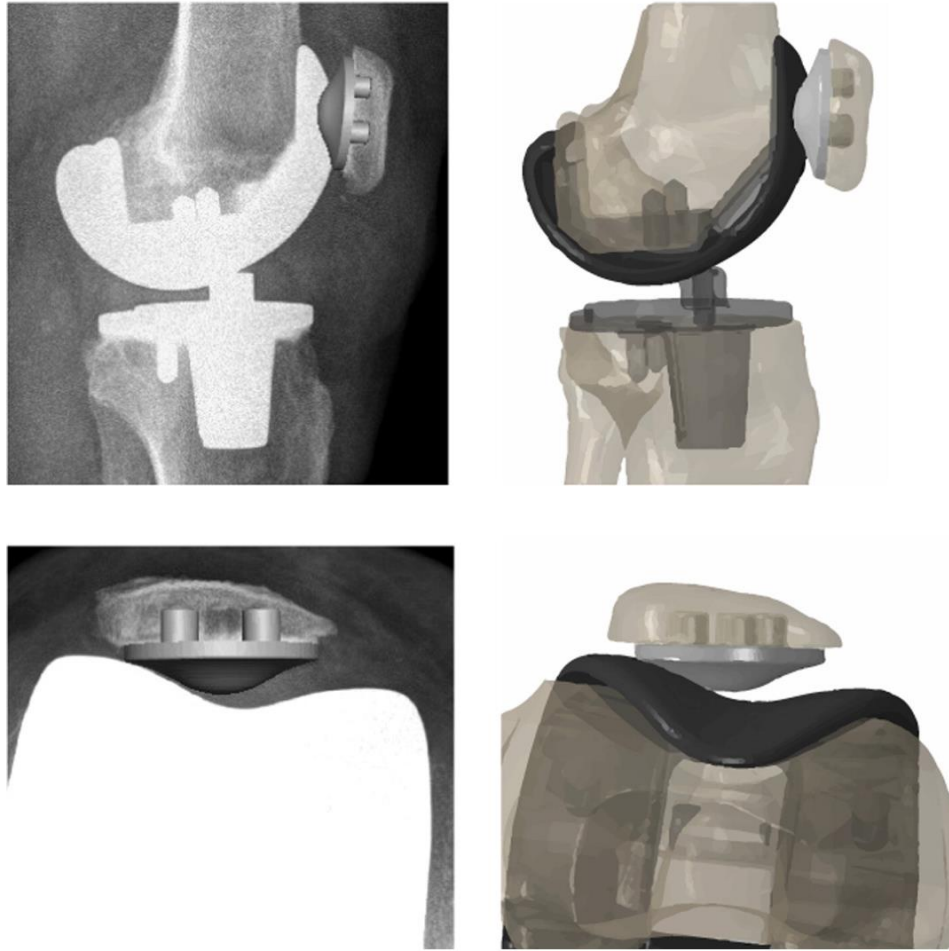


APPLICATION TO PATIENTS

- 14 patients
- Preoperative CT & planning
- 1 year follow-up
- No complications
- Patellar cut from post-op X-Ray
- Loaded squat (BW)
- Muscles ratios (PCSA and EMG)
- Strain (octahedral shear) 60° knee flexion



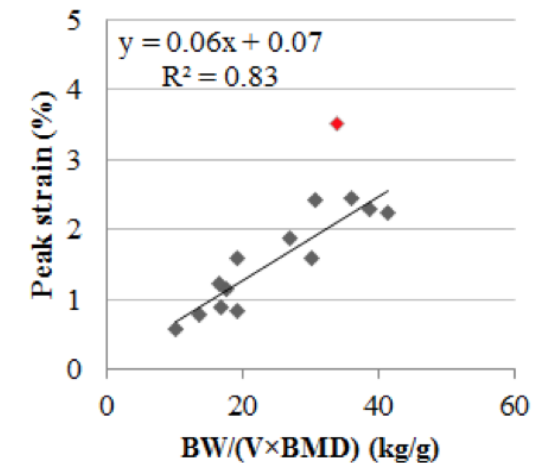
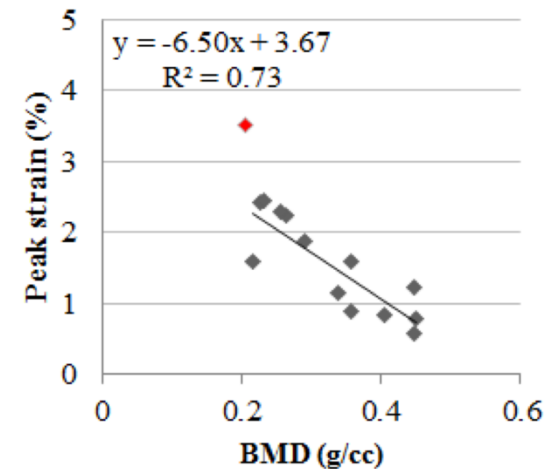
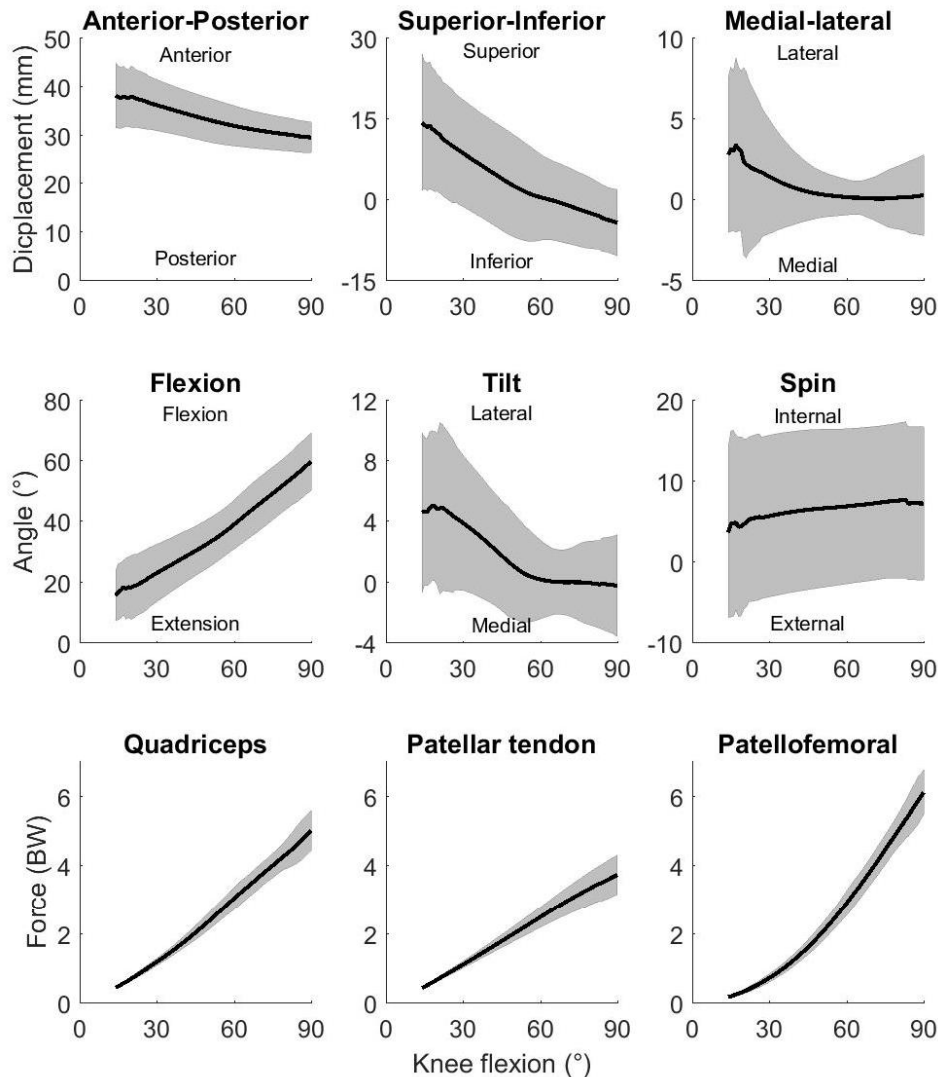
Patient-specific modeling



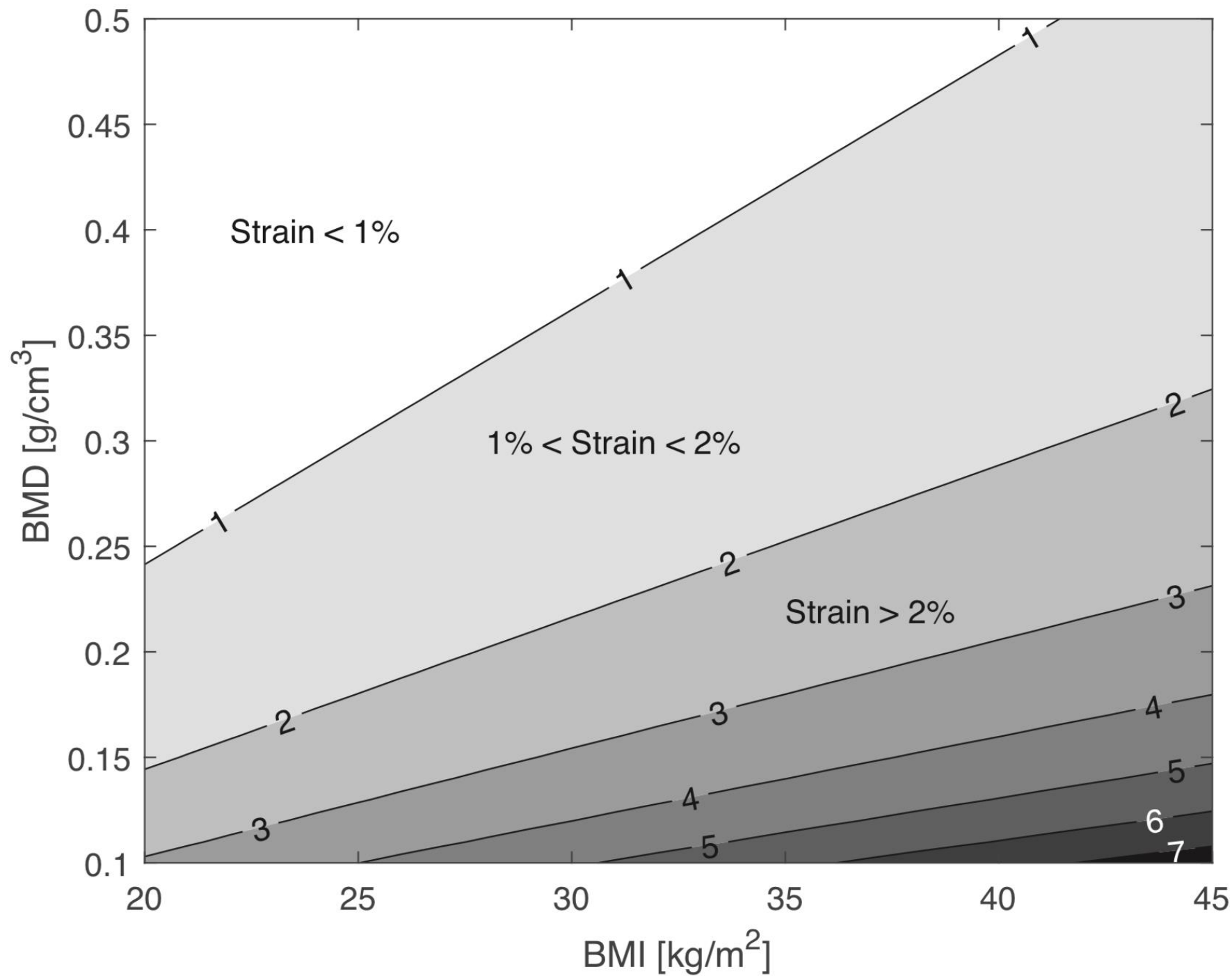
Postoperative X-ray vs model predictions

Patient-specific modeling

14 patients



Peak strain: maximum strain in 99% bone volume
BMD: average bone mineral density
BW: Body weight
V: patellar bone volume after resurfacing

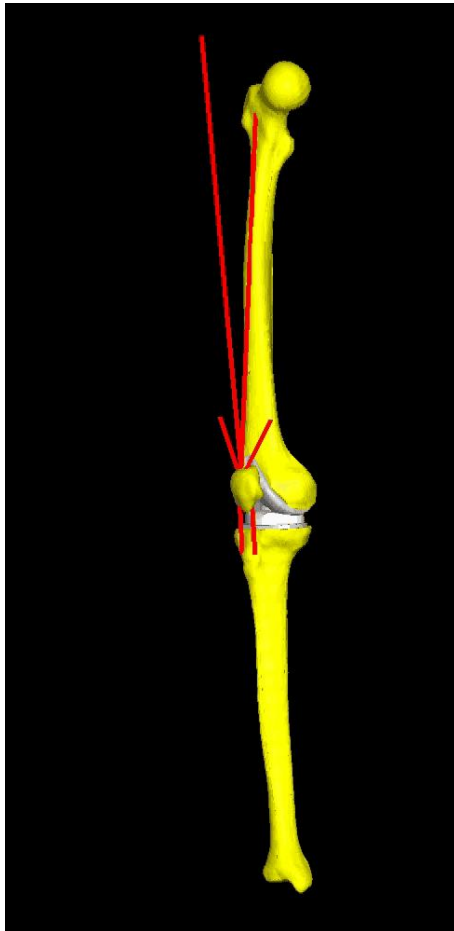


Summary

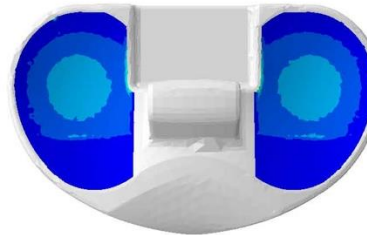
- Patient-specific TKA model with focus on patella
- Adaptation to anatomy, implant design and position, body weight
- Muscle control
- Identified and validated patellar material properties (anisotropic and isotropic)
- Application to patients
 - Variation between patient
 - Highlighted importance of patellar density and volume, body weight in preoperative planning
- Potential of the model as surgery planning tool
- Application to the patients
 - Two groups of patients (pathologic/control)
 - Other clinical applications (wear, evaluation of new design, etc.)

Knee

Polyethylene contact pattern (max/mean)
at 60° of knee flexion

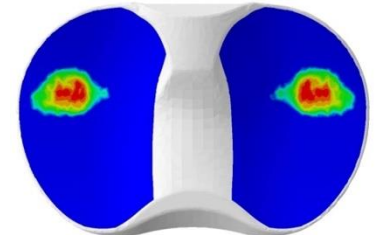


FIRST



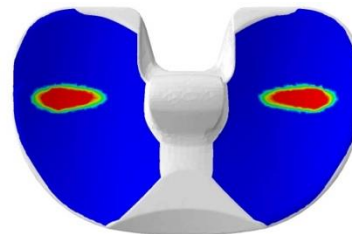
11 Mpa / 3 MPa

PFC



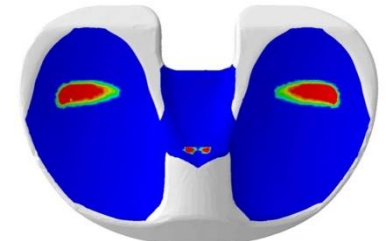
21 Mpa / 11 MPa

NexGen LPS flex



32 Mpa / 17 MPa

HLS



56 Mpa / 18 MPa

EPFL-LBO (A. Terrier)